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# SMS

*AC & DC  
STANDARD  
GEAR MOTOR*



**SMS SHINMYUNG SERVO CO., LTD.**

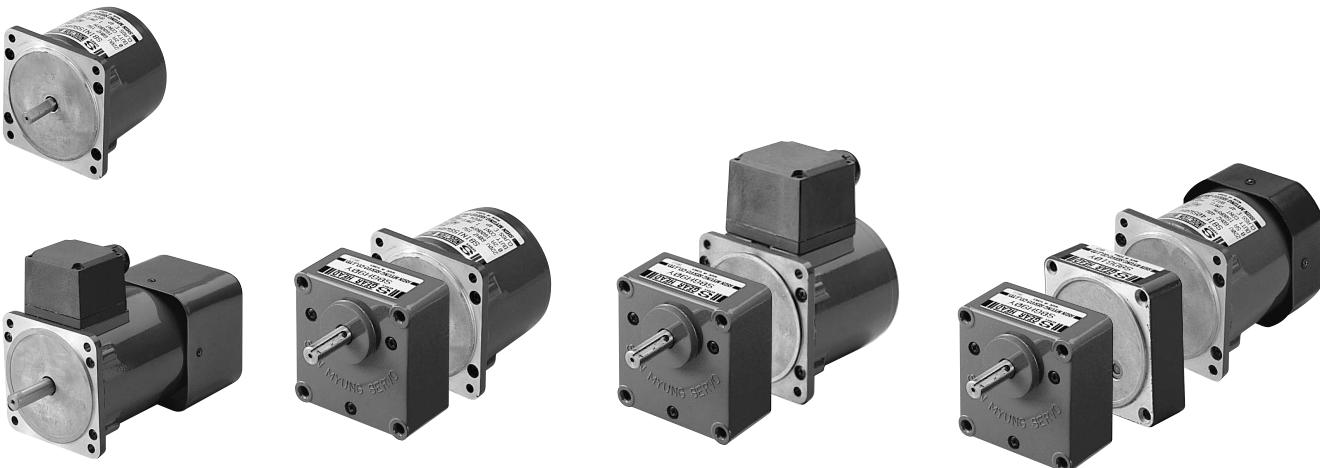
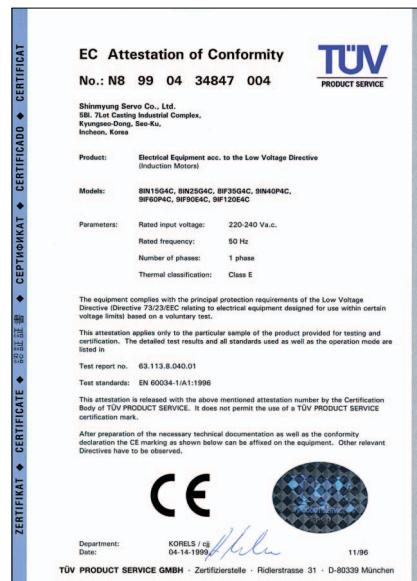
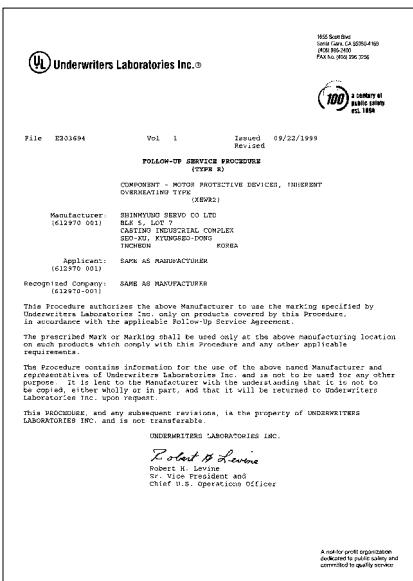
## ■ OUTLINE

The MOTORS supplied by SHINMYUNG SERVO CO.,LTD. are widely utilized as AC & DC STANDARD SMALL MOTORS, which are standardized with all kinds of gear heads to meet diversified customer's demands. These motors are designed and manufactured for high accuracy, stability and durability by the support of SHINMYUNG ELECTRIC Mfg Co., Ltd. high-level design capability, mass production technology and 40 year's experience. From now our company can supply the motors with reasonable price and high quality to the customers as quickly as possible and acquire CE U.L. CSA and VDE mark by your demands.

## ■ FEATURES

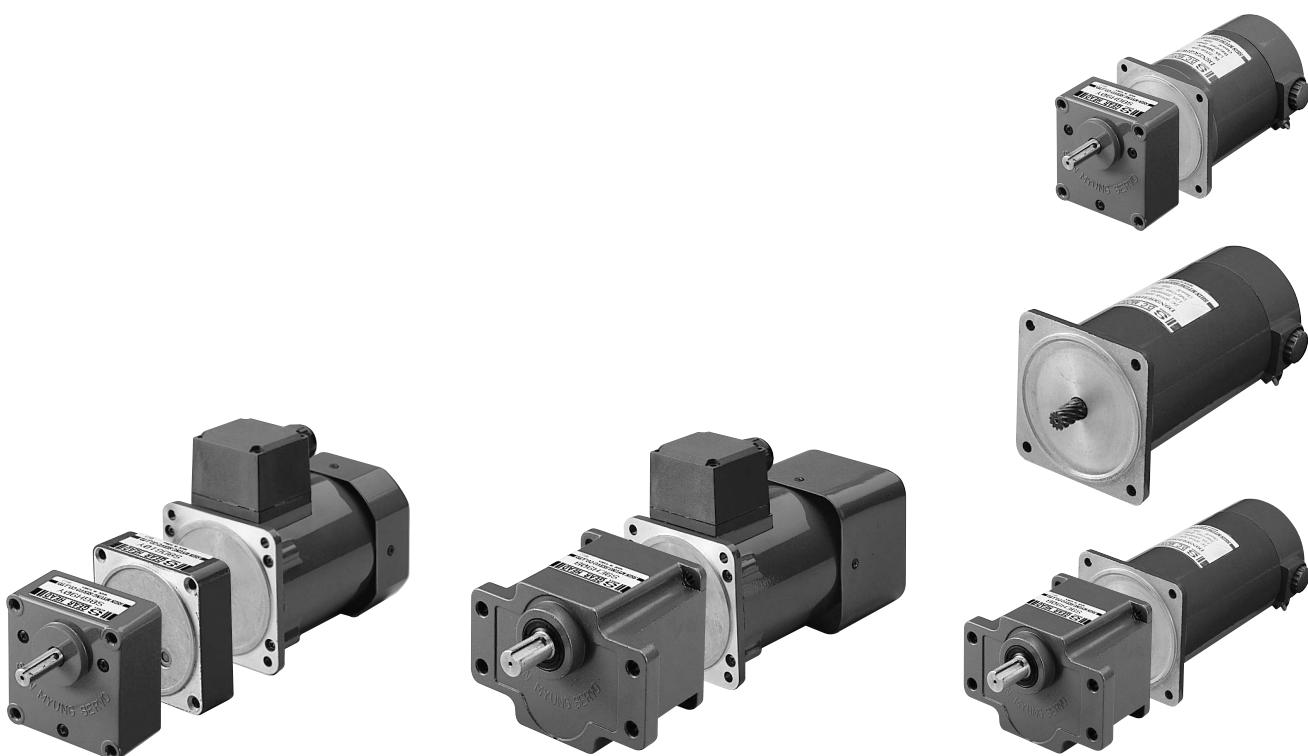
1. INDUCTION motors are used for continuous duty applications to the same direction in the long time, but as reversible motors is used for frequent starting and stopping characteristics, these motors are designed specially for high starting torque. Therefore, REVERSIBLE motors are applied for normal rotation, stop, reverse rotation alternately in the short time.
2. The customer can select all kinds of gear heads that suit with each motor. Standard gear ratios are divided into 20 steps in the range from 1/3 to 1/180. Depend on the demand, the ratio can be available from 1/30 to 1/1800 with a decimal gearhead.
3. As the strength of gear heads are designed optimally for motors output, these motors can be stably available for wide range of gear ratio.
4. As the motors are assembled by using standard parts, whose quality is stable and also these motors are designed and manufactured for low noise, low vibration and long life expectancy.

## ■ UL, CE Certificates



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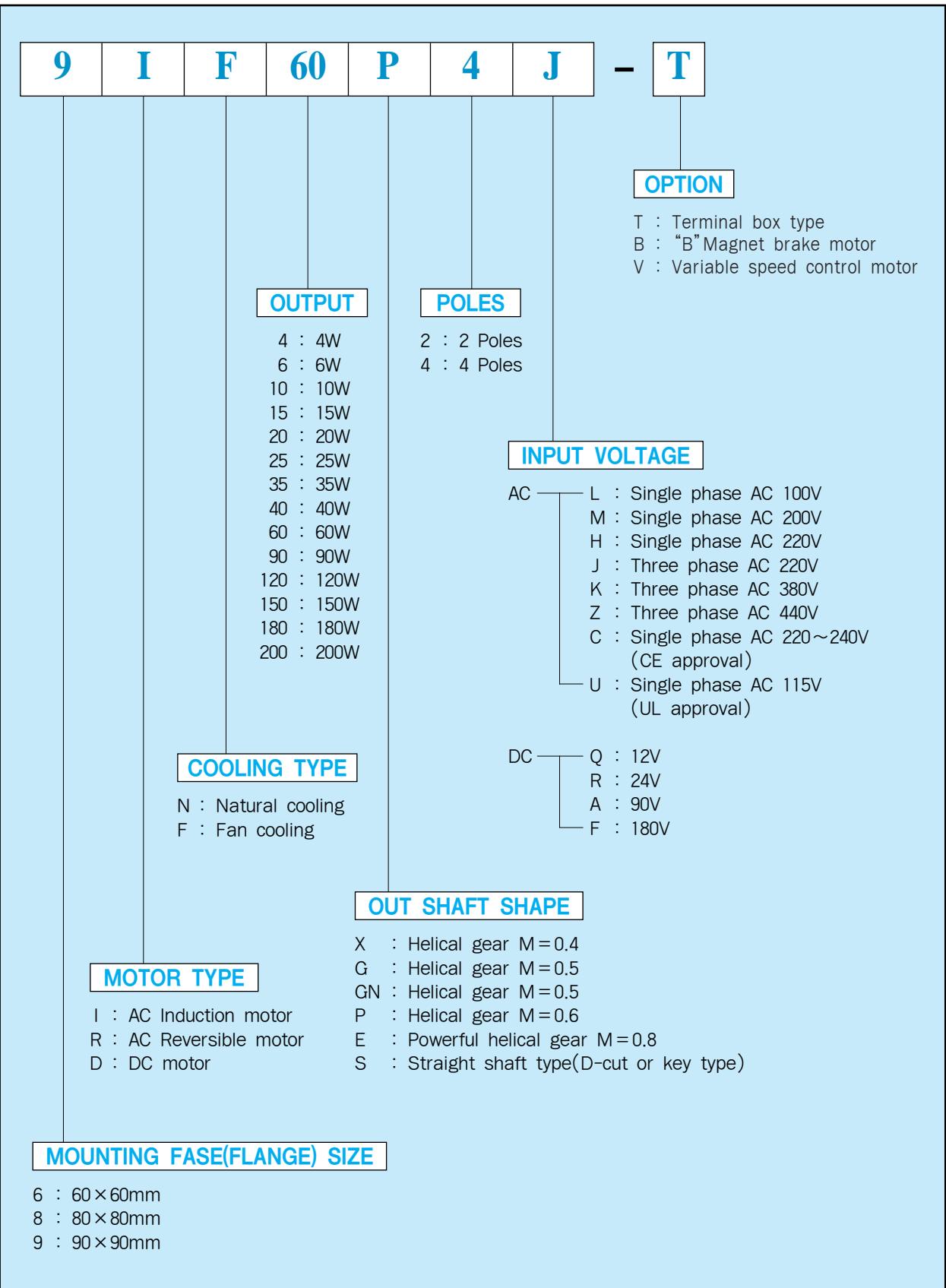


# CODING SYSTEM

## AC MOTOR & DC MOTOR

### ■ MODEL

4



# CODING SYSTEM

## GEARHEAD

### ■ MODEL

9	P	30	Y	-	
<b>OPTION(Limited worm gerahead)</b>					
				L : Left direction	
				R : Right direction	
				D : Dual direction	
				H : Hollow shaft	
<b>BEARING TYPE</b>					
			B : Ball bearing		
			Y : Ball + Metal sleeve bearing		
<b>GEAR RATIO</b>					
Ex) 30 = 1 : 30 (1 : 3 ~ 1 : 180)					
<b>GEAR TOOTH TYPE</b>					
X	:	Helical gear M=0.4			
G	:	Helical gear M=0.5			
GN	:	Helical gear M=0.5			
P	:	Helical gear M=0.6			
E	:	Powerful helical gear M=0.8			
W	:	Worm gear head			
<b>MOUNTING FASE(FLANGE) SIZE</b>					
6	:	60×60mm			
8	:	80×80mm			
9	:	90×90mm			

### ◆ DECIMAL GEAR HEAD

Decimal gearhead is a mediate gearbox which is assembled between a motor and a gearhead to get the transmission ratio 1:250~1:1800.

There are two kinds of decimal gearboxes as follows:

MODEL	REDUCTION	MOUNTING FASE(FLANGE) SIZE
6DG10Y	1:10	60×60mm
8DGN10Y	1:10	80×80mm
9DP10Y	1:10	90×90mm

# HOW TO HANDLE

## AC MOTOR

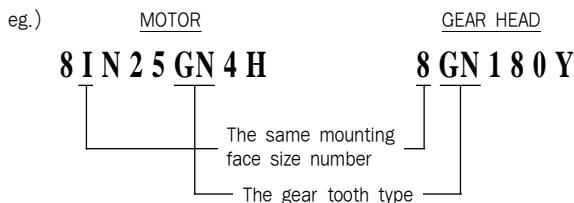
### CHECK BEFORE OPERATION

- 1) Confirm the name of model, voltage, output, etc.
- 2) In case of single phase motors, an attached condenser must be used. Connect firmly condenser terminal and the lead wires of motor with a pressing terminal or soldering.
- 3) Be careful. There are twice times of voltage of input voltage between the terminals of condenser.
- 4) Do not disassemble and modify.

### WARNING

- 1) Use the motor at ambient temperature between -10~40°C and humidity at 85%.
- 2) Avoid the following places where ;
  - The sun shines directly.
  - Damp or oily place
  - The places are being vibrated
  - The place is dusty
  - There are flammable materials.

3) Make sure that surface temperature of the motor case should not be exceeded 90°C. A same type of gear tooth must be connected between motor and gearhead.



1) Motors and gear head should be connected as belows.

MOTOR	GEAR HEAD	MODULE
X	X	0.4
GN	GN	0.5
P	P	0.6
E	E	0.8

2) Make sure that same model name and number can only be connected.

### REVERSIBLE MOTORS ARE MADE

For short-time revolution, so that temperature rapidly rises in 30 minutes compared to induction motors.

But the temperatures of the motor case remains cool under 90°C, if the motor dose not work continuously.

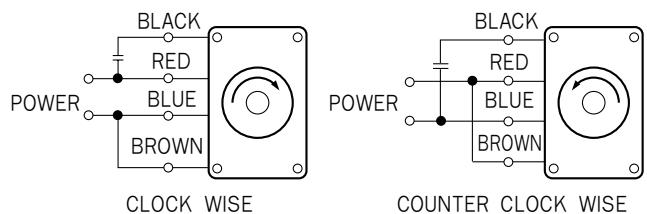
### HOW TO CONNECT THE LEADWIRES

Try again to connect the leadwires when the following troubles are occurred.  
 1) Motor does not start.  
 2) Torque is less powerful.  
 3) When it turns to the wrong direction.  
 Contact us when the cause is unknown.

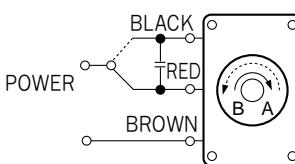
### !! CAUTION

As the rotation direction of output shaft of an gearhead depends on the ratio. Please confirm the ratio. Only after motor stops, reconnect it to reverse the direction of an induction motor.

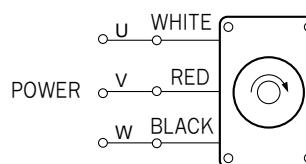
#### !! INDUCTION MOTOR



#### !! REVERSIBLE MOTOR



#### !! 3-phase INDUCTION MOTOR



The rotation will be changed to opposite direction, if the 2wires of 3 are changed.

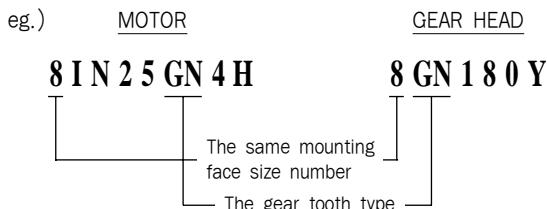
# HOW TO HANDLE

## GEAR HEAD

### ■ AVAILABLE MOTOR

Check the motor and gear head before connect them.

The following motor and gear head can be connected.

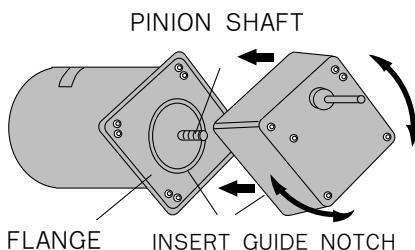


- 1) Connectable motor and gear tooth type

MOTOR	DECIMAL	GEAR TOOTH	MODULE
X	DX	X	0.4
GN	DGN	GN	0.5
P	DP	P	0.6
E	-	E	0.8

- 2) Connection can not be done when the gear head types of motor and gearhead types & sizes are different.

### ■ ASSEMBLING OF MOTOR AND GEARHEAD



A motor and gearhead must be connected as shown above by turning the gearhead right and left a little repeatedly using the inside guide line with enough care that the pinion does not hit the base-plate or gearhead heavily.

### ■ GEAR HEAD OUTPUT SHAFT TURNING DIRECTION

GEAR HEAD	SAME DIRECTION WITH MOTOR	REVERSE DIRECTION WITH MOTOR
6G□Y	3~18, 50~180	25~50
8GN□Y	3~18, 50~180	25~36
9P□Y	3~18, 50~180	25~36
9E□Y	3~9, 25~60	12.5~18, 75~180

### ■ ACCESSORIES

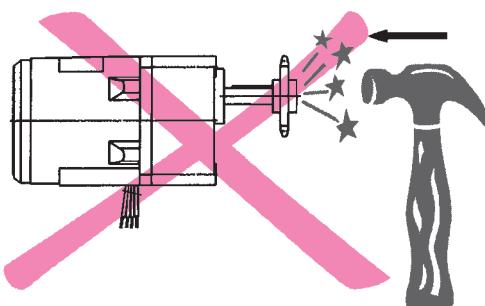
- Mounting screw, hex. nut and plain washer
  - • 4 pcs. each
- Parallel key (Only for key-grooved shaft)
  - • • 1 pc.

GEAR HEAD	SCREW	KEY SIZE
6G3Y~6G18Y	M4 0.7×50	-
6G25Y~6G180Y	M4 0.7×60	-
8GN3Y~8GN18Y	M5 0.8×50	4×4×25
8GN25Y~8GN180Y	M5 0.8×60	4×4×25
9P3Y~9P18Y	M6 1.0×65	4×4×25
9P25Y~9P180Y	M6 1.0×80	4×4×25
9E3B~6G180B	M6 1.0×25	5×5×25
6DG10Y	M4 0.7×90	-
8DGN10Y	M5 0.8×90	-
9DP10Y	M6 1.0×110	-

### ■ Caution in mounting transmission parts

When you mount a pulley, gear or other power transmissin part to a Gear Head, take care not to give shock to the output shaft which will affect bearings badly.

In key insertion, especially, never hit with hammer or similar tool.



# HOW TO HANDLE

## GEAR HEAD

### THE LIFE OF GEAR HEAD

Generally, the life of the gearhead is determined by the bearing mostly. The bearing life of gearhead is reflected by the friction load transmitted from gearshaft and overhung load and thrust load.

The life of ball bearing type is about 5000 hours in the conditions of the permissible overhung loads and thrust loads with the following operation conditions:

- \* Torque : Permissible torque
- \* Loads : Continued
- \* Hours : 8 hours / day
- \* Case temperature : 80°C (Ballbearing Type)

But, generally use the coefficient, which is called the service factor(see table 1) as the loads are changeable a lot of times.

Table 1 service factor

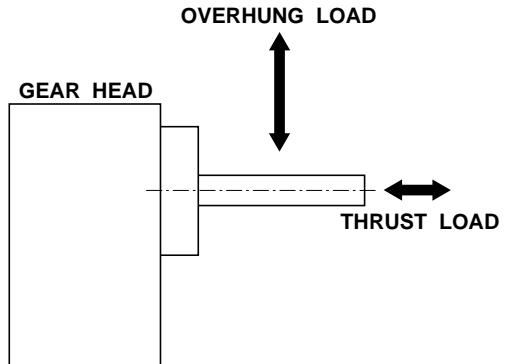
Load class	Service factor(f)		
	5hrs / day	8hrs / day	24hrs / day
<b>Uniform</b>	0.8	1.0	1.5
<b>Moderate shock</b>	1.2	1.5	2.5
<b>Heavy shock</b>	1.5	2.0	2.5

⟨Load examples⟩

<b>Uniform</b>	- Velt conveyor - Operation in the same direction continued - Film winding
<b>Moderate shock</b>	- Frequent starting, stopping - CAM running
<b>Heavy shock</b>	- The frequent conversion of reversible motor - The frequent short stop by the brake pack - the conversion of reversible motor (Speed control pack)

### PERMISSIBLE OVERHUNG & THRUST LOAD OF GEAR HEAD

Model	Ratio	Allowable Max. Torque		Allowable overhung load		Allowable thrust load	
		Kg-cm	N-m	Kg	N	Kg	N
<b>6G□Y</b>	<b>3~18</b>	30	3	5	50	3	30
<b>6G□B</b>	<b>25~180</b>			15	150		
<b>8GN□Y</b>	<b>3~18</b>	100	10	10	100	5	50
<b>8GN□B</b>	<b>25~180</b>			20	200		
<b>9P□Y</b>	<b>3~18</b>	120	12	25	250	10	100
<b>9P□B</b>	<b>25~180</b>			30	300		
	<b>3~9</b>	300	30	40	400		
	<b>12.5~36</b>			45	450	15	150
	<b>50~180</b>			50	500		



$$* \text{ Overhung load } W = \frac{K \times T \times f}{r}$$

W : Overhung load

K : Load connection of gearhead shaft(Kg-cm)

T : Service factor(see Table 2)

f : Service factor(see table 2)

r : The diameter of gear or pully etc.

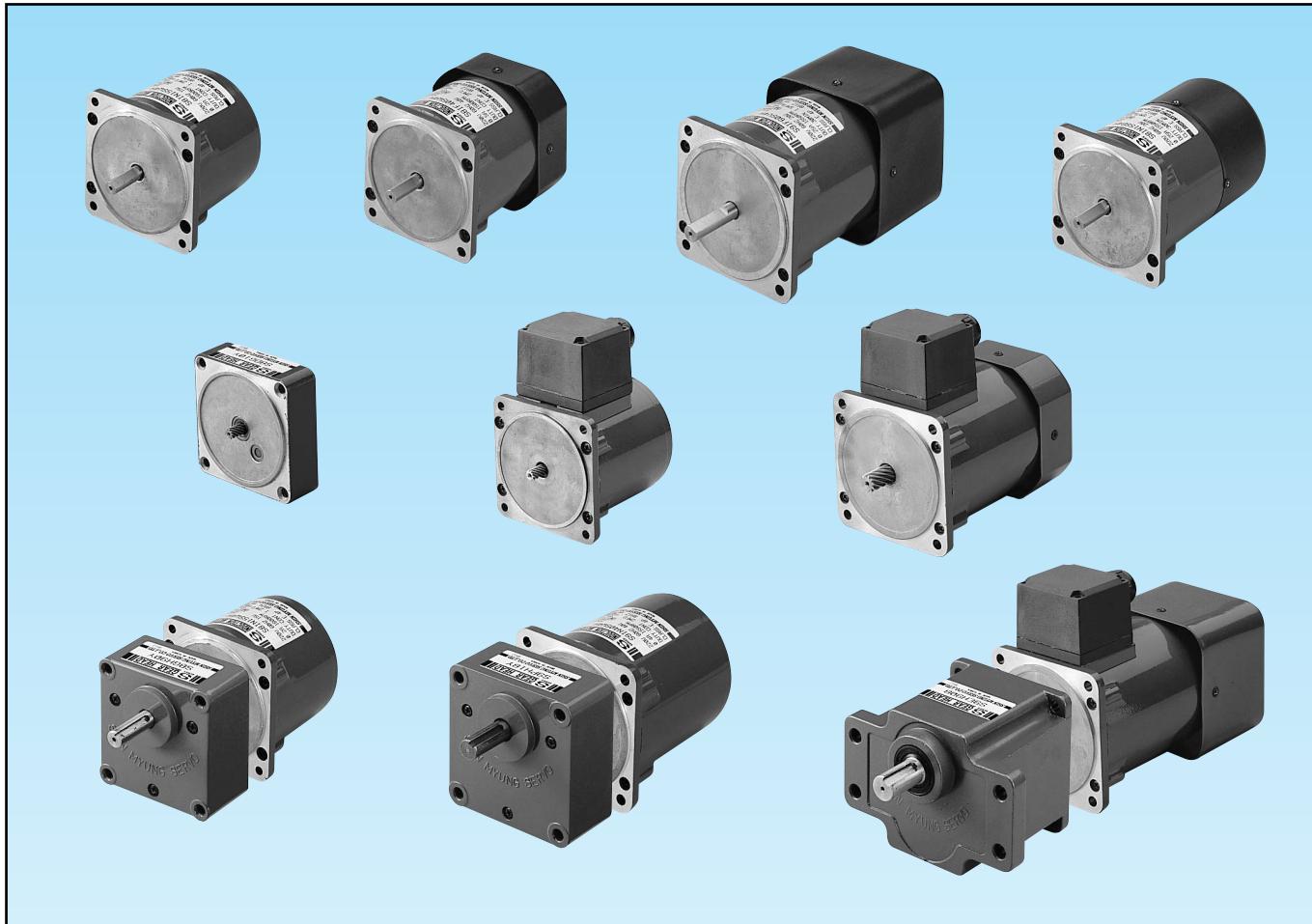
Table 2 Load connection factor

Connection method	Factor(K)
Chain sprocket	1
Gear, Pinion	1.25
V-belt	1.5
Flat-belt	2.5

The above listed ratings are the maximum permissible overhung and thrust loads.

Calculate the actual overhungload from the formular and then do not exceed the permissible loads to avoid a failure or a deformation of the shaft.

# AC MOTOR & GEAR HEAD



## PRODUCTS

- |  |          |
|--|----------|
| 1. INDUCTION MOTOR                             | 6W~120W  |
| 2. REVERSIBLE MOTOR                            | 6W~120W  |
| 3. SPEED CONTROL INDUCTION MOTOR & CONTROLLER  | 15W~120W |
| 4. SPEED CONTROL REVERSIBLE MOTOR & CONTROLLER | 20W~120W |
| 5. MAGNETIC BRAKE INDUCTION MOTOR              | 15W~120W |
| 6. MAGNETIC BRAKE REVERSIBLE MOTOR             | 20W~120W |

# INDUCTION MOTOR(CE approved)

**6W**

**□60mm**

**LEAD WIRE TYPE**

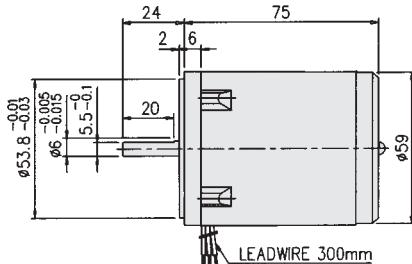
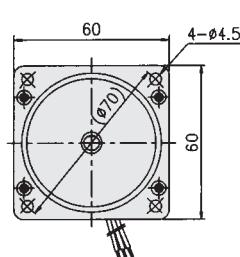
## MOTOR DIMENSIONS

10



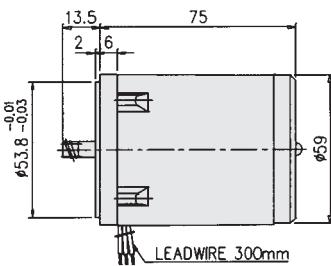
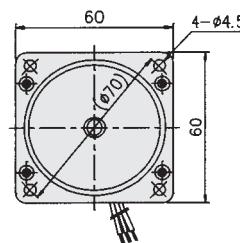
**6IN6S4H(L)**

WEIGHT 0.7kg

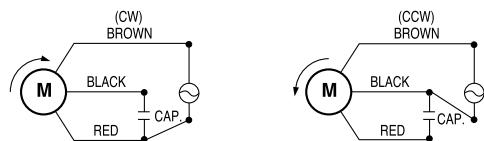


**6IN6G4H(L)**

WEIGHT 0.7kg



## WIRING DIAGRAM



## ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

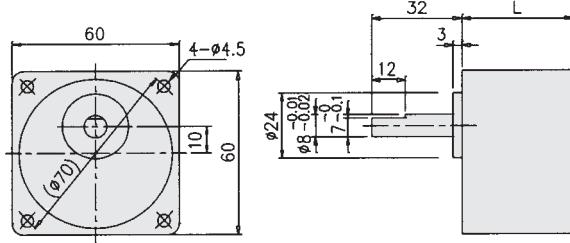
MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
					SPEED rpm	INPUT W	CURRENT mA	TORQUE					
STRAIGHT SHAFT	PINION SHAFT												
<b>6IN6S4L</b>	<b>6IN6G4L</b>	6	100	50	1250	28	280	0.5	0.05	0.55	0.055	400	4
				60	1550	28	280	0.4	0.04	0.55	0.055	400	4
<b>6IN6S4H</b>	<b>6IN6G4H</b>	6	220	50	1250	40	180	0.5	0.05	0.55	0.055	220	0.8
				60	1550	40	180	0.4	0.04	0.55	0.055	220	0.8
<b>6IN6S4C</b>	<b>6IN6G4C</b>	6	220~240	50	1250	45	190	0.4	0.04	0.55	0.055	240	0.8

# GEAR HEAD

## MOTOR DIMENSIONS

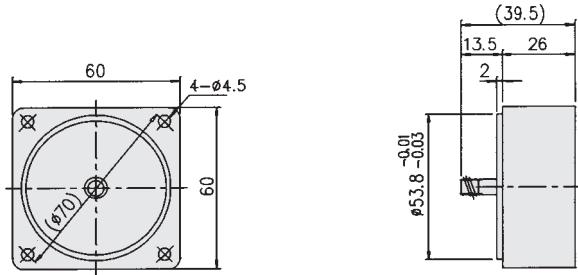


**GEARHEAD  
6G□Y(B)**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.25	M4×50
1/25~1/180	40	0.35	M4×60

**DECIMAL GEARHEAD  
6DG10Y(B)**



- ◊ □ OF GEAR HEAD MODEL NAME INDICATE THE DEDUCTION RATIO.
- ◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.
- THE NORMAL TORQUE(kg·cm) IS 30kg·cm IN CASE THE DECIMAL GEARHEAD OF THE DEDUCTION RATIO 1/10 IS CONNECTED.
- ◊ THE ROTATION DIRECTION OF OUTPUT SHAFT FOR THE GEARHEAD INDICATED ■ ROTATES WITH MOTOR ON THE CONTRARY.
- ◊ THE ACTUAL ROTATION SPEED IS 2-20% LESS THAN SYNCHRONOUS SPEED ACCORDING TO THE SIZE OF THE LOAD.

## 50HZ

	MODEL	rpm	500	416	300	250	200	166	120	100	83	75	60	50	42	30	25	20	16	15	12	10	8
		Ratio	3	3.6	5	6	7.5	9	12.5	15	18	20	25	30	36	50	60	75	90	100	120	150	180
	6G□Y 6G□B	kg·cm	1.3	1.5	2.1	2.6	3.2	3.9	5.4	6.4	7.7	8.5	9.7	11.6	13.9	17.5	21.0	26.2	30	30	30	20	30
		N·m	0.13	0.15	0.21	0.26	0.31	0.38	0.53	0.63	0.75	0.83	0.95	1.14	1.36	1.72	2.06	2.57	2.94	2.94	2.94	2.94	2.94

## 60HZ

	MODEL	rpm	600	500	360	300	240	200	144	120	100	90	72	60	50	36	30	24	20	18	15	12	10
		Ratio	3	3.6	5	6	7.5	9	12.5	15	18	20	25	30	36	50	60	75	90	100	120	150	180
	6G□Y 6G□B	kg·cm	1.0	1.3	1.7	2.1	2.6	3.1	4.4	5.2	6.3	6.6	8.2	9.8	11.8	16.4	18.2	22.5	26.5	29.5	30	30	30
		N·m	0.10	0.13	0.17	0.21	0.25	0.30	0.43	0.51	0.62	0.65	0.84	0.96	1.16	1.60	1.78	2.20	2.59	2.89	2.94	2.94	2.94

# INDUCTION MOTOR

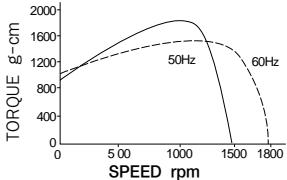
## MOTOR

### N - T CURVE

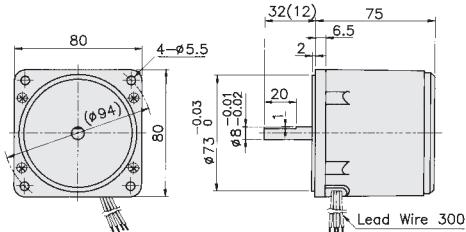
### MOTOR DIMENSIONS

### PINION SHAFT

① 8IN15S4□  
8IN15GN4□



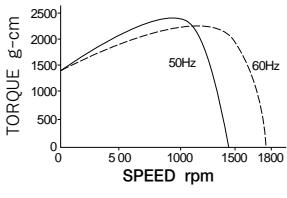
WEIGHT 1.5kg



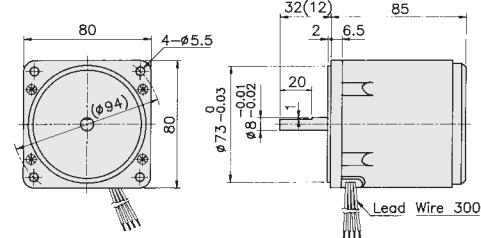
MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	φ 7.2mm
LENGTH	12mm

12

② 8IN25S4□  
8IN25GN4□

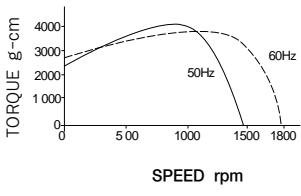


WEIGHT 1.6kg

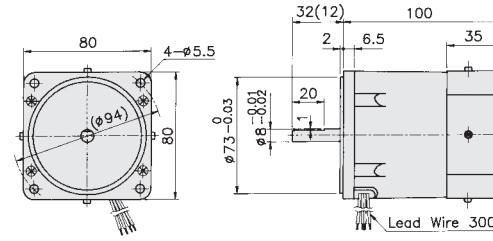


MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	φ 7.2mm
LENGTH	12mm

③ 8IF35S4□  
8IF35GN4□



WEIGHT 1.7kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	φ 7.2mm
LENGTH	12mm

#### ◆ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m		
①	8IN15S4L	8IN15GN4L	15	100	50	1250	45	400	1.10	0.108	0.68	0.067	800	3
						1550	45	400	0.90	0.088	0.68	0.067	750	
①	8IN15S4H	8IN15GN4H	15	220	50	1250	45	200	1.10	0.108	0.68	0.067	400	1.2
						1550	45	200	0.90	0.088	0.68	0.067	400	
②	8IN25S4L	8IN25GN4L	25	100	50	1250	60	600	1.75	0.172	1.00	0.098	1100	6
						1550	60	600	1.40	0.137	1.00	0.098	1000	
②	8IN25S4H	8IN25GN4H	25	220	50	1250	60	290	1.75	0.172	1.00	0.098	500	1.5
						1550	60	290	1.40	0.137	1.00	0.098	500	
③	8IF35S4L	8IF35GN4L	35	100	50	1200	100	1000	3.10	0.304	1.90	0.186	1300	10
						1500	100	1000	2.60	0.255	1.90	0.186	1300	
③	8IF35S4H	8IF35GN4H	35	220	50	1200	100	500	3.10	0.304	1.90	0.186	650	2
						1500	100	500	2.60	0.255	1.90	0.186	650	

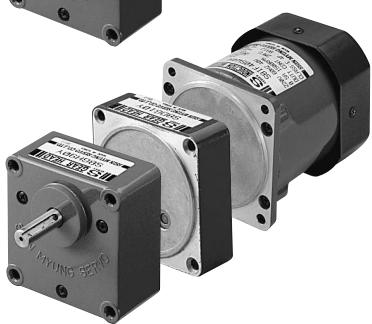
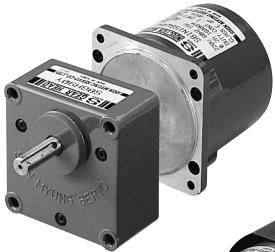
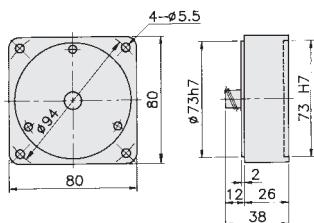
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

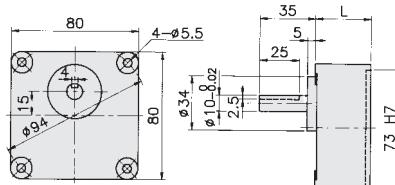
**② 8DGN10Y**

WEIGHT 0.3kg

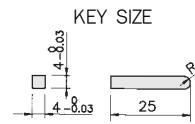


**I 8GN□B**

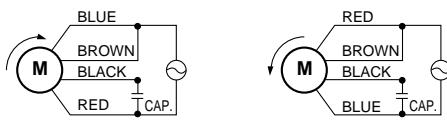
**8GN□Y**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
				60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
	② 8DGN10Y	① 8GN□Y, 8GN□B			2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
	② 8DGN10Y	① 8GN□Y, 8GN□B			2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
	② 8DGN10Y	① 8GN□Y, 8GN□B			4.1	6.8	10	17	20	31	37	55	83	100	100	D35	D35	D65	D80	D100
	② 8DGN10Y	① 8GN□Y, 8GN□B			4.1	6.8	10	17	20	31	37	55	83	100	100	D35	D35	D65	D80	D100
	② 8DGN10Y	① 8GN□Y, 8GN□B			7.6	13	19	32	38	57	68	100	100	100	100	D35	D35	D65	D80	D100
	② 8DGN10Y	① 8GN□Y, 8GN□B			7.6	13	19	32	38	57	68	100	100	100	100	D35	D35	D65	D80	D100

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR

## MOTOR

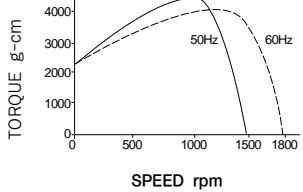
### N - T CURVE

### MOTOR DIMENSIONS

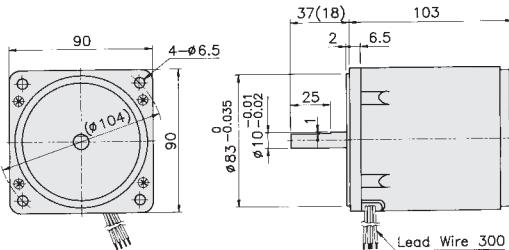
### PINION SHAFT

④ 9IN40S4□

9IN40P4□



WEIGHT 2.5kg

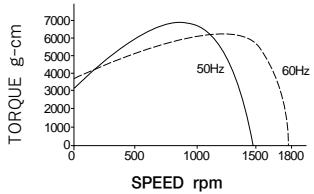


MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETER  
LENGTH

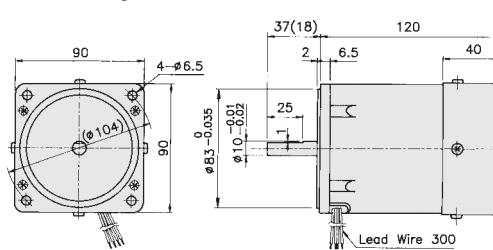
0.6  
20°  
12  
Φ9.63mm  
18mm

⑤ 9IF60S4□

9IF60P4□



WEIGHT 2.6kg

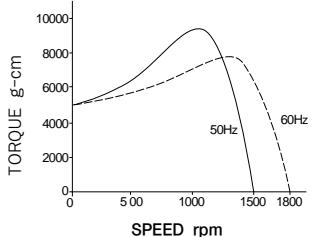


MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETER  
LENGTH

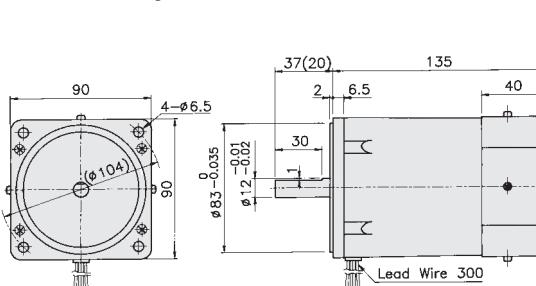
0.6  
20°  
12  
Φ9.63mm  
18mm

⑥ 9IF90S4□

9IF90E4□



WEIGHT 3.2kg

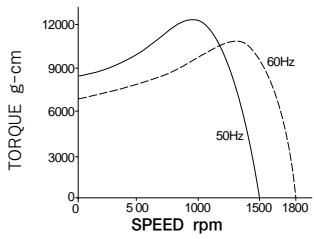


MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETER  
LENGTH

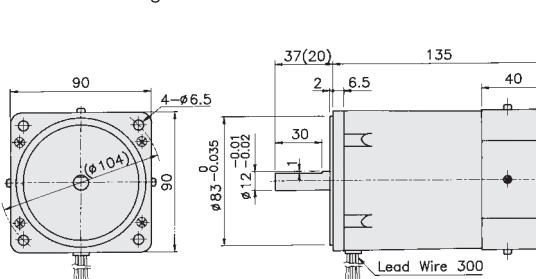
0.8  
20°  
11  
Φ11.55mm  
20mm

⑦ 9IF120S4□

9IF120E4□



WEIGHT 3.2kg



MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETER  
LENGTH

0.8  
20°  
11  
Φ11.55mm  
20mm

14

#### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m		
④	9IN40S4L	9IN40P4L	40	100	50	1250	110	1100	3.00	0.294	1.80	0.176	1700	10
					60	1550	110	1100	2.50	0.245	1.80	0.176	1600	
④	9IN40S4H	9IN40P4H	40	220	50	1250	110	520	3.00	0.294	1.80	0.176	1100	2
					60	1550	110	520	2.50	0.245	1.80	0.176	1100	
⑤	9IF60S4L	9IF60P4L	60	100	50	1250	150	1300	4.50	0.441	3.00	0.294	2200	16
					60	1550	150	1300	3.80	0.372	3.00	0.294	2200	
⑤	9IF60S4H	9IF60P4H	60	220	50	1250	150	700	4.50	0.441	3.00	0.294	1300	3.5
					60	1550	150	700	3.80	0.372	3.00	0.294	1300	
⑥	9IF90S4L	9IF90E4L	90	100	50	1250	200	2000	6.80	0.666	4.20	0.412	3200	25
					60	1550	200	2000	5.70	0.559	4.20	0.412	3000	
⑥	9IF90S4H	9IF90E4H	90	220	50	1250	200	1000	6.80	0.666	4.20	0.412	1600	5
					60	1550	200	1000	5.70	0.559	4.20	0.412	1500	
⑦	9IF120S4L	9IF120E4L	120	100	50	1350	240	2400	8.70	0.853	5.40	0.540	4800	35
					60	1600	240	2400	7.30	0.715	5.40	0.540	4600	
⑦	9IF120S4H	9IF120E4H	120	220	50	1350	350	1600	8.70	0.853	5.40	0.540	3200	6
					60	1600	350	1600	7.30	0.715	5.40	0.540	3200	

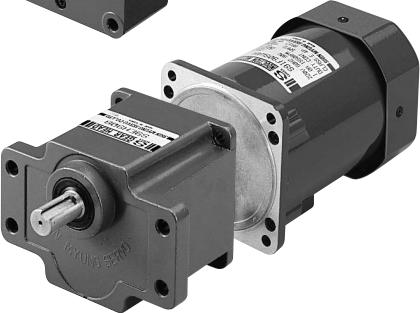
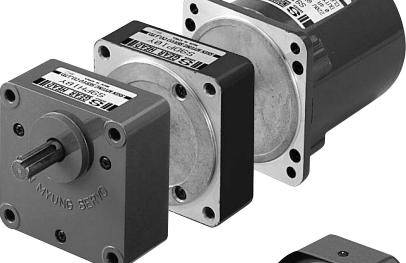
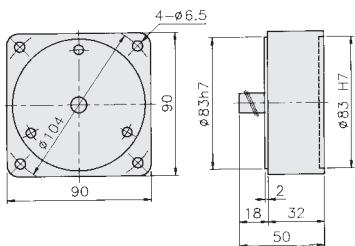
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

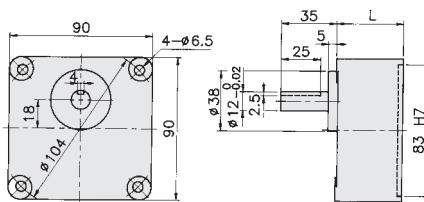
**4 9DP10Y**

WEIGHT 0.6kg



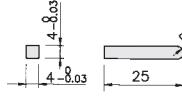
**3 9P□B**

**9P□Y**

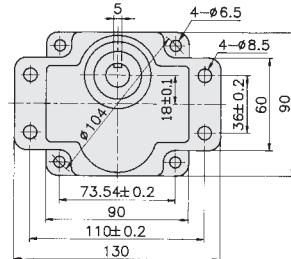


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80

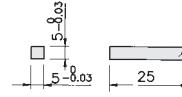
KEY SIZE



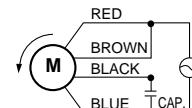
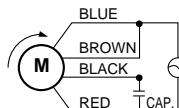
**5 9E□B**



KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS	500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1	
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750
			60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
<b>4 9DP10Y</b>		<b>3 9P□Y, 9P□B</b>		7.3	12	18	30	36	55	66	98	120	120	120	D 120				
<b>4 9DP10Y</b>		<b>3 9P□Y, 9P□B</b>		7.3	12	18	30	36	55	66	98	120	120	120	D 120				
<b>4 9DP10Y</b>		<b>3 9P□Y, 9P□B</b>		11	18	28	46	55	83	100	120	120	120	120	D 120				
<b>4 9DP10Y</b>		<b>3 9P□Y, 9P□B</b>		11	18	28	46	55	83	100	120	120	120	120	D 120				
—		<b>5 9E□B</b>		17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—		<b>5 9E□B</b>		17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—		<b>5 9E□B</b>		21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-
—		<b>5 9E□B</b>		21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(CE approved)

## MOTOR

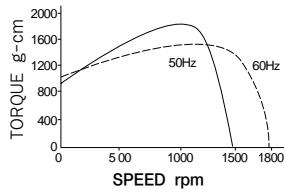
### N - T CURVE

### MOTOR DIMENSIONS

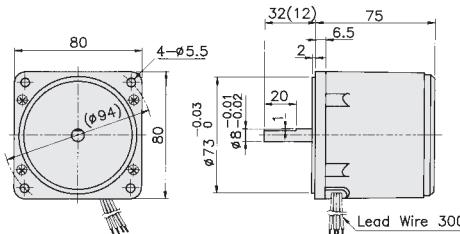
### PINION SHAFT

16

#### ⑧ 8IN15S4C 8IN15GN4C

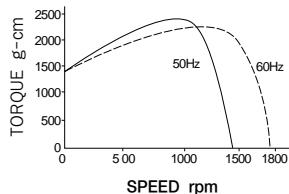


WEIGHT 1.5kg

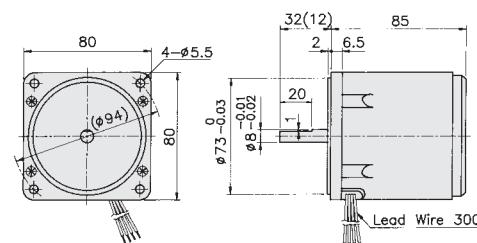


MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER ø 7.2mm  
LENGTH 12mm

#### ⑨ 8IN25S4C 8IN25GN4C

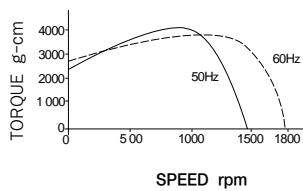


WEIGHT 1.6kg

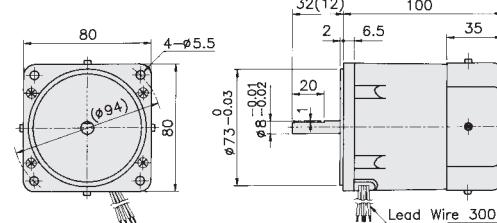


MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER ø 7.2mm  
LENGTH 12mm

#### ⑩ 8IF35S4C 8IF35GN4C



WEIGHT 1.7kg



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER ø 7.2mm  
LENGTH 12mm

#### ◆ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR µF	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE					
	STRAIGHT SHAFT	PINION SHAFT							kg-cm	N-m	kg-cm	N-m		
⑧	8IN15S4C	8IN15GN4C	15	220~240	50	1300	55	260	1.10	0.100	0.68	0.067	400	1.2
⑨	8IN25S4C	8IN25GN4C	25	220~240	50	1250	65	300	1.75	0.170	1.00	0.098	450	1.5
⑩	8IF35S4C	8IF35GN4C	35	220~240	50	1200	90	360	2.72	0.260	0.19	0.186	510	2.0

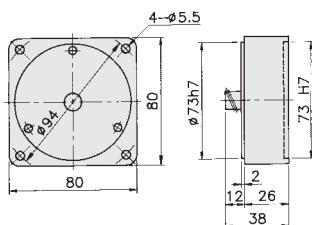
# GEAR HEAD

## DECIMAL GEAR HEAD

## GEAR HEAD (RATIO 1/3~1/180)

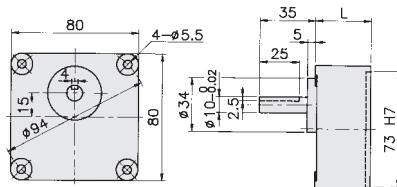
**2 8DGN10Y**

WEIGHT 0.3kg



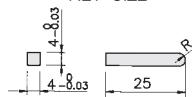
**I 8GN□B**

**8GN□Y**

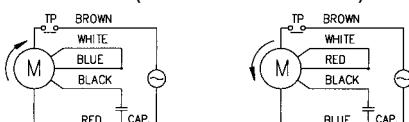


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
	28DGN10Y	18GN□Y, 8GN□B			2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
	28DGN10Y	18GN□Y, 8GN□B			4.1	6.8	10	17	20	31	37	55	83	100	100	D35	D35	D65	D80	D100
	28DGN10Y	18GN□Y, 8GN□B			7.6	13	19	32	38	57	68	100	100	100	100	D35	D35	D65	D80	D100

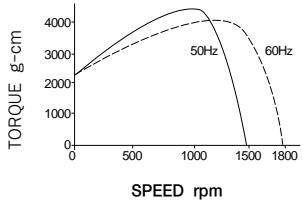
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(C E approved)

## MOTOR

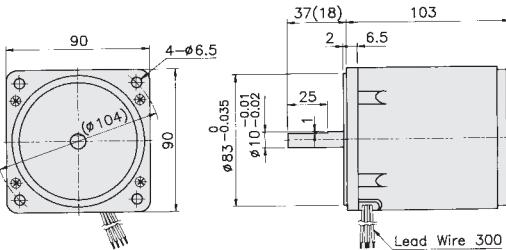
### N - T CURVE

⑪ 9IN40S4C  
9IN40P4C



### MOTOR DIMENSIONS

WEIGHT 2.5kg

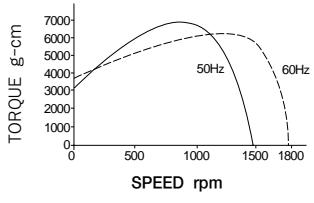


### PINION SHAFT

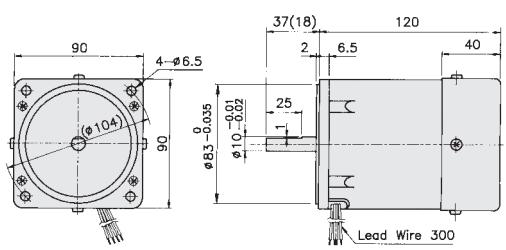
MODULE	0.6
PRESSURE ANGLE	20°
TEETH No.	12
DIAMETER	Φ 9.63mm
LENGTH	18mm

18

⑫ 9IF60S4C  
9IF60P4C

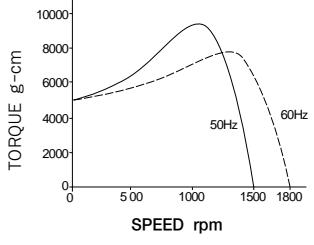


WEIGHT 2.6kg

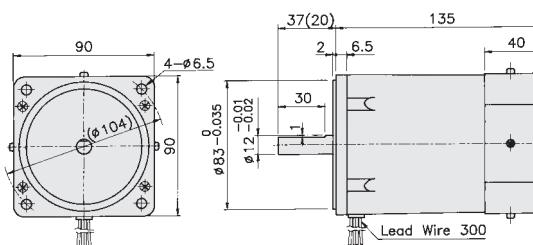


MODULE	0.6
PRESSURE ANGLE	20°
TEETH No.	12
DIAMETER	Φ 9.63mm
LENGTH	18mm

⑬ 9IF90S4C  
9IF90E4C

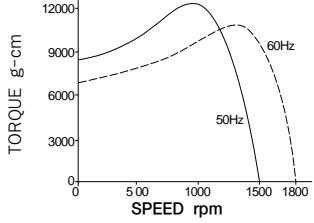


WEIGHT 3.2kg

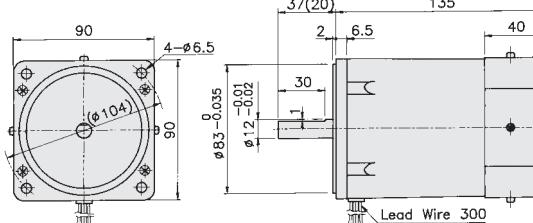


MODULE	0.8
PRESSURE ANGLE	20°
TEETH No.	11
DIAMETER	Φ 11.55mm
LENGTH	20mm

⑭ 9IF120S4C  
9IF120E4C



WEIGHT 3.2kg



MODULE	0.8
PRESSURE ANGLE	20°
TEETH No.	11
DIAMETER	Φ 11.55mm
LENGTH	20mm

#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR $\mu F$	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m		
⑪	9IN40S4C	9IN40P4C	40	220~240	50	1300	100	490	3.00	0.294	1.79	0.176	900	2.0
⑫	9IF60S4C	9IF60P4C	60	220~240	50	1300	160	700	4.50	0.441	3.00	0.294	1140	3.5
⑬	9IF90S4C	9IF90E4C	90	220~240	50	1300	200	1000	6.79	0.666	4.19	0.411	1480	5.0
⑭	9IF120S4C	9IF120E4C	120	220~240	50	1250	400	1800	8.70	0.853	5.61	0.550	2800	7.0

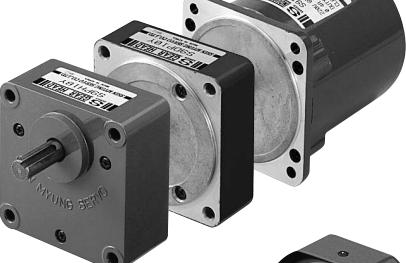
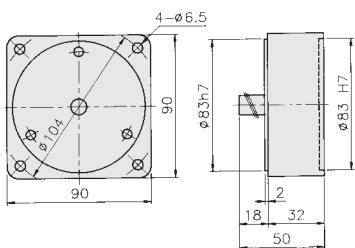
# GEAR HEAD

## DECIMAL GEAR HEAD

## GEAR HEAD (RATIO 1/3~1/180)

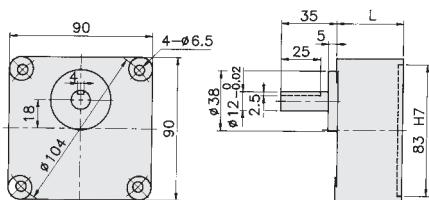
**4 9DP10Y**

WEIGHT 0.6kg

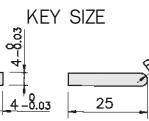


**3 9P□B**

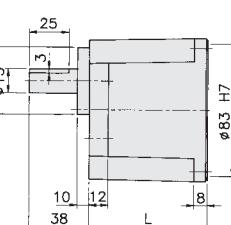
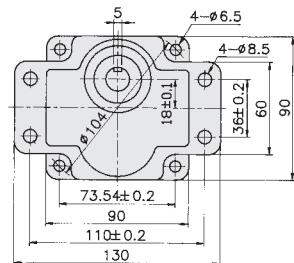
**3 9P□Y**



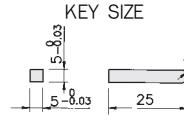
GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



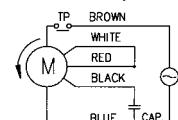
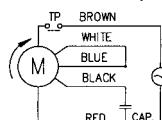
**5 9E□B**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	120	150	250	300	500	750
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>			7.3	12	18	30	36	55	66	98	120	120	120	D 120	D 120	D 120	D 120	D 120
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>			11	18	28	46	55	83	100	120	120	120	120	D 120	D 120	D 120	D 120	D 120
-	<b>5 9E□B</b>			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
-	<b>5 9E□B</b>			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(C E approved)

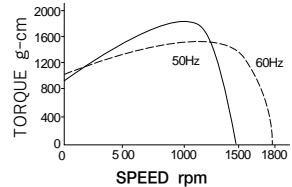
## MOTOR

### N - T CURVE

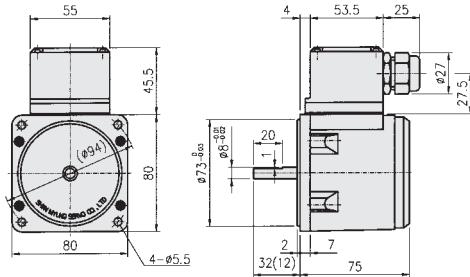
### MOTOR DIMENSIONS

### PINION SHAFT

⑯ 8IN15S4C-T  
8IN15GN4C-T



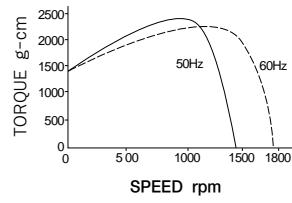
WEIGHT 1.7kg



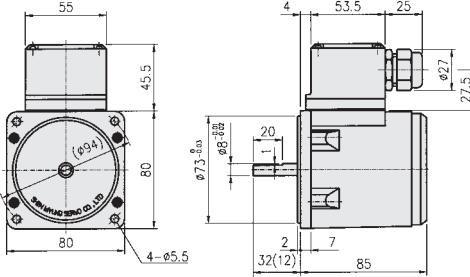
MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER #7.2mm  
LENGTH 12mm

20

⑰ 8IN25S4C-T  
8IN25GN4C-T

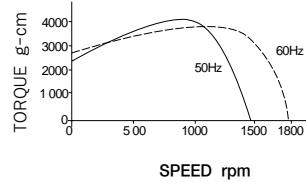


WEIGHT 1.8kg

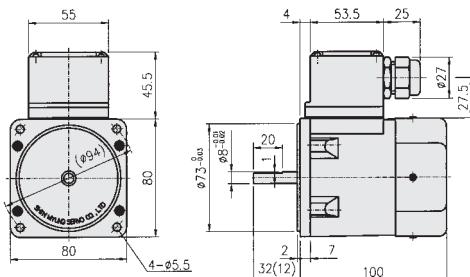


MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER #7.2mm  
LENGTH 12mm

⑱ 8IF35S4C-T  
8IF35GN4C-T



WEIGHT 1.9kg



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETER #7.2mm  
LENGTH 12mm

#### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED					STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE						
	STRAIGHT SHAFT	PINION SHAFT							kg-cm	N-m	kg-cm	N-m			
⑯	8IN15S4C-T	8IN15GN4C-T	15	220~240	50	1300	55	260	1.10	0.100	0.68	0.067	400	1.2	
⑰	8IN25S4C-T	8IN25GN4C-T	25	220~240	50	1250	65	300	1.75	0.170	1.00	0.098	450	1.5	
⑱	8IF35S4C-T	8IF35GN4C-T	35	220~240	50	1200	90	360	2.72	0.260	0.19	0.186	510	2.0	

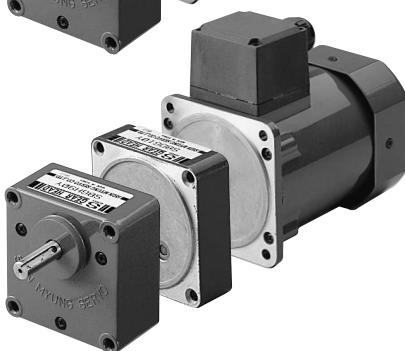
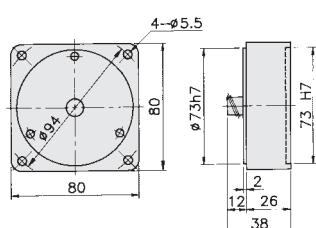
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

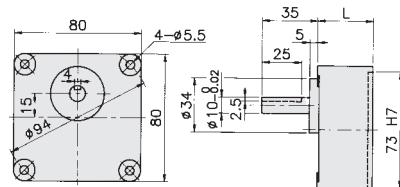
② 8DGN10Y

WEIGHT 0.3kg



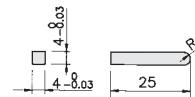
I 8GN□B

8GN□Y

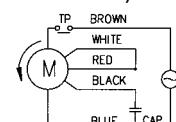
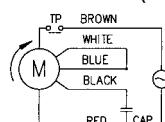


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750
	②8DGN10Y	①8GN□Y, 8GN□B		2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
	②8DGN10Y	①8GN□Y, 8GN□B		4.1	6.8	10	17	20	31	37	55	83	100	100	D35	D35	D65	D80	D100
	②8DGN10Y	①8GN□Y, 8GN□B		7.6	13	19	32	38	57	68	100	100	100	100	D35	D35	D65	D80	D100

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(CE approved)

## MOTOR

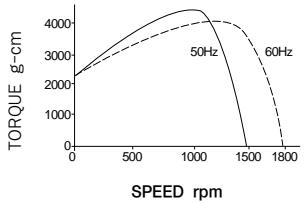
### N - T CURVE

### MOTOR DIMENSIONS

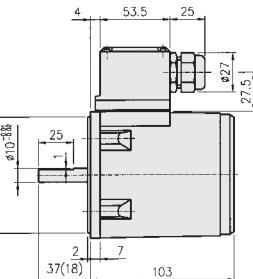
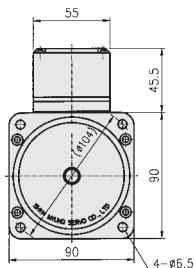
### PINION SHAFT

22

⑯ 9IN40S4C-T  
9IN40P4C-T

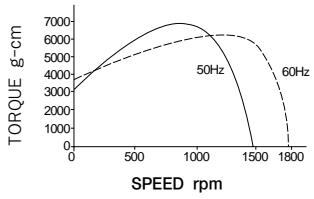


WEIGHT 2.7kg

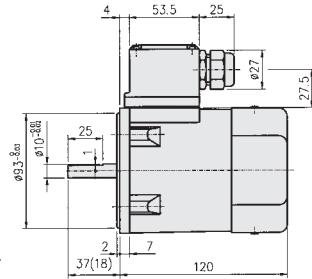
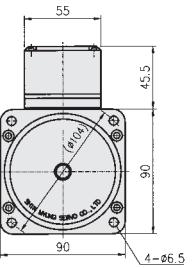


MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH NO. 12  
DIAMETER ø 9.63mm  
LENGTH 18mm

⑰ 9IF60S4C-T  
9IF60P4C-T

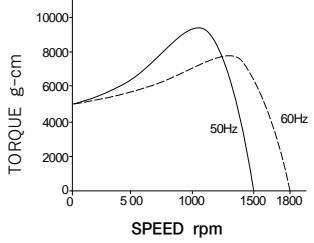


WEIGHT 2.8kg

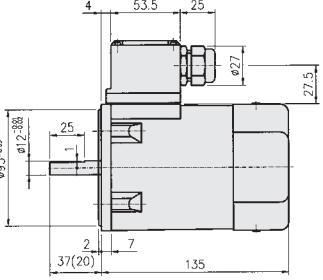
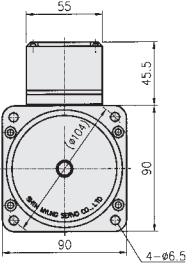


MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH NO. 12  
DIAMETER ø 9.63mm  
LENGTH 18mm

㉑ 9IF90S4C-T  
9IF90E4C-T

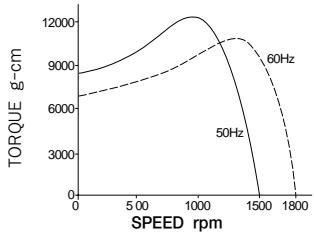


WEIGHT 3.4kg

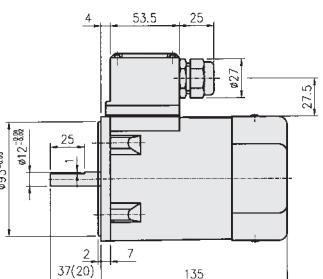
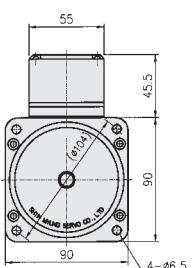


MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH NO. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

㉒ 9IF120S4C-T  
9IF120E4C-T



WEIGHT 3.4kg



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH NO. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR $\mu F$	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m		
⑯	9IN40S4C-T	9IN40P4C-T	40	220~240	50	1300	100	490	3.00	0.294	1.79	0.176	900	2.0
⑰	9IF60S4C-T	9IF60P4C-T	60	220~240	50	1300	160	700	4.50	0.441	3.00	0.294	1140	3.5
㉑	9IF90S4C-T	9IF90E4C-T	90	220~240	50	1300	200	1000	6.79	0.666	4.19	0.411	1480	5.0
㉒	9IF120S4C-T	9IF120E4C-T	120	220~240	50	1250	400	1800	8.70	0.853	5.61	0.550	2800	7.0

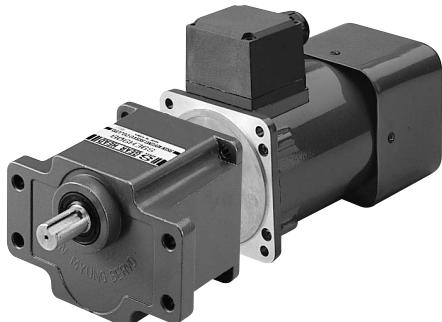
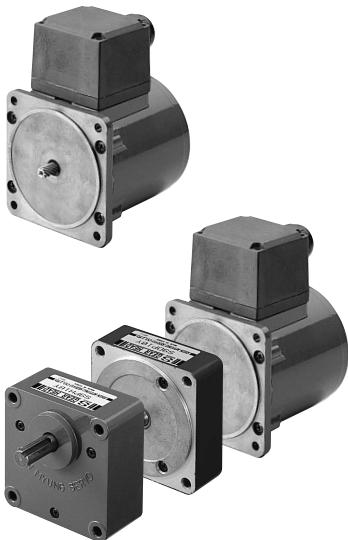
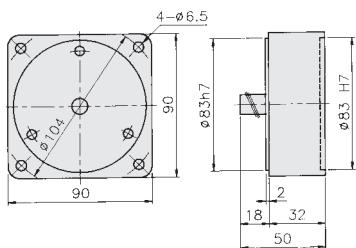
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

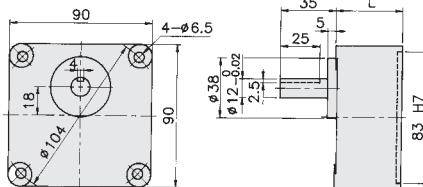
**4 9DP10Y**

WEIGHT 0.6kg

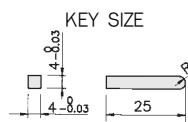


**3 9P□B**

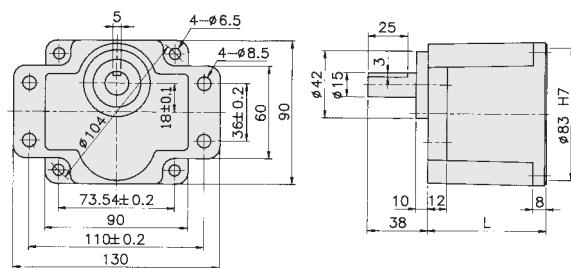
**9P□Y**



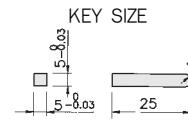
GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



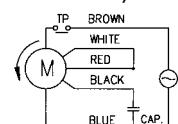
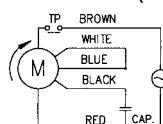
**5 9E□B**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	120	150	250	300	500	750
	<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>			7.3	12	18	30	36	55	66	98	120	120	120	D 120				
	<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>			11	18	28	46	55	83	100	120	120	120	120	D 120				
	-	<b>5 9E□B</b>			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
	-	<b>5 9E□B</b>			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(UL us approved)

## MOTOR

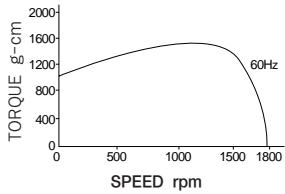
### N - T CURVE

### MOTOR DIMENSIONS

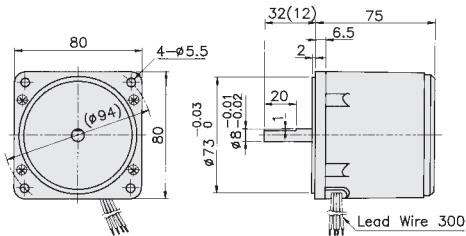
### PINION SHAFT

24

㉚ 8IN15S4U  
8IN15GN4U

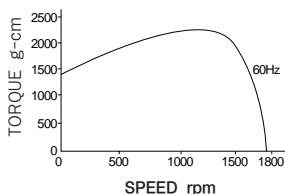


WEIGHT 1.5kg

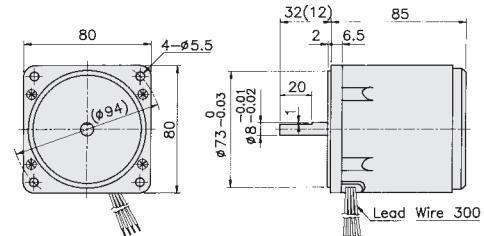


MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Ø 7.2mm
LENGTH	12mm

㉛ 8IN25S4U  
8IN25GN4U



WEIGHT 1.6kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Ø 7.2mm
LENGTH	12mm

#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "A"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED					STARTING TORQUE		STARTING CURRENT mA	CAPACITOR $\mu F$	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE						
	Straight Shaft	Pinion Shaft							kg-cm	N-m	kg-cm	N-m			
㉚	8IN15S4U	8IN15GN4U	15	115	60	1600	46	400	0.90	0.088	0.68	0.067	750	2.0	
㉛	8IN25S4U	8IN25GN4U	25	115	60	1550	69	600	1.4	0.137	1.0	0.098	1000	4.0	

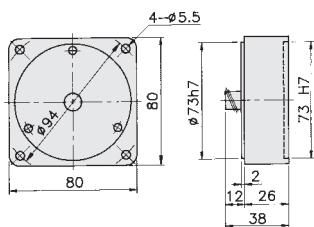
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

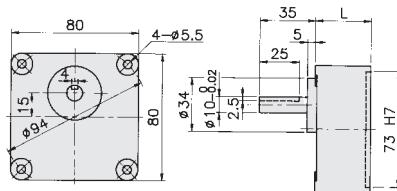
**2 8DGN10Y**

WEIGHT 0.3kg



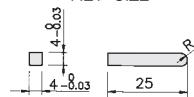
**I 8GN□B**

**8GN□Y**

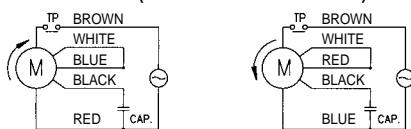


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

❖ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

❖ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

❖ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	600	360	240	144	100	60	36	24	18	12	7.2	5	3	2	1
			500	300	200	120	72	50	30	20	15	10	6	3.6	2.4	1.2	
		DENOMINATOR OF REDUCTION RATIO (60Hz)	3	5	7.5	12.5	18	30	50	75	100	150	250	360	600	900	1800
<b>2 8DGN10Y</b>	<b>1 8GN□Y, 8GN□B</b>	2	3	5	9	13	16	29	44	59	88	D35	D35	D65	D80	D100	
		2	4	6	10	16	19	35	53	70	100	D35	D65	D80	D100		
<b>2 8DGN10Y</b>	<b>1 8GN□Y, 8GN□B</b>	3	5	8	14	20	30	45	68	91	100	D35	D35	D65	D80	D100	
		4	6	10	17	25	36	55	82	100	100	D35	D65	D80	D100		

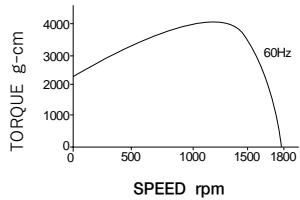
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR(UL us approved)

## MOTOR

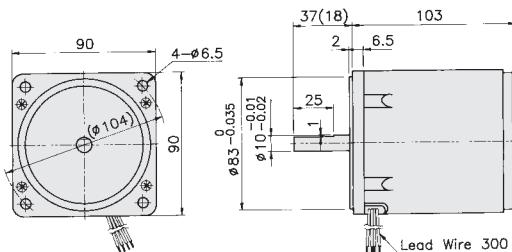
### N - T CURVE

㉔ 9IN40S4U  
9IN40P4U



### MOTOR DIMENSIONS

WEIGHT 2.5kg

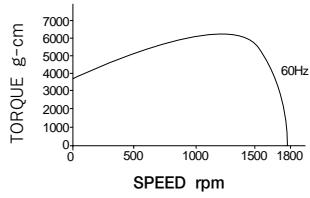


### PINION SHAFT

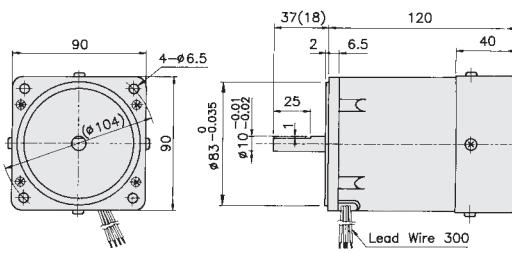
MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH NO. 12  
DIAMETER ɸ 9.63mm  
LENGTH 18mm

26

㉕ 9IF60S4U  
9IF60P4U

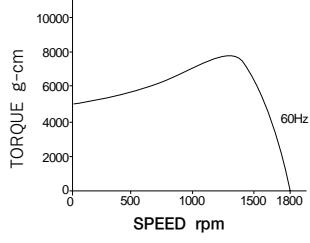


WEIGHT 2.6kg

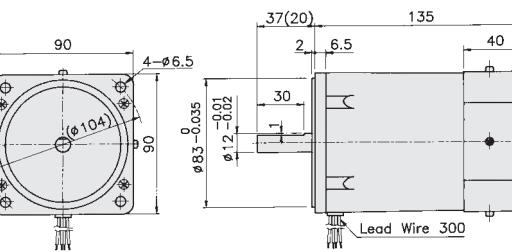


MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH NO. 12  
DIAMETER ɸ 9.63mm  
LENGTH 18mm

㉖ 9IF90S4U  
9IF90E4U



WEIGHT 3.2kg



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH NO. 11  
DIAMETER ɸ 11.55mm  
LENGTH 20mm

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "A"

FIG. NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF		
						SPEED rpm	INPUT W	CURRENT mA	TORQUE						
	Straight Shaft	Pinion Shaft				kg-cm	N-m	kg-cm	N-m						
㉔	9IN40S4U	9IN40P4U	40	115	60	1600	97	850	2.5	0.245	1.8	1.176	1600	8.0	
㉕	9IF60S4U	9IF60P4U	60	115	60	1600	149	1300	3.8	0.372	3.0	0.294	2200	12.0	
㉖	9IF90S4U	9IF90E4U	90	115	60	1600	230	2000	5.7	0.559	4.2	0.412	3000	20.0	

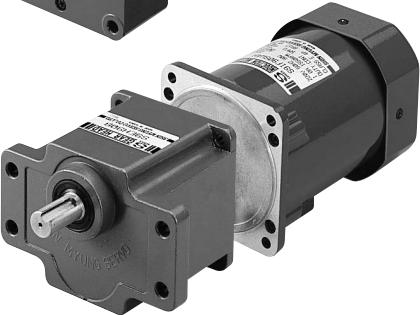
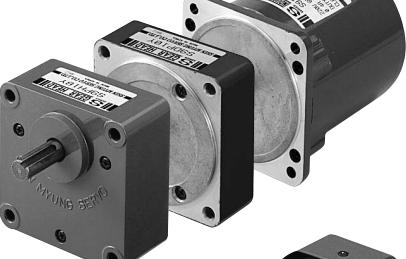
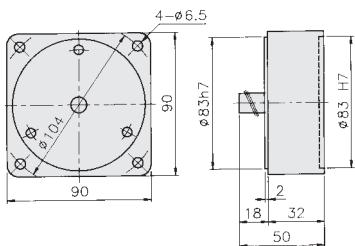
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

4 9DP10Y

WEIGHT 0.6kg



3 9P□Y  
9P□B

KEY SIZE

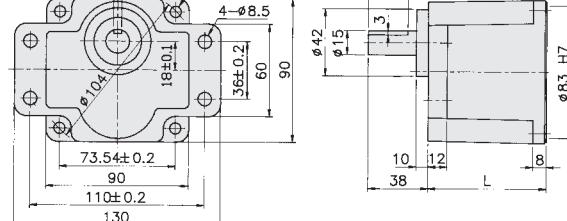
GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80

KEY SIZE



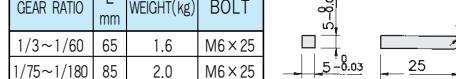
5 9E□B

KEY SIZE

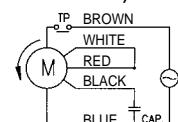
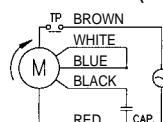


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	600	360	240	144	100	60	36	24	18	12	7.2	5	3	2	1
			500	300	200	120	72	50	30	20	15	10	6	3.6	2.4	1.2	
		DENOMINATOR OF REDUCTION RATIO (60Hz)	3	5	7.5	12.5	18	30	50	75	100	150	250	360	600	900	1800
4 9DP10Y	3 9P□Y, 9P□B	6	10	15	25	36	54	82	120	120	120	D120	D120	D120	D120	D120	D120
		7	12	18	30	45	65	98	120	120	120	D120	D120	D120	D120	D120	D120
4 9DP10Y	3 9P□Y, 9P□B	9	15	23	38	55	83	120	120	120	120	D120	D120	D120	D120	D120	D120
		11	18	27	46	69	99	120	120	120	120	D120	D120	D120	D120	D120	D120
-	5 9E□B	13	23	34	57	83	124	186	280	300	300						
		16	27	41	69	103	149	224	300	300	300						

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR D:USE DECIMAL GEAR

# INDUCTION MOTOR(UL us approved)

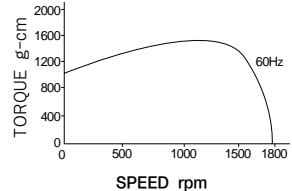
## MOTOR

### N - T CURVE

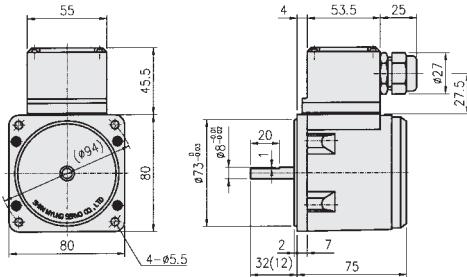
### MOTOR DIMENSIONS

### PINION SHAFT

㉗ 8IN15S4U -T  
8IN15GN4U -T



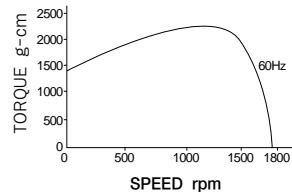
WEIGHT 1.7kg



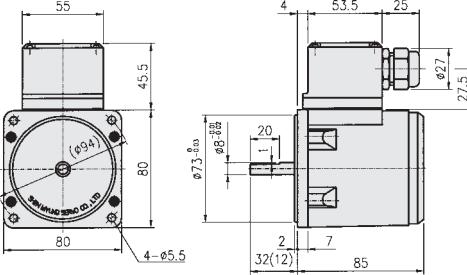
MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Ø 7.2mm
LENGTH	12mm

28

㉘ 8IN25S4U -T  
8IN25GN4U -T



WEIGHT 1.8kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Ø 7.2mm
LENGTH	12mm

❖ ELECTRICAL PERFORMANCES  
- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "A"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR mF	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE					
	STRAIGHT SHAFT	PINION SHAFT							kg-cm	N-m	kg-cm	N-m		
㉗	8IN15S4U-T	8IN15GN4U-T	15	115	60	1600	46	400	0.9	0.088	0.68	0.067	750	2.0
㉘	8IN25S4U-T	8IN25GN4U-T	25	115	60	1550	69	600	1.4	0.137	1.0	0.098	1000	4.0

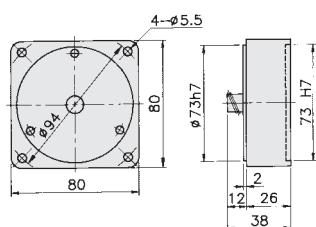
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

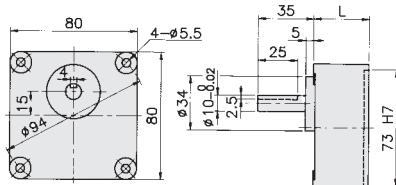
## GEAR HEAD (RATIO 1/3~1/180)

② 8DGN10Y

WEIGHT 0.3kg

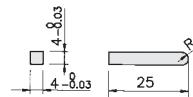


I 8GN□B  
8GN□Y

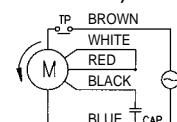
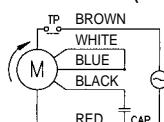


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	600	360	240	144	100	60	36	24	18	12	7.2	5	3	2	1
			500	300	200	120	72	50	30	20	15	10	6	3.6	2.4	1.2	
		DENOMINATOR OF REDUCTION RATIO (60Hz)	3	5	7.5	12.5	18	30	50	75	100	150	250	360	600	900	1800
②8DGN10Y	①8GN□Y, 8GN□B	2	3	5	9	13	16	29	44	59	88	D35	D35	D65	D80	D100	
		2	4	6	10	16	19	35	53	70	100	D35	D65	D80	D100		
②8DGN10Y	①8GN□Y, 8GN□B	3	5	8	14	20	30	45	68	91	100	D35	D35	D65	D80	D100	
		4	6	10	17	25	36	55	82	100	100	D35	D65	D80	D100		

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR (us approved)

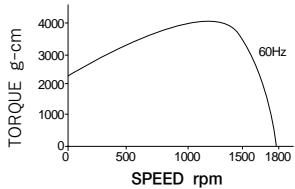
## MOTOR

### N - T CURVE

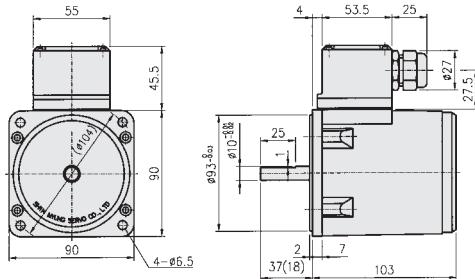
### MOTOR DIMENSIONS

### PINION SHAFT

㉙ 9IN40S4U -T  
9IN40P4U -T



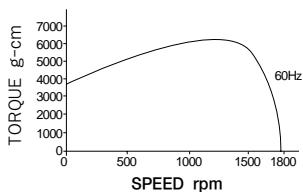
WEIGHT 2.7kg



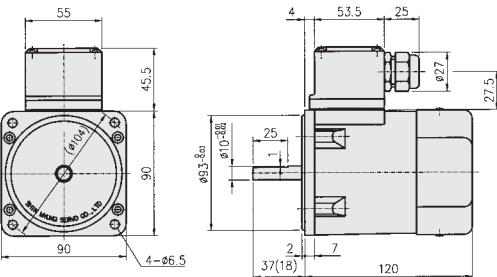
MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETER ø 9.63mm  
LENGTH 18mm

30

㉚ 9IF60S4U -T  
9IF60P4U -T

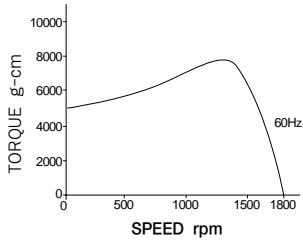


WEIGHT 2.8kg

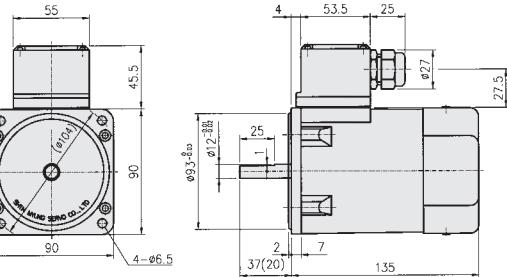


MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETER ø 9.63mm  
LENGTH 18mm

㉛ 9IF90S4U -T  
9IF90E4U -T



WEIGHT 3.4kg



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

#### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "A"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR µF		
						SPEED rpm	INPUT W	CURRENT mA	TORQUE						
	STRAIGHT SHAFT	PINION SHAFT							kg-cm	N-m					
㉙	9IN40S4U-T	9IN40P4U-T	40	115	60	1600	97	850	2.5	0.245	1.8	1.176	1600	8.0	
㉚	9IF60S4U-T	9IF60P4U-T	60	115	60	1600	149	1300	3.8	0.372	3.0	0.294	2200	12.0	
㉛	9IF90S4U-T	9IF90E4U-T	90	115	60	1600	230	2000	5.7	0.559	4.2	0.412	3000	20.0	

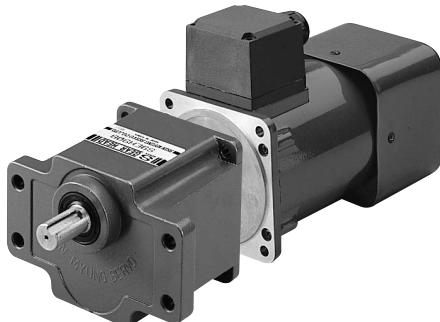
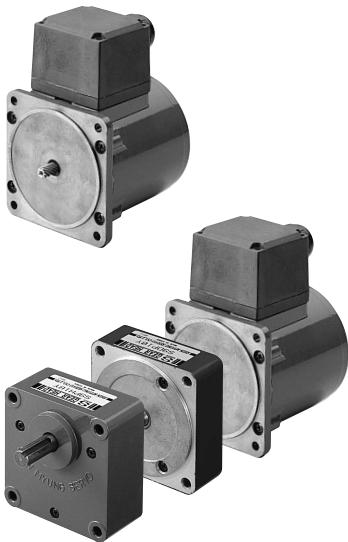
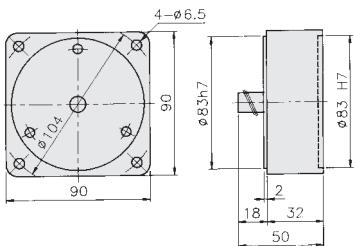
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

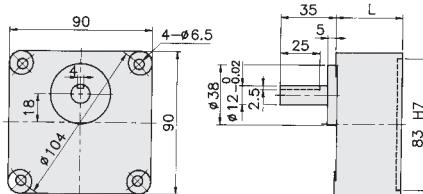
④ 9DP10Y

WEIGHT 0.6kg

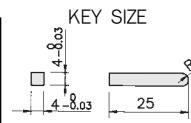


③ 9P□B

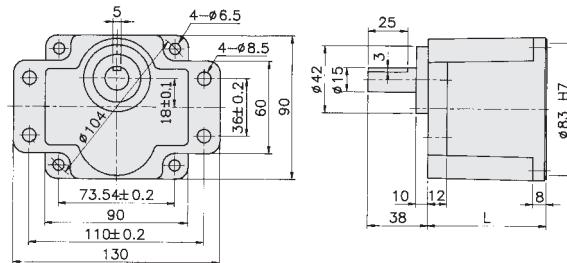
9P□Y



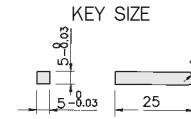
GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



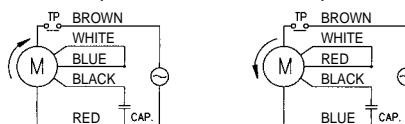
⑤ 9E□B



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	600	360	240	144	100	60	36	24	18	12	7.2	5	3	2	1
			500	300	200	120	72	50	30	20	15	10	6	3.6	2.4	1.2	
		DENOMINATOR OF REDUCTION RATIO (60Hz)	3	5	7.5	12.5	18	30	50	75	100	150	250	360	600	900	1800
④ 9DP10Y	③ 9P□Y, 9P□B		6	10	15	25	36	54	82	120	120	120	D120	D120	D120	D120	D120
			7	12	18	30	45	65	98	120	120	120	D120	D120	D120	D120	D120
④ 9DP10Y	③ 9P□Y, 9P□B		9	15	23	38	55	83	120	120	120	120	D120	D120	D120	D120	D120
			11	18	27	46	69	99	120	120	120	120	D120	D120	D120	D120	D120
-	⑤ 9E□B		13	23	34	57	83	124	186	280	300	300					
			16	27	41	69	103	149	224	300	300	300					

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# INDUCTION MOTOR

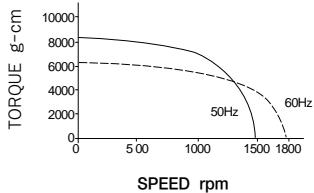
## MOTOR

### N - T CURVE

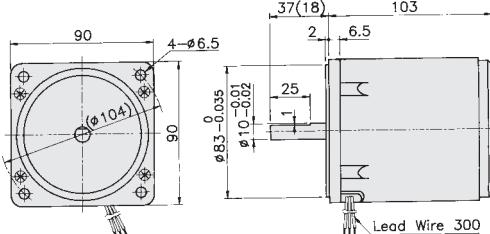
### MOTOR DIMENSIONS

### PINION SHAFT

③ 9IN40S4□  
9IN40P4□



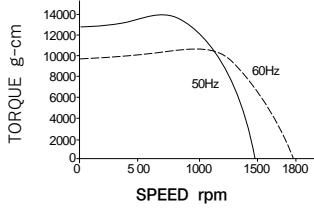
WEIGHT 2.5kg



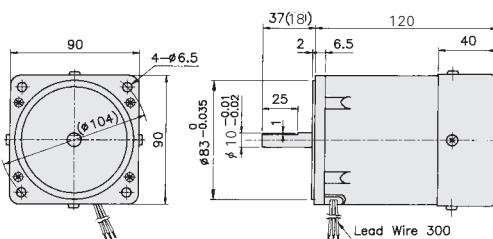
MODULE	0.6
PRESSURE	20°
TEETH No.	12
DIAMETER	Φ 9.63mm
LENGTH	18mm

32

③ 9IF60S4□  
9IF60P4□



WEIGHT 2.6kg



MODULE	0.6
PRESSURE	20°
ANGLE	12
TEETH No.	12
DIAMETER	Φ 9.63mm
LENGTH	18mm



#### ◆ ELECTRICAL PERFORMANCES

- THREE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG. NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE			
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE				
									kg-cm	N-m	kg-cm	N-m	
③	9IN40S4J	9IN40P4J	40	220	50	1300	90	400	3.00	0.294	6.50	0.637	
					60	1550	90	400	2.60	0.255	5.00	0.490	
③	9IN40S4K	9IN40P4K	40	380	50	1300	90	230	3.00	0.294	6.50	0.637	
					60	1550	90	230	2.60	0.255	5.00	0.490	
③	9IN40S4Z	9IN40P4Z	40	440	50	1300	90	200	3.00	0.294	6.50	0.637	
					60	1550	90	200	2.60	0.255	5.00	0.490	
③	9IF60S4J	9IF60P4J	60	220	50	1300	135	600	4.50	0.441	7.50	0.735	
					60	1550	135	600	3.80	0.372	6.00	0.588	
③	9IF60S4K	9IF60P4K	60	380	50	1300	135	350	4.50	0.441	7.50	0.735	
					60	1550	135	350	3.80	0.372	7.50	0.588	
③	9IF60S4Z	9IF60P4Z	60	440	50	1300	135	300	4.50	0.441	7.50	0.735	
					60	1550	135	300	3.80	0.372	6.00	0.588	

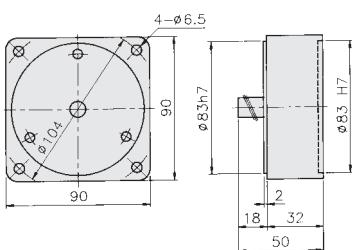
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

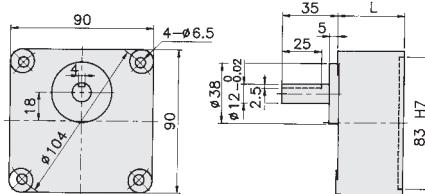
④ 9DP10Y

WEIGHT 0.6kg

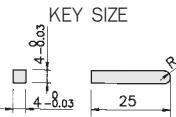


③ 9P□B

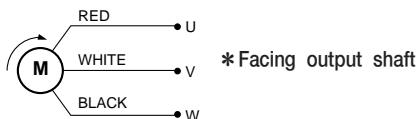
9P□Y



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



### WIRING(THREE PHASE MOTOR)



As for CCW rotation, change the  
2wires among U.V.W shown above.

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
			60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
④S9DP10Y	③9P□Y, 9P□B			7.6	13	19	32	38	57	68	102	120	120	120	D 120	D 120	D 120	D 120	
④S9DP10Y	③9P□Y, 9P□B			7.6	13	19	32	38	57	68	102	120	120	120	D 120	D 120	D 120	D 120	
④S9DP10Y	③9P□Y, 9P□B			7.6	13	19	32	38	57	68	102	120	120	120	D 120	D 120	D 120	D 120	
④S9DP10Y	③9P□Y, 9P□B			11	18	28	46	55	83	100	120	120	120	120	D 120	D 120	D 120	D 120	
④S9DP10Y	③9P□Y, 9P□B			11	18	28	46	55	83	100	120	120	120	120	D 120	D 120	D 120	D 120	
④S9DP10Y	③9P□Y, 9P□B			11	18	28	46	55	83	100	120	120	120	120	D 120	D 120	D 120	D 120	

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR D:USE DECIMAL GEAR

# INDUCTION MOTOR

## MOTOR

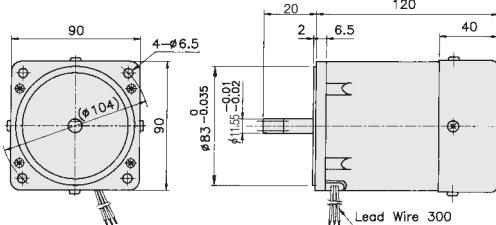
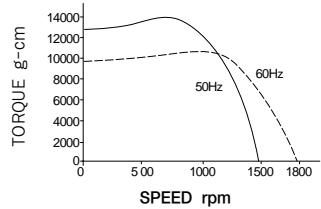
### N - T CURVE

### MOTOR DIMENSIONS

### PINION SHAFT

④ 9IF60E4□

WEIGHT 2.6kg



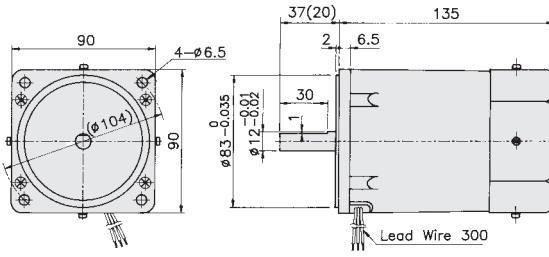
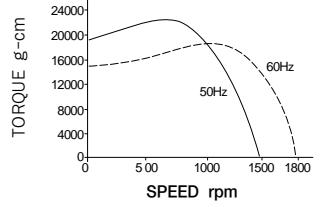
MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER  $\Phi 11.55\text{mm}$   
LENGTH 20mm

34

⑤ 9IF90S4□

9IF90E4□

WEIGHT 3.2kg

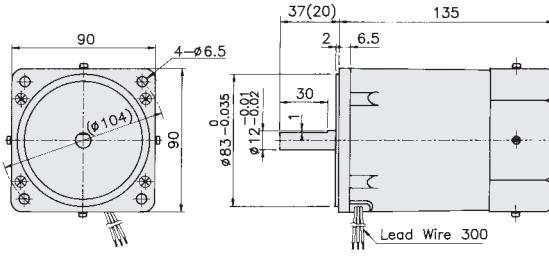
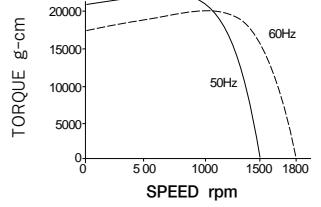


MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER  $\Phi 11.55\text{mm}$   
LENGTH 20mm

⑥ 9IF120S4□

9IF120E4□

WEIGHT 3.2kg



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER  $\Phi 11.55\text{mm}$   
LENGTH 20mm

#### ❖ ELECTRICAL PERFORMANCES

- THREE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE					
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m			
									kg-cm	N-m					
④	-	9IF60E4J	60	220	50	1300	135	600	4.50	0.441	7.50	0.735			
					60	1550	135	600	3.80	0.372	6.00	0.588			
④	-	9IF60E4K	60	380	50	1300	135	350	4.50	0.441	7.50	0.735			
					60	1550	135	350	3.80	0.372	6.00	0.588			
④	-	9IF60E4Z	60	440	50	1300	135	300	4.50	0.441	7.50	0.735			
					60	1550	135	300	3.80	0.372	6.00	0.588			
⑤	9IF90S4J	9IF90E4J	90	220	50	1250	180	800	6.80	0.666	8.50	0.833			
					60	1500	180	800	5.70	0.559	7.00	0.686			
⑤	9IF90S4K	9IF90E4K	90	380	50	1250	180	450	6.80	0.666	8.50	0.833			
					60	1500	180	450	5.70	0.559	7.00	0.686			
⑤	9IF90S4Z	9IF90E4Z	90	440	50	1250	180	400	6.80	0.666	8.50	0.833			
					60	1500	180	400	5.70	0.559	7.00	0.686			
⑥	9IF120S4J	9IF120E4J	120	220	50	1300	240	1000	9.00	0.882	16.00	1.568			
					60	1550	240	1000	7.60	0.745	14.00	1.372			
⑥	9IF120S4K	9IF120E4K	120	380	50	1300	240	600	9.00	0.882	16.00	1.568			
					60	1550	240	600	7.60	0.745	14.00	1.372			
⑥	9IF120S4Z	9IF120E4Z	120	440	50	1300	240	500	9.00	0.882	16.00	1.568			
					60	1550	240	500	7.60	0.745	14.00	1.372			

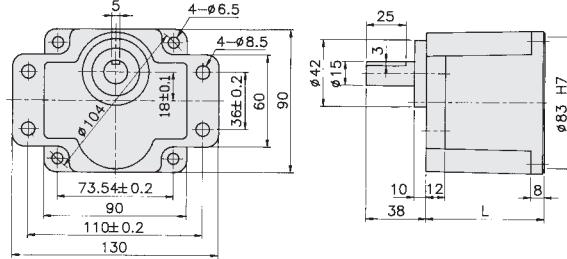
# GEAR HEAD

DECIMAL GEAR HEAD (RATIO 1/10)

GEAR HEAD (RATIO 1/3~1/180)

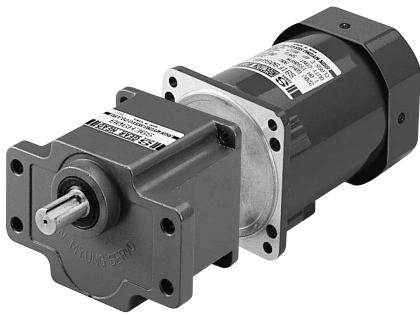
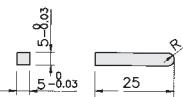


5 9E□B

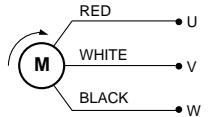


GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25

KEY SIZE



WIRING(THREE PHASE MOTOR)



\* Facing output shaft

◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◊ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◊ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
			60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
-	5 9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
-	5 9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
-	5 9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
-	5 9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
-	5 9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
-	5 9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
-	5 9E□B			22	37	55	83	100	150	180	299	300	300	300	-	-	-	-	-
-	5 9E□B			22	37	55	83	100	150	180	299	300	300	300	-	-	-	-	-
-	5 9E□B			22	37	55	83	100	150	180	299	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR

# INDUCTION MOTOR (2 POLES)

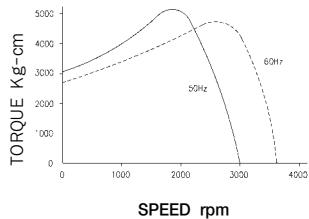
## MOTOR

### N - T CURVE

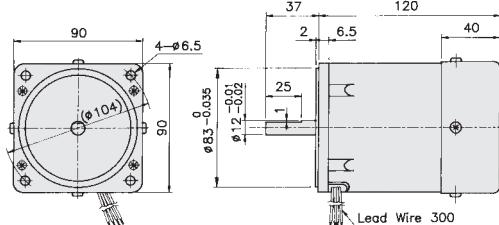
### MOTOR DIMENSIONS

36

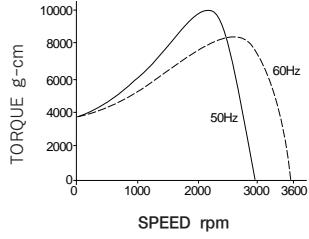
⑦ 9IF90S2L  
9IF90S2H



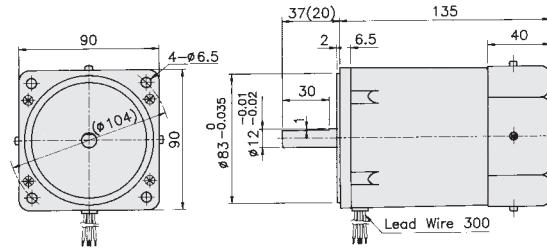
WEIGHT 2.6kg



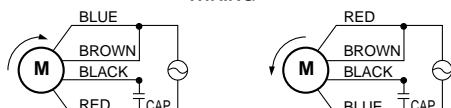
⑧ 9IF150S2L  
9IF150S2H



WEIGHT 3.2kg



### WIRING



\* Facing output shaft

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 2 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL	OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR $\mu F$	
					SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	Nm		
								kg-cm	Nm	kg-cm	Nm		
⑦	9IF90S2L	90	100	50	2600	190	1800	3.40	0.333	2.30	0.225	1400	
				60	3150	190	2000	2.80	0.274	2.30	0.225	1500	16
⑦	9IF90S2H	90	220	50	2600	280	1500	3.40	0.333	2.30	0.225	2400	
				60	3200	250	1200	2.80	0.274	2.30	0.225	2400	5.0
⑧	9IF150S2L	150	100	50	2650	300	2800	5.60	0.549	3.80	0.372	6800	
				60	3200	300	3200	4.60	0.451	3.80	0.372	6600	40
⑧	9IF150S2H	150	220	50	2650	300	1400	5.60	0.549	3.80	0.372	3400	
				60	3200	300	1600	4.60	0.451	3.80	0.372	3300	8

# REVERSIBLE MOTOR

A condenser driven type single-phase reversible motor has both 100V and 220V models.

Designed to operate in alternative repetition such as opening and closing gate, normal and the reversible movement of lift, starting and halting operation with the following features.

## 1. RATED HOUR

Suitable for using in operation where starting torque is necessary to be large and a short time is needed to reach loading torque, as continuous operation should be limited within 30 minutes. When normal and reversible operation or start and stop repetition is continued, the motor can be operated long within the temperature of the motor case at 90°C or below keeping an interval between the stops long.

## 2. CONTROLLER AND CONTROLLING TORQUE

Motor's responding speed is required to be quick at the operation of nomal and reversible revolution, braking and stoping.

The reversible motor with built-in controller works the mechanical controlling torque all the time as shown in the picture below. So the motor is designed to make an easy alternation from nomal to reverse motions and the like while in operation.

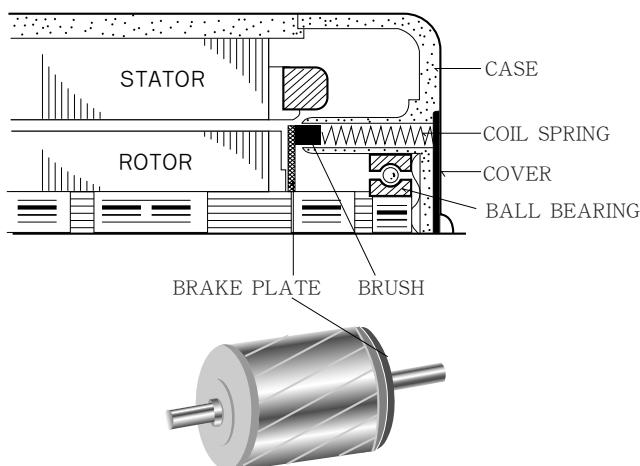
\* The life length of the controlling brush is about 5000 hours.

\* The following indicates motor's control characteristics.

MODEL	BRAKE TORQUE (g-cm)	OVER RUN	OVER RUN WITHOUT SOFT BRAKE
6RN6S	100	3-4	30~50
8RN20S	150	3-4	40~60
8RN25S	220	3-4	50~70
9RN40S	600	4-5	80~100
9RN60S	600	5-6	80~100
9RF90S	600	5-6	80~100
9RF120S	600	5-6	80~100

## 2) BRAKE TORQUE

The motor with controller makes resistance as brake torque when the motor axle is turned by outside force at the stop condition.



## 3. OVER RUN & BRAKE TORQUE

### 1) OVER RUN

When the motor runs in no-load condition at the rated voltage, the rotor continues to run by an inertia after electricity is off.

# REVERSIBLE MOTOR(CE approved)

**6W**

**□60mm**

**LEAD WIRE TYPE**

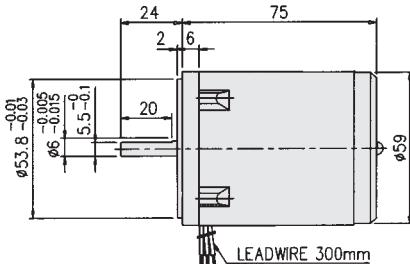
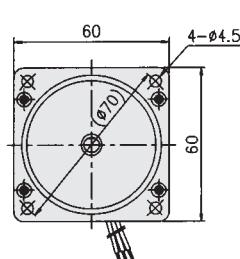
## MOTOR DIMENSIONS

38



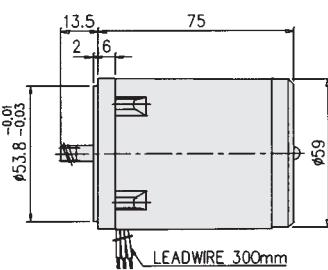
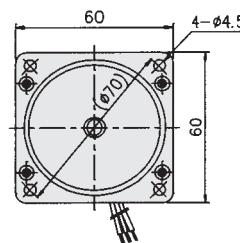
**6RN6S4H(L)**

WEIGHT 0.7kg

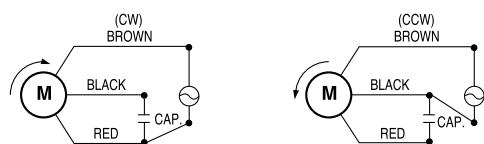


**6RN6G4H(L)**

WEIGHT 0.7kg



## WIRING DIAGRAM



## ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN DUTY, INSULATION CLASS "E"

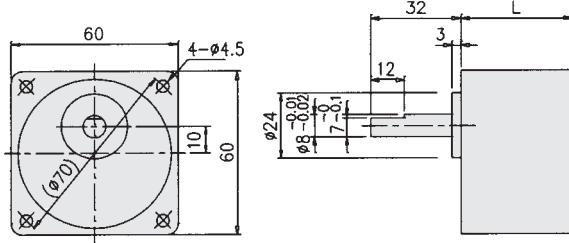
MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
					SPEED rpm	INPUT W	CURRENT mA	TORQUE					
Straight Shaft	Pinion Shaft												
<b>6RN6S4L</b>	<b>6RN6G4L</b>	6	100	50	1250	28	280	0.5	0.05	0.55	0.055	400	4
				60	1550	28	280	0.4	0.04	0.55	0.055	400	4
<b>6RN6S4H</b>	<b>6RN6G4H</b>	6	220	50	1250	36	160	0.5	0.05	0.68	0.069	200	1
				60	1550	36	160	0.4	0.04	0.68	0.069	200	1
<b>6RN6S4C</b>	<b>6RN6G4C</b>	6	220~240	50	1250	40	180	0.4	0.04	0.68	0.069	220	1

# GEAR HEAD

## MOTOR DIMENSIONS

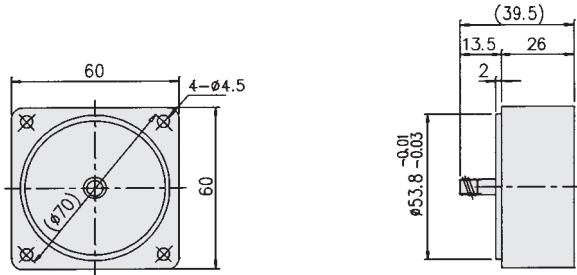


**GEARHEAD  
6G□Y(B)**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.25	M4×50
1/25~1/180	40	0.35	M4×60

**DECIMAL GEARHEAD  
6DG10Y(B)**



- ◊ □ OF GEAR HEAD MODEL NAME INDICATE THE DEDUCTION RATIO.
- ◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.
- THE NORMAL TORQUE(kg·cm) IS 30kg·cm IN CASE THE DECIMAL GEARHEAD OF THE DEDUCTION RATIO 1/10 IS CONNECTED.
- ◊ THE ROTATION DIRECTION OF OUTPUT SHAFT FOR THE GEARHEAD INDICATED ■ ROTATES WITH MOTOR ON THE CONTRARY.
- ◊ THE ACTUAL ROTATION SPEED IS 2-20% LESS THAN SYNCHRONOUS SPEED ACCORDING TO THE SIZE OF THE LOAD.

## 50HZ

	MODEL	rpm	500	416	300	250	200	166	120	100	83	75	60	50	42	30	25	20	16	15	12	10	8
		Ratio	3	3.6	5	6	7.5	9	12.5	15	18	20	25	30	36	50	60	75	90	100	120	150	180
	6G□B	kg·cm	1.3	1.5	2.1	2.6	3.2	3.9	5.4	6.4	7.7	8.5	9.7	11.6	13.9	17.5	21.0	26.2	30	30	30	20	30
		N·m	0.13	0.15	0.21	0.26	0.31	0.38	0.53	0.63	0.75	0.83	0.95	1.14	1.36	1.72	2.06	2.57	2.94	2.94	2.94	2.94	2.94

## 60HZ

	MODEL	rpm	600	500	360	300	240	200	144	120	100	90	72	60	50	36	30	24	20	18	15	12	10
		Ratio	3	3.6	5	6	7.5	9	12.5	15	18	20	25	30	36	50	60	75	90	100	120	150	180
	6G□B	kg·cm	1.0	1.3	1.7	2.1	2.6	3.1	4.4	5.2	6.3	6.6	8.2	9.8	11.8	16.4	18.2	22.5	26.5	29.5	30	30	30
		N·m	0.10	0.13	0.17	0.21	0.25	0.30	0.43	0.51	0.62	0.65	0.84	0.96	1.16	1.60	1.78	2.20	2.59	2.89	2.94	2.94	2.94

# REVERSIBLE MOTOR

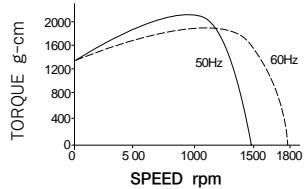
## MOTOR

### N - T CURVE

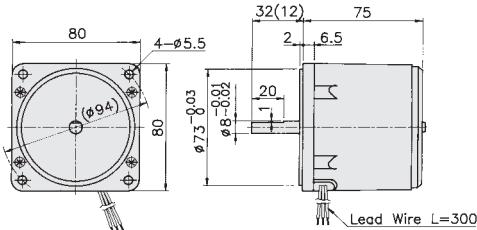
### MOTOR DIMENSIONS

### PINION SHAFT

#### ① 8RN20S4□ 8RN20GN4□



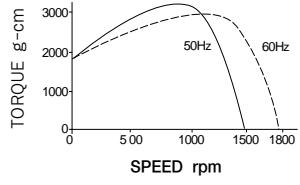
WEIGHT 1.5kg



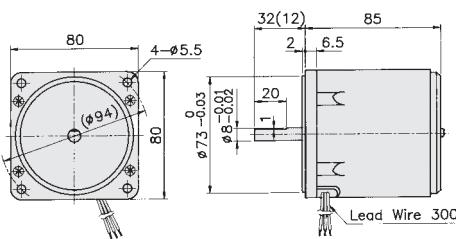
MODULE	0.5
PRESSURE ANGLE	20°
TEETH NO.	10
DIAMETER	Φ 7.2mm
LENGTH	12mm

40

#### ② 8RN25S4□ 8RN25GN4□



WEIGHT 1.6kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH NO.	10
DIAMETER	Φ 7.2mm
LENGTH	12mm



#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN DUTY, INSULATION CLASS "E"

FIG. NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE					
	STRAIGHT SHAFT	PINION SHAFT							kg·cm	Nm	kg·cm	Nm		
①	8RN20S4L	8RN20GN4L	20	100	50 60	1250 1550	50 50	500 500	1.50 1.17	0.147 0.115	1.04 1.04	0.102 0.102	900 850	8
①	8RN20S4H	8RN20GN4H	20	220	50 60	1250 1550	60 60	280 280	1.50 1.17	0.147 0.115	1.04 1.04	0.102 0.102	430 430	1.5
②	8RN25S4L	8RN25GN4L	25	100	50 60	1300 1600	65 65	650 650	1.80 1.37	0.176 0.134	1.28 1.28	0.125 0.125	1250 1200	10
②	8RN25S4H	8RN25GN4H	25	220	50 60	1300 1600	70 70	330 330	1.80 1.37	0.176 0.134	1.28 1.28	0.125 0.125	600 550	2

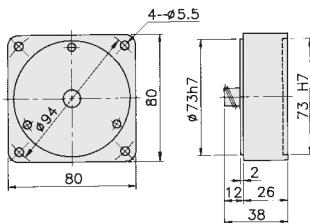
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

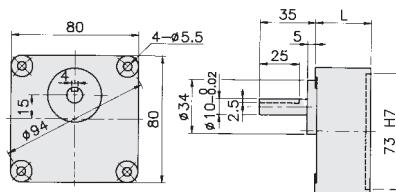
2 8DGN10Y

WEIGHT 0.3kg

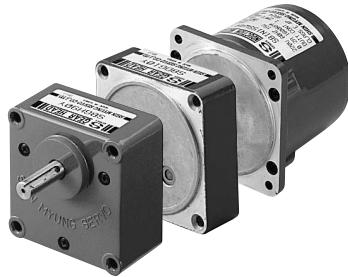
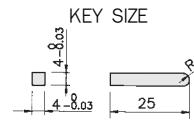


1 8GN□B

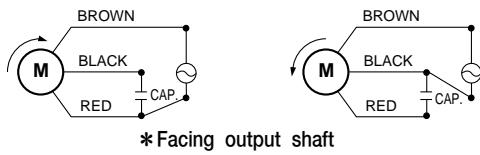
8GN□Y



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60



WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
			60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
28DGN10Y	18GN□Y, 8GN□B			3.4	5.7	8.5	14	17	26	31	46	69	92	100	D35	D35	D65	D80	D100
28DGN10Y	18GN□Y, 8GN□B			3.4	5.7	8.5	14	17	26	31	46	69	92	100	D35	D35	D65	D80	D100
28DGN10Y	18GN□Y, 8GN□B			4.0	6.7	10	17	20	30	36	54	81	100	100	D35	D35	D65	D80	D100
28DGN10Y	18GN□Y, 8GN□B			4.0	6.7	10	17	20	30	36	54	81	100	100	D35	D35	D65	D80	D100

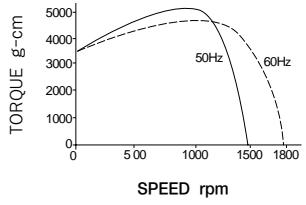
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# REVERSIBLE MOTOR

## MOTOR

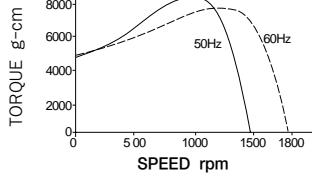
### N - T CURVE

③ 9RN40S4□  
9RN40P4□



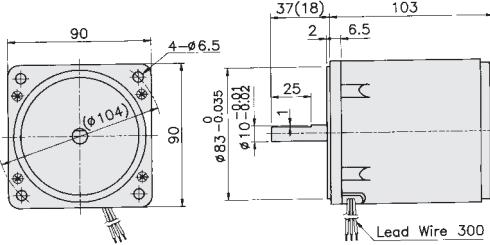
42

④ 9RN60S4□  
9RN60E4□



### MOTOR DIMENSIONS

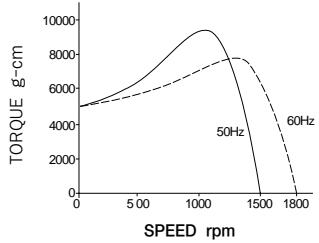
WEIGHT 2.5kg



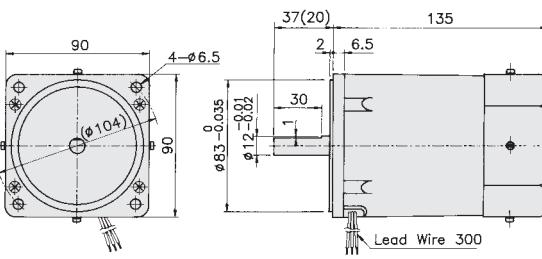
### PINION SHAFT

MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETER 9.63mm  
LENGTH 18mm

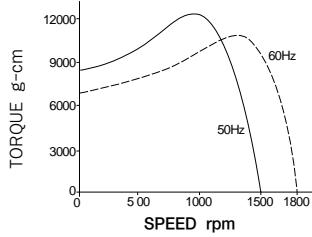
⑤ 9RF90S4□  
9RF90E4□



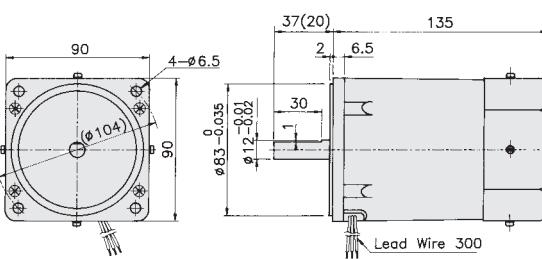
WEIGHT 2.6kg



⑥ 9RF120S4□  
9RF120E4□



WEIGHT 2.6kg



### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR μF	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	Nm		
									kg-cm	Nm	kg-cm	Nm	mA	
③	9RN40S4L	9RN40P4L	40	100	50	1200	115	1150	3.20	0.314	2.60	0.255	1850	16
						1500	115	1150	2.60	0.255	2.60	0.255	1850	
③	9RN40S4H	9RN40P4H	40	220	50	1200	140	650	3.20	0.314	2.60	0.255	900	3.5
						1500	140	650	2.60	0.255	2.60	0.255	900	
④	9RN60S4L	9RN60E4L	60	100	50	1300	180	1800	4.50	0.441	3.50	0.343	3000	25
						1600	180	1800	3.80	0.372	3.50	0.343	3000	
④	9RN60S4H	9RN60E4H	60	220	50	1300	220	1000	4.50	0.441	3.50	0.343	1700	5
						1600	220	1000	3.80	0.372	3.50	0.343	1700	
⑤	9RF90S4L	9RF90E4L	90	100	50	1250	200	2000	6.80	0.666	4.20	0.412	3200	25
						1550	200	2000	5.70	0.559	4.20	0.412	3000	
⑤	9RF90S4H	9RF90E4H	90	220	50	1250	200	1000	6.80	0.666	4.20	0.412	1600	5
						1550	200	1000	5.70	0.559	4.20	0.412	1500	
⑥	9RF120S4L	9RF120E4L	120	100	50	1350	240	2400	8.70	0.853	6.00	0.588	4800	35
						1600	240	2400	7.30	0.715	6.00	0.588	4600	
⑥	9RF120S4H	9RF120E4H	120	220	50	1300	320	1400	8.70	0.853	6.00	0.588	2200	7
						1600	320	1400	7.30	0.715	6.00	0.588	2200	

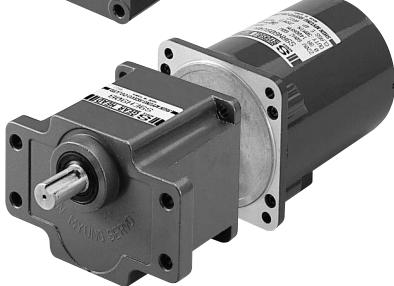
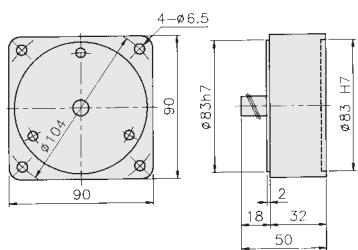
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

**4 9DP10Y**

WEIGHT 0.6kg



THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

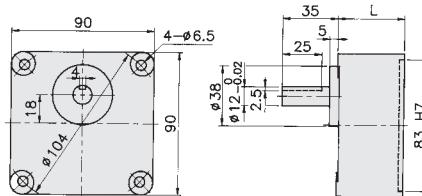
INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

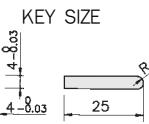
DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			3 50Hz	7.5 15	12.5 18	15 30	25 36	30 60	50 90	75 120	100 180	120 269	100 300	150 300	250 360	300 600	500 900	750 1500
		DENOMINATOR OF REDUCTION RATIO	60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900
<b>4 9DP10Y</b>	<b>3 9P□Y 9P□B</b>	7.6	13	19	32	38	57	68	102	120	120	120	D 120	D 120	D 120	D 120	D 120	
<b>4 9DP10Y</b>	<b>3 9P□Y S9P□B</b>	7.6	13	19	32	38	57	68	102	120	120	120	D 120	D 120	D 120	D 120	D 120	
—	<b>5 9E□B</b>	11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-	
—	<b>5 9E□B</b>	11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-	
—	<b>5 9E□B</b>	17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-	
—	<b>5 9E□B</b>	17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-	
—	<b>5 9E□B</b>	21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-	
—	<b>5 9E□B</b>	21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-	

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

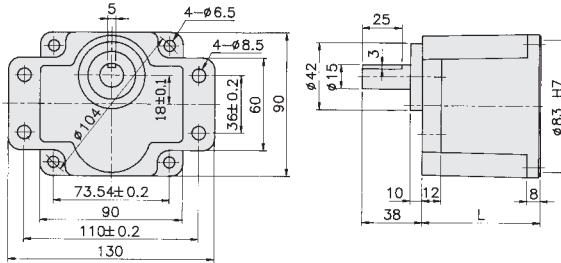
**3 9P□B**  
**9P□Y**



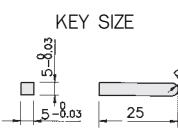
GEAR RATIO	mm L	mm W	mm H	BOLT
1/3~1/18	42	0.8	83	M6×65
1/25~1/180	60	0.9	83	M6×80



**5 9E□B**



GEAR RATIO	mm L	mm W	mm H	BOLT
1/3~1/60	65	1.6	83	M6×25
1/75~1/180	85	2.0	83	M6×25



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

# SPEED CONTROL INDUCTION MOTOR

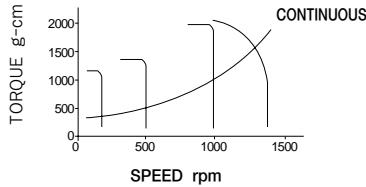
## MOTOR

### N - T CURVE

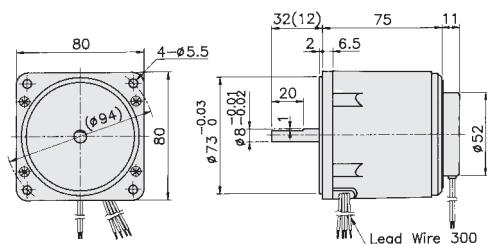
### MOTOR DIMENSIONS

### PINION SHAFT

① 8IN15S4□-V  
8IN15GN4□-V



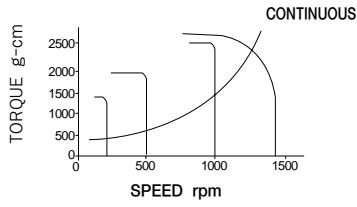
WEIGHT 1.6kg



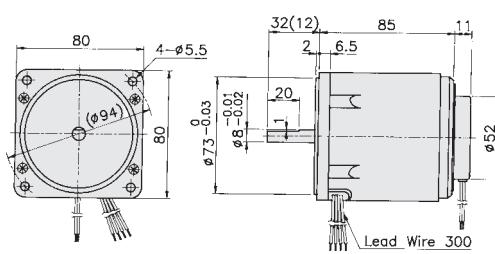
MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Φ 7.2mm
LENGTH	12mm

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② 8IN25S4□-V  
8IN25GN4□-V



WEIGHT 1.7kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETER	Φ 7.2mm
LENGTH	12mm



#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		MAXIMUM OUTPUT W	VOLTAGE V	FREQUENCY Hz	VARIABLE SPEED RANGE rpm	MAXIMUM CURRENT mA	STARTING TORQUE		ALLOWABLE TORQUE		CAPACITOR $\mu F$
	STRAIGHT SHAFT	PINION SHAFT						kg-cm	N-m	kg-cm	N-m	
①	8IN15S4L-V	8IN15GN4L-V	15	100	50 / 60	70~1400	460	0.68	0.067	0.30~1.6	0.029~0.157	3
①	8IN15S4H-V	8IN15GN4H-V	15	220	50 / 60	70~1400	250	0.68	0.067	0.30~1.6	0.029~0.157	1.2
②	8IN25S4L-V	8IN25GN4L-V	25	100	50 / 60	70~1400	600	1.00	0.098	0.35~1.9	0.034~0.186	6
②	8IN25S4H-V	8IN25GN4H-V	25	220	50 / 60	70~1400	320	1.00	0.098	0.35~1.10	0.034~0.186	1.5

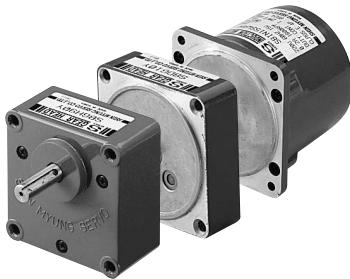
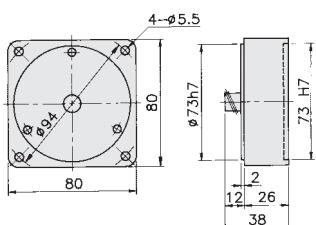
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

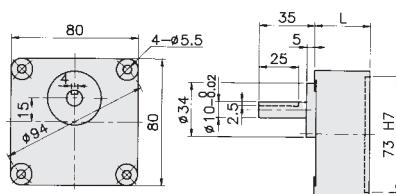
**2 8DGN10Y**

WEIGHT 0.6kg

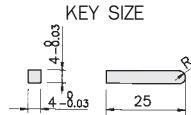


**1 8GN□B**

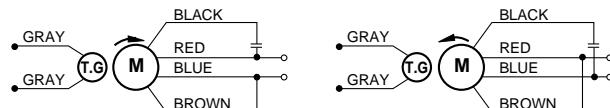
**8GN□Y**



GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SPEED RANGE	L.SPEED 70rpm	95	11.7	7.8	4.7	3.9	2.3	1.9	1.2	0.8	0.6	0.4
			H.SPEED 1400rpm	389	233	156	93	79	47	39	23	16	12	8
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150
28DGN10Y	18GN□Y, S8GN□B	Low speed	0.9	1.5	2.2	3.6	4.4	6.6	7.9	12	18	24	100	
		High speed	4.7	7.8	11.7	19	23	35	42	63	94	100	100	
28DGN10Y	18GN□Y, S8GN□B	Low speed	0.9	1.5	2.2	3.6	4.4	6.6	7.9	12	18	24	100	
		High speed	4.7	7.8	11.7	19	23	35	42	63	94	100	100	
28DGN10Y	18GN□Y, S8GN□B	Low speed	1.0	1.7	2.6	4.3	5.1	7.7	9.2	100	100	100	100	100
		High speed	5.5	9.2	14	23	28	42	50	100	100	100	100	100
28DGN10Y	18GN□Y, S8GN□B	Low speed	1.0	1.7	2.6	4.3	5.1	7.7	9.2	100	100	100	100	100
		High speed	5.5	9.2	14	23	28	42	50	100	100	100	100	100

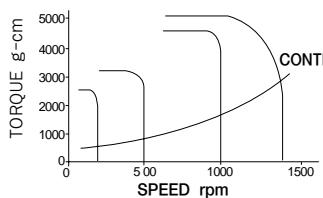
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# SPEED CONTROL INDUCTION MOTOR

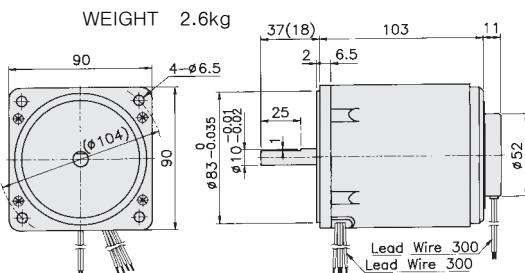
## MOTOR

### N - T CURVE

③ 9IN40S4□-V  
9IN40P4□-V



### MOTOR DIMENSIONS

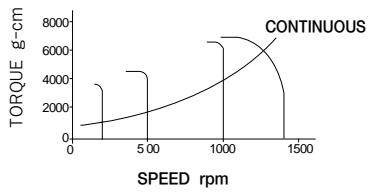


### PINION SHAFT

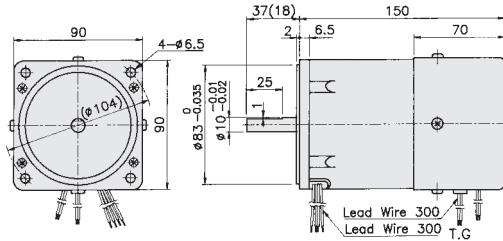
MODULE	0.6
PRESSURE ANGLE	20°
TEETH No.	12
DIAMETER	Ø9.63mm
LENGTH	18mm

46

④ 9IF60S4□-V  
9IF60P4□-V

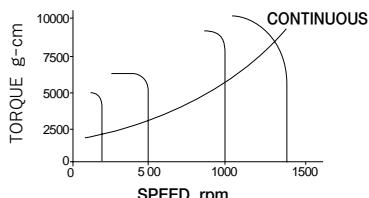


WEIGHT 2.9kg

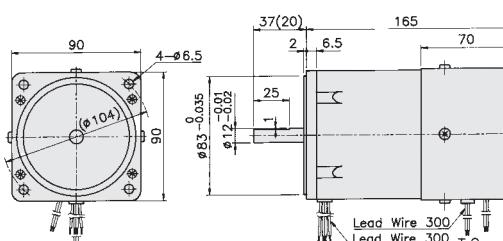


MODULE	0.6
PRESSURE ANGLE	20°
TEETH No.	12
DIAMETER	Ø9.63mm
LENGTH	18mm

⑤ 9IF90S4□-V  
9IF90E4□-V

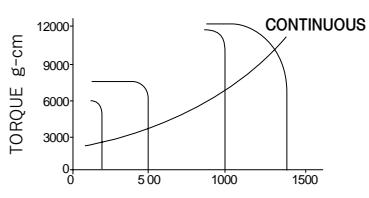


WEIGHT 3.5kg

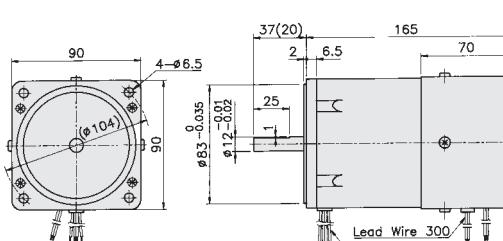


MODULE	0.8
PRESSURE ANGLE	20°
TEETH No.	11
DIAMETER	Ø11.55mm
LENGTH	20mm

⑥ 9IF120S4□-V  
9IF120E4□-V



WEIGHT 3.5kg



MODULE	0.8
PRESSURE ANGLE	20°
TEETH No.	11
DIAMETER	Ø11.55mm
LENGTH	20mm

! Attention : As the model no. 9IF60S(P)4L(H)-V, 9IF90S(E)4L(H)-V, 9IF120S(E)4L(H)-V each has a fan motor inside, the black lead wire should be connected to the wire no. 1 and 2 of the controller (Refer to use only the controller model no.2290G)

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

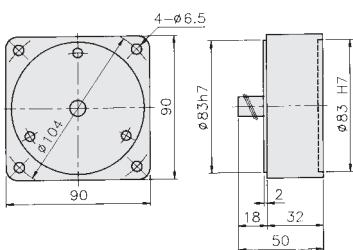
FIG NO.	MODEL		MAXIMUM OUTPUT W	VOLTAGE V	FREQUENCY Hz	VARIABLE SPEED RANGE rpm	MAXIMUM CURRENT mA	STARTING TORQUE		ALLOWABLE TORQUE		CAPACITOR $\mu F$
	STRAIGHT SHAFT	PINION SHAFT						kg-cm	N-m	kg-cm	N-m	
③	9IN40S4L-V	9IN40P4L-V	40	100	50 / 60	70~1400	1100	1.80	0.176	0.60~2.80	0.059~0.274	10
③	9IN40S4H-V	9IN40P4H-V	40	220	50 / 60	70~1400	600	1.80	0.176	0.60~2.80	0.059~0.274	2.0
④	9IF60S4L-V	9IF60P4L-V	60	100	50 / 60	70~1400	1300	3.00	0.294	1.20~3.70	0.118~0.363	16
④	9IF60S4H-V	9IF60P4H-V	60	220	50 / 60	70~1400	650	3.00	0.294	1.20~3.70	0.118~0.363	3.5
⑤	9IF90S4L-V	9IF90E4L-V	90	100	50 / 60	70~1400	2000	4.20	0.412	2.50~5.50	0.245~0.539	25
⑤	9IF90S4H-V	9IF90E4H-V	90	220	50 / 60	70~1400	1000	4.20	0.412	2.50~5.50	0.245~0.539	5
⑥	9IF120S4L-V	9IF120E4L-V	120	100	50 / 60	70~1400	2200	6.00	0.588	3.00~6.50	0.294~0.637	35
⑥	9IF120S4H-V	9IF120E4H-V	120	220	50 / 60	70~1400	1100	6.00	0.588	3.00~6.50	0.294~0.637	6

# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

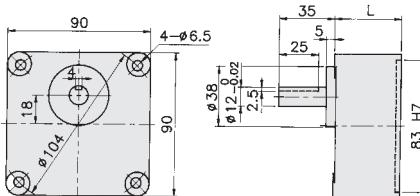
**4 9DP10Y**

WEIGHT 0.6kg

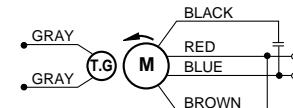
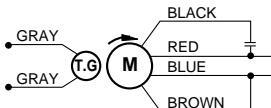
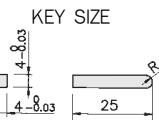


## GEAR HEAD (RATIO 1/3~1/180)

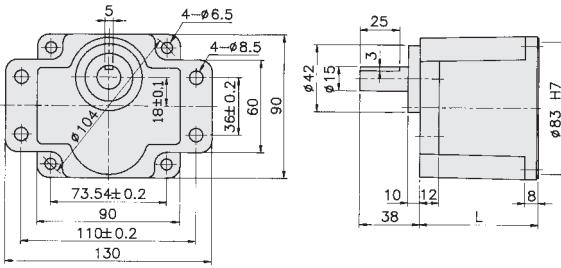
**3 9P□B  
9P□Y**



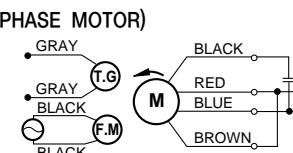
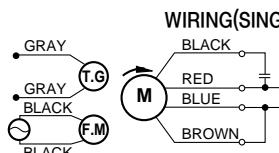
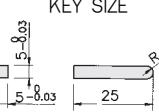
GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



**5 9E□B**



GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	80	2.0	M6×25



WIRING(SINGLE PHASE MOTOR)

\* Facing output shaft (60W~120W)

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SPEED RANGE	L.SPEED 70rpm	95	11.7	7.8	4.7	3.9	2.3	1.9	1.2	0.8	0.6	0.4
			H.SPEED 1400rpm	389	233	156	93	78	47	39	23	16	12	8
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>	Low speed	1.7	2.9	4.4	7.3	8.7	13	16	24	35	47	71	120
		High speed	8.2	14	20	34	41	61	73	110	120	120	120	120
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>	Low speed	1.7	2.9	4.4	7.3	8.7	13	16	24	35	47	71	120
		High speed	8.2	14	20	34	41	61	73	110	120	120	120	120
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>	Low speed	3.5	5.8	8.7	15	17	26	31	47	71	94	120	120
		High speed	11	18	27	45	54	81	97	120	120	120	120	120
<b>4 9DP10Y</b>	<b>3 9P□Y, 9P□B</b>	Low speed	3.5	5.8	8.7	15	17	26	31	47	120	120	120	120
		High speed	11	18	27	45	54	81	97	120	120	120	120	120
	<b>5 9E□B</b>	Low speed	7.3	12	18	27	33	49	59	98	133	177	266	300
		High speed	16	27	40	60	72	108	130	217	292	300	300	300
	<b>5 9E□B</b>	Low speed	7.3	12	18	27	33	49	59	98	133	177	266	300
		High speed	16	27	40	60	72	108	130	217	292	300	300	300
	<b>5 9E□B</b>	Low speed	8.7	15	22	33	39	59	71	118	159	213	300	300
		High speed	19	32	47	71	85	128	154	256	300	300	300	300
	<b>5 9E□B</b>	Low speed	8.7	15	22	33	39	59	71	118	159	213	300	300
		High speed	19	32	47	71	85	128	154	256	300	300	300	300

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# SPEED CONTROL REVERSIBLE MOTOR

## MOTOR

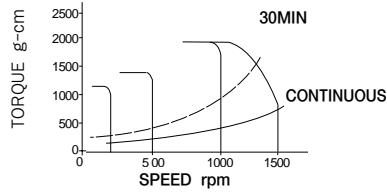
### N - T CURVE

### MOTOR DIMENSIONS

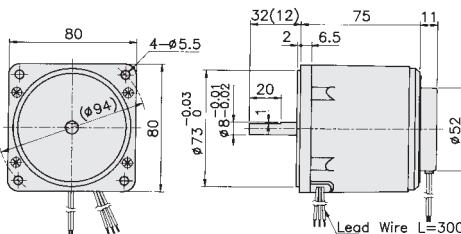
### PINION SHAFT

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#### ⑦ 8RN20S4□-V 8RN20GN4□-V

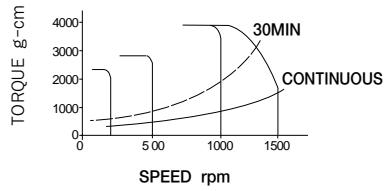


WEIGHT 1.6kg

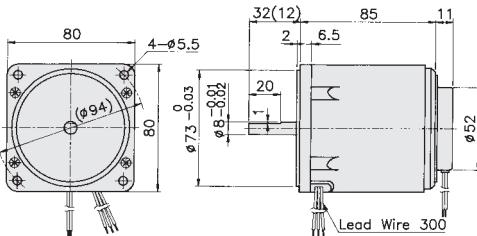


MODULE	0.5
PRESSURE ANGLE	20°
TEETH NO.	10
DIAMETER	φ 7.2mm
LENGTH	12mm

#### ⑧ 8RN25S4□-V 8RN25GN4□-V



WEIGHT 1.7kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH NO.	10
DIAMETER	φ 7.2mm
LENGTH	12mm



#### ◆ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4POLES, 30MIN, DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		MAXIMUM OUTPUT W	VOLTAGE V	FREQUENCY Hz	VARIABLE SPEED RANGE rpm	MAXIMUM CURRENT mA	STARTING TORQUE		ALLOWABLE TORQUE		CAPACITOR mF
	STRAIGHT SHAFT	PINION SHAFT						kg-cm	N-m	kg-cm	N-m	
⑦	8RN20S4L-V	8RN20GN4L-V	20	100	50 / 60	70~1400	550	1.04	0.102	0.30~1.6	0.039~0.176	8
⑦	8RN20S4H-V	8RN20GN4H-V	20	220	50 / 60	70~1400	270	1.04	0.102	0.30~1.6	0.039~0.176	1.5
⑧	8RN25S4L-V	8RN25GN4L-V	25	100	50 / 60	70~1400	800	1.28	0.125	0.35~1.9	0.059~0.255	10
⑧	8RN25S4H-V	8RN25GN4H-V	25	220	50 / 60	70~1400	410	1.28	0.125	0.35~1.9	0.059~0.255	2

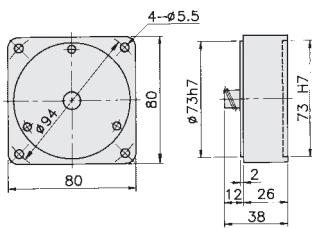
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

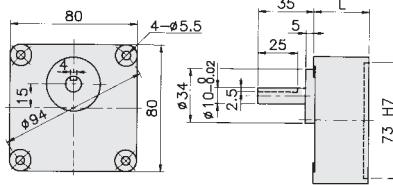
② 8DGN10Y

WEIGHT 0.3kg



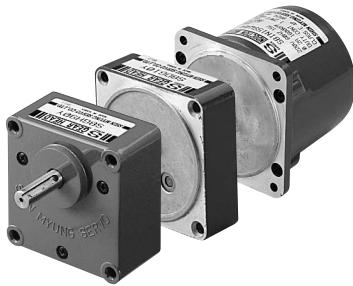
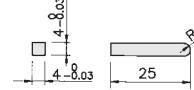
① 8GN□B

8GN□Y

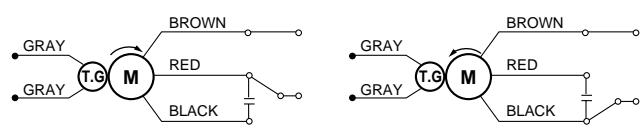


GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SPEED RANGE	L.SPEED 70rpm	95	11.7	7.8	4.7	3.9	2.3	1.9	1.2	0.8	0.6	0.4
			H.SPEED 1400rpm	389	233	156	93	78	47	39	23	16	12	8
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150
② 8DGN10Y	① 8GN□Y, 8GN□B	Low speed	1.2	1.9	2.9	4.9	5.8	8.7	10	16	24	31	47	
		High speed	5.2	8.7	13	22	26	39	47	71	100	100	100	100
② 8DGN10Y	① 8GN□Y, 8GN□B	Low speed	1.2	1.9	2.9	4.9	5.8	8.7	10	16	24	31	47	
		High speed	5.2	8.7	13	22	26	39	47	71	100	100	100	100
② 8DGN10Y	① 8GN□Y, 8GN□B	Low speed	1.7	2.9	4.4	7.3	8.7	13	16	24	35	47	71	
		High speed	7.6	13	19	32	38	57	68	100	100	100	100	100
② 8DGN10Y	① 8GN□Y, 8GN□B	Low speed	1.7	2.9	4.4	7.3	8.7	13	16	24	35	47	71	
		High speed	7.6	13	19	32	38	57	68	100	100	100	100	100

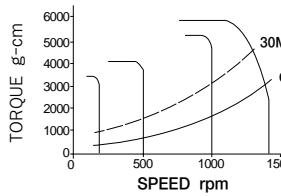
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# SPEED CONTROL REVERSIBLE MOTOR

## MOTOR

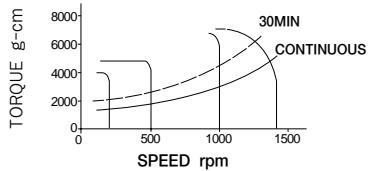
### N - T CURVE

⑨ 9RN40S4□-V  
9RN40P4□-V

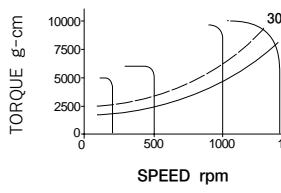


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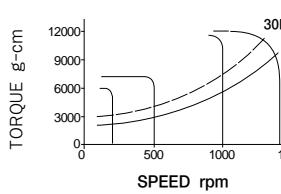
⑩ 9RN60S4□-V  
9RN60E4□-V



⑪ 9RF90S4□-V  
9RF90E4□-V

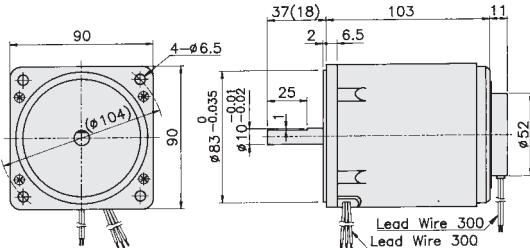


⑫ 9RF120S4□-V  
9RF120E4□-V

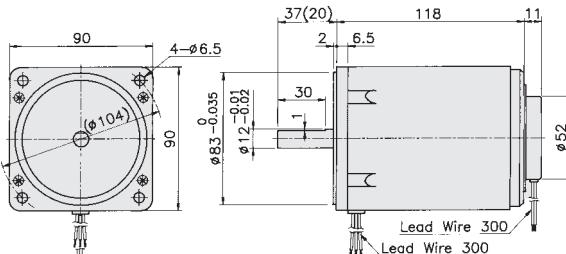


### MOTOR DIMENSIONS

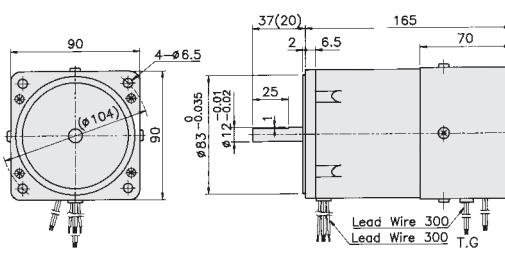
WEIGHT 2.6kg



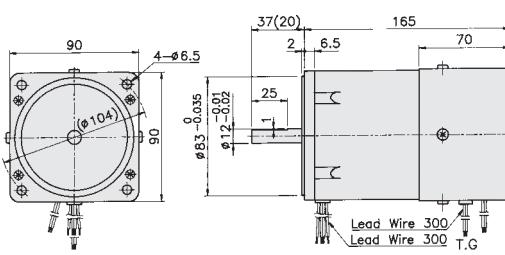
WEIGHT 2.7kg



WEIGHT 3.5kg



WEIGHT 3.5kg



### PINION SHAFT

MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETER ø 9.63mm  
LENGTH 18mm

MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETER ø 11.55mm  
LENGTH 20mm

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN. DUTY, INSULATION CLASS "E"

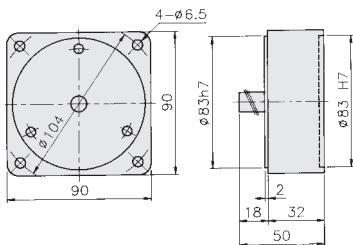
FIG NO.	MODEL		MAXIMUM OUTPUT W	VOLTAGE V	FREQUENCY Hz	VARIABLE SPEED RANGE rpm	MAXIMUM CURRENT mA	STARTING TORQUE		ALLOWABLE TORQUE		CAPACITOR MF
	Straight Shaft	Pinion Shaft						kg-cm	N-m	kg-cm	N-m	
⑨	9RN40S4L-V	9RN40P4L-V	40	100	50 / 60	70~1400	1300	2.60	0.255	0.65~3.00	0.064~0.294	16
⑨	9RN40S4H-V	9RN40P4H-V	40	220	50 / 60	70~1400	650	2.60	0.255	0.65~3.00	0.064~0.294	3.5
⑩	9RN60S4L-V	9RN60E4L-V	60	100	50 / 60	70~1400	1800	3.00	0.294	1.20~3.70	0.118~0.363	25
⑩	9RN60S4H-V	9RN60E4H-V	60	220	50 / 60	70~1400	900	3.00	0.294	1.20~3.70	0.118~0.363	5
⑪	9RF90S4L-V	9RF90E4L-V	90	100	50 / 60	70~1400	2200	4.20	0.412	2.50~5.50	0.245~0.539	25
⑪	9RF90S4H-V	9RF90E4H-V	90	220	50 / 60	70~1400	1100	4.20	0.412	2.50~5.50	0.245~0.539	5
⑫	9RF120S4L-V	9RF120E4L-V	120	100	50 / 60	70~1400	2200	6.00	0.588	3.00~6.50	0.294~0.637	35
⑫	9RF120S4H-V	9RF120E4H-V	120	220	50 / 60	70~1400	1100	6.00	0.588	3.00~6.50	0.294~0.637	7

# GEAR HEAD

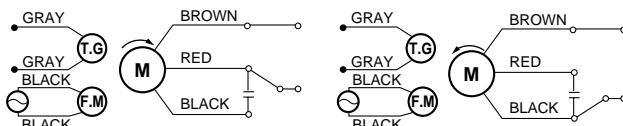
## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

**4 9DP10Y**



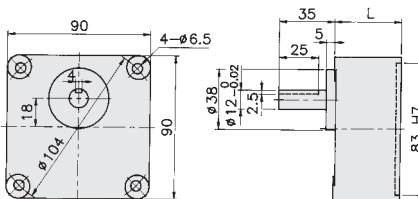
WIRING(SINGLE PHASE MOTOR)



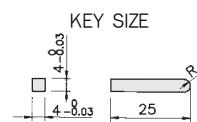
\* Facing output shaft (90W~120W)

**3 9P□B**

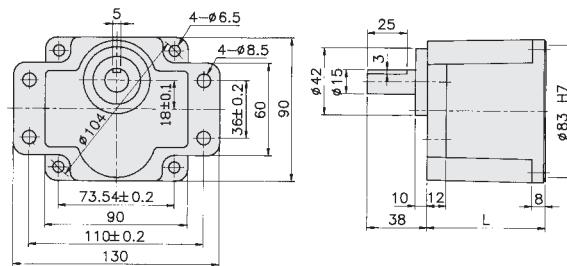
**9P□Y**



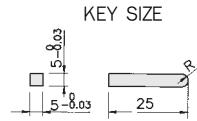
GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



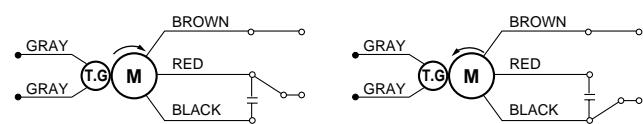
**5 9E□B**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	80	2.0	M6×25



WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft (S9RN type)

◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◊ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◊ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SPEED RANGE	L.SPEED 70rpm	95	11.7	7.8	4.7	3.9	2.3	1.9	1.2	0.8	0.6	0.4
			H.SPEED 1400rpm	389	233	156	93	78	47	39	23	16	12	8
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100
49DP10Y	39P□Y, 9P□YB	Low speed	1.9	3.2	4.7	7.9	9.5	14	17	26	38	51	77	
		High speed	8.7	15	22	36	44	66	79	118	120	120	120	120
49DP10Y	39P□Y, S9P□YB	Low speed	1.9	3.2	4.7	7.9	9.5	14	17	26	38	51	77	
		High speed	8.7	15	22	36	44	66	79	118	120	120	120	120
—	59E□B	Low speed	3.5	5.8	8.7	13	16	24	28	47	64	85	128	
		High speed	11	18	27	40	49	73	87	146	197	262	300	
—	59E□B	Low speed	3.5	5.8	8.7	13	16	24	28	47	64	85	128	
		High speed	11	18	27	40	49	73	87	146	197	262	300	
—	59E□B	Low speed	7.3	12	18	27	33	49	59	98	133	177	266	
		High speed	16	27	40	60	72	108	130	217	292	300	300	
—	59E□B	Low speed	7.3	12	18	27	33	49	59	98	133	177	266	
		High speed	16	27	40	60	72	108	130	217	292	300	300	
—	59E□B	Low speed	8.7	15	22	33	39	59	71	118	159	213	300	
		High speed	19	32	47	71	85	128	154	256	300	300	300	
—	59E□B	Low speed	8.7	15	22	33	39	59	71	118	159	213	300	
		High speed	19	32	47	71	85	128	154	256	300	300	300	

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# SPEED CONTROLLER

## FOR SPEED CONTROL MOTOR

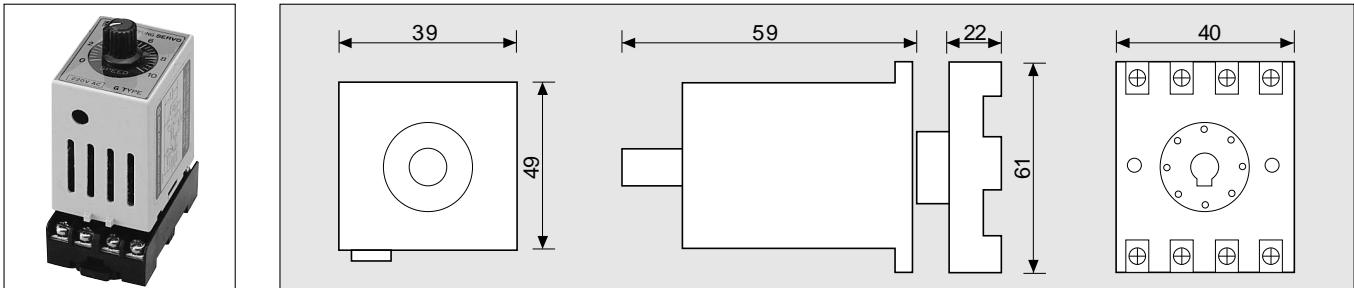
The speed control equipments are used for small AC motor on which tachogenerator is attached. It checks the rotation speed of motor with tachogenerator and compare with the fixed rotation speed. Therefore, it is the closed Loop control method for keeping the stable speed range from low to high.

## 1. SPECIFICATION

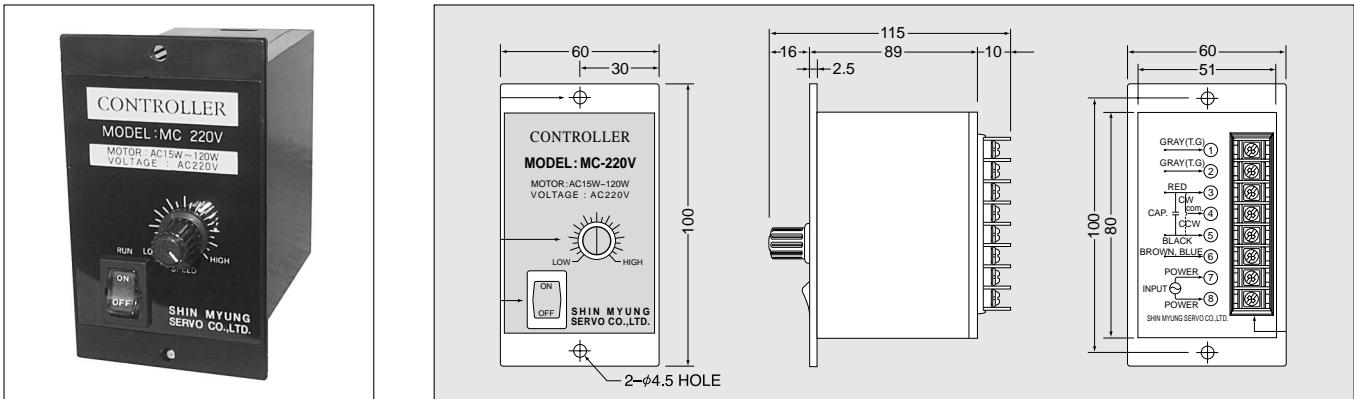
Item	SC-1190G	SC-2290G	MC100V	MC220V	MC100DN	MC220DN
Input Voltage	110VAC+10%	220VAC+10%	110VAC+10%	220VAC+10%	110VAC+10%	220VAC+10%
Speed Control Range	70~1400 rpm			90~1700rpm		
Applicable Motor Output	15W~90W(T. G. Attached)		15W~120W		15W~1800W	
Remote Control	Available		Not Available		Available	
Control Method	Analog		Analog		Digital	
Soft Run Function	×	×	×	×	○	○

## 2. DIMENSION

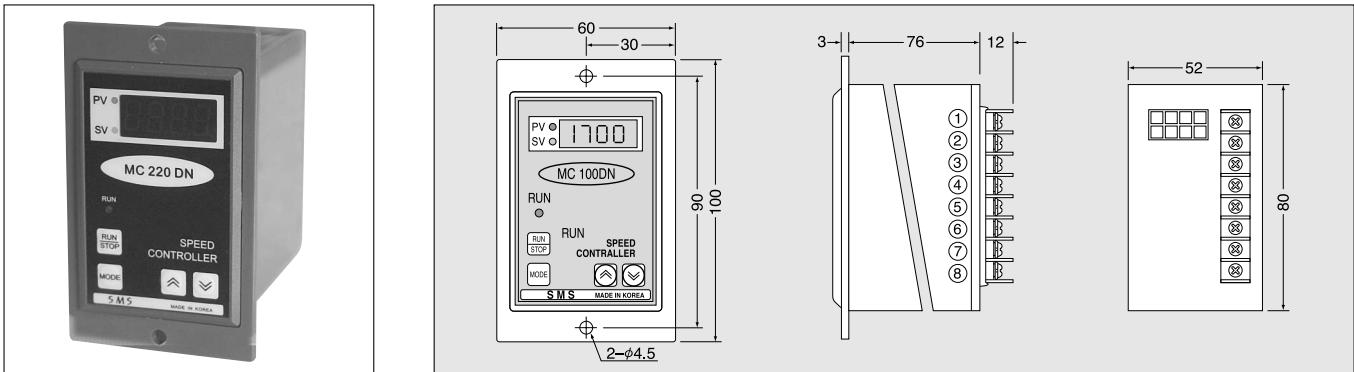
### 1) SC-1190G, SC-2290G



### 2) MC100V, MC220V



### 3) MC100DN, MC220DN

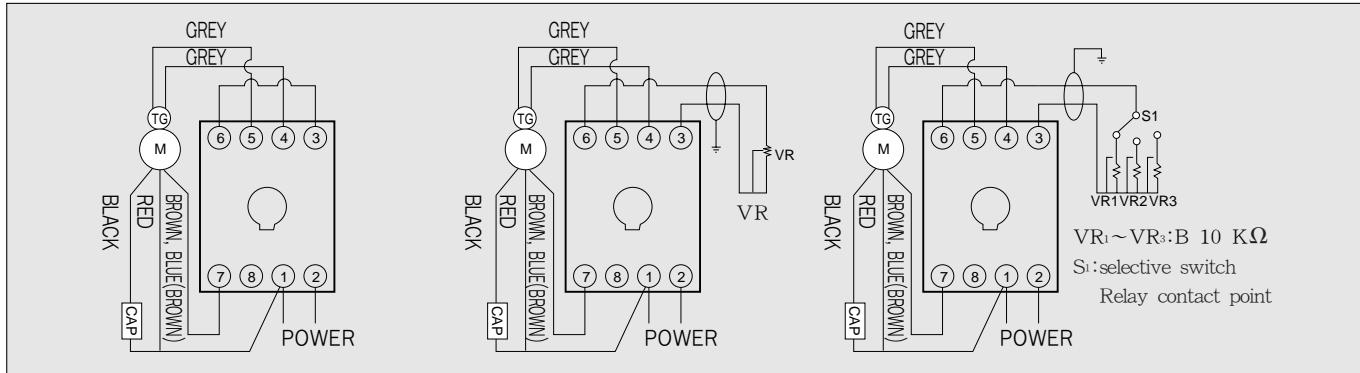


# SPEED CONTROLLER

## FOR SPEED CONTROL MOTOR

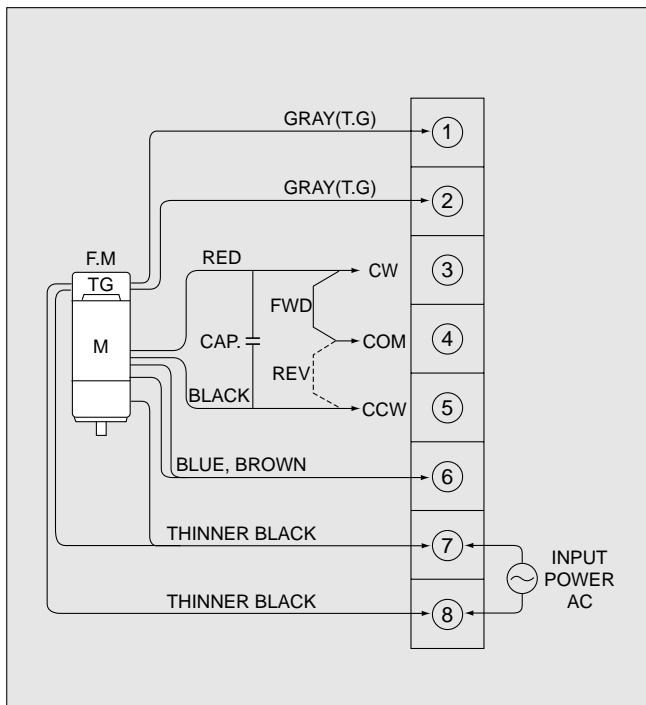
### 3. WIRING

#### 1) SC-1190G, SC-2290G

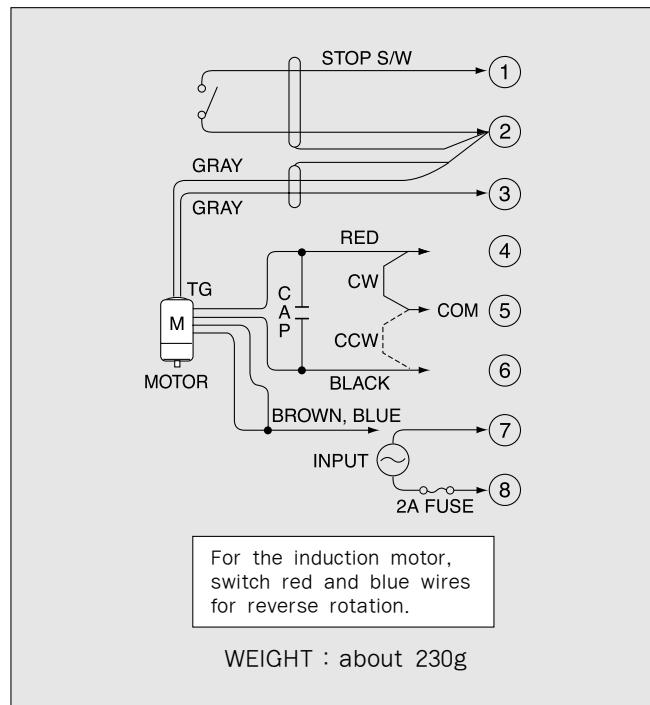


Ret. 1. The wiring makes the rotation in the same direction of watch from the side of the motor's output.  
 2. For the opposite direction of rotation, the wiring between Red and Blue or between Brown and Black should be changed each other in the induction motor. And the Red line and Black line must be changed for the wiring in the reversible motor.

#### 2) MC100V, MC220V



#### 3) MC100DN, MC220DN



# MAGNETIC BRAKE INDUCTION MOTOR

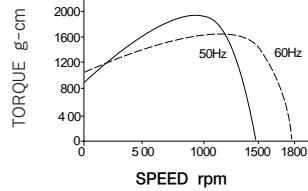
## MOTOR

### N - T CURVE

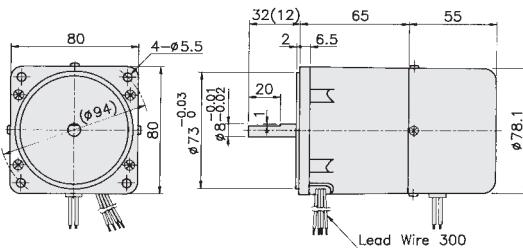
### MOTOR DIMENSIONS

### PINION SHAFT

**① 8IN15S4□-B  
8IN15GN4□-B**

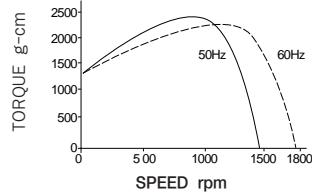


WEIGHT 1.7kg

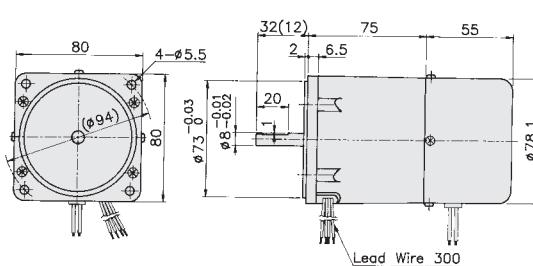


MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETTER	φ 7.2mm
LENGTH	12mm

**② 8IN25S4□-B  
8IN25GN4□-B**



WEIGHT 1.8kg



MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETTER	φ 7.2mm
LENGTH	12mm



❖ ELECTRICAL PERFORMANCES  
- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR $\mu\text{F}$	BRAKE TORQUE		BRAKE CURRENT mA	
						SPEED rpm	INPUT W	CURRENT mA	TORQUE		TORQUE kg-cm	TORQUE N-m		kg-cm	N-m		
	STRAIGHT SHAFT	PINION SHAFT				50	60	1250	45	400	1.10	0.108	0.68	0.067	800	3	0.10
①	8IN15S4L-B	8IN15GN4L-B	15	100	50	1250	45	400	1.10	0.108	0.68	0.067	800	3	0.10	0.010	100
①	8IN15S4H-B	8IN15GN4H-B	15	220	50	1250	45	200	1.10	0.108	0.68	0.067	400	1.2	0.10	0.010	100
②	8IN25S4L-B	8IN25GN4L-B	25	100	50	1250	60	600	1.75	0.172	1.00	0.098	1100	6	0.10	0.010	100
②	8IN25S4H-B	8IN25GN4H-B	25	220	50	1250	60	290	1.75	0.172	1.00	0.098	500	1.5	0.10	0.010	100
					60	1550	60	290	1.40	0.137	1.00	0.098	500				

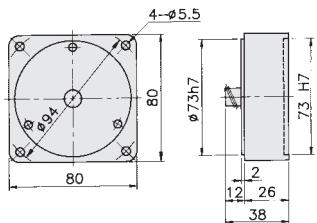
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

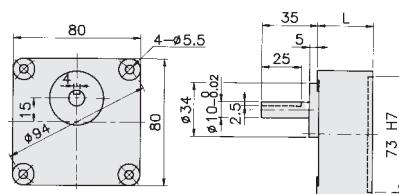
**2 8DGN10Y**

WEIGHT 0.3kg



**I 8GN□B**

**8GN□Y**

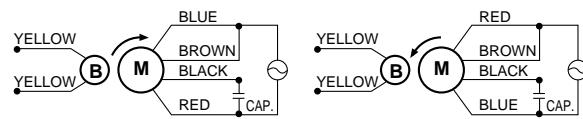


GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)	500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750
		60Hz	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800
28DGN10Y	I8GN□Y, 8GN□B		2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
28DGN10Y	I8GN□Y, 8GN□B		2.6	4.4	6.6	11	13	20	24	35	53	71	100	D35	D35	D65	D80	D100
28DGN10Y	I8GN□Y, 8GN□B		4.1	6.8	10	17	20	31	37	55	83	110	100	D35	D35	D65	D80	D100
28DGN10Y	I8GN□Y, 8GN□B		4.1	6.8	10	17	20	31	37	55	83	110	100	D35	D35	D65	D80	D100

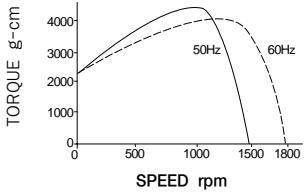
■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# MAGNETIC BRAKE INDUCTION MOTOR

## MOTOR

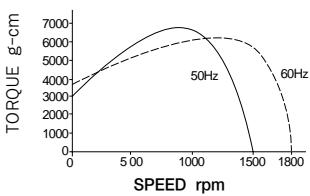
### N - T CURVE

③ 9IN40S4□-B  
9IN40P4□-B

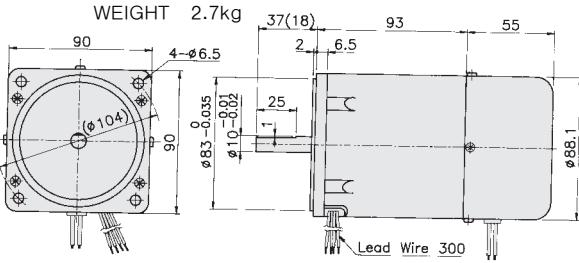


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④ 9IF60S4□-B  
9IF60P4□-B



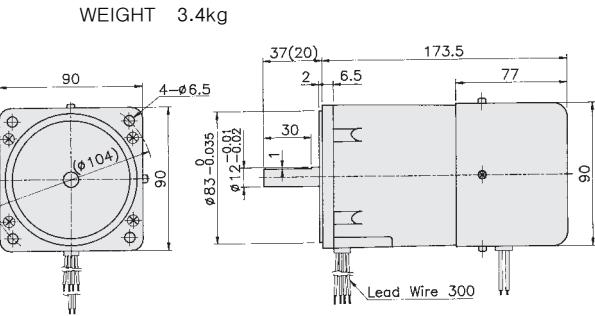
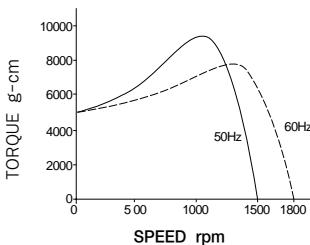
### MOTOR DIMENSIONS



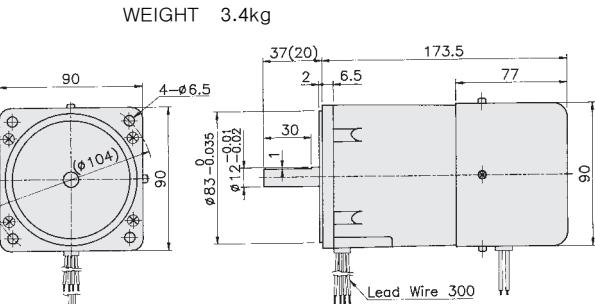
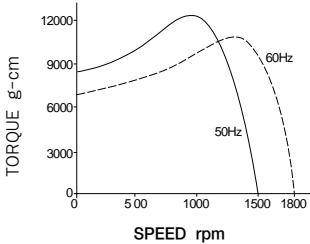
### PINION SHAFT

MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETTER ø 9.63mm  
LENGTH 18mm

⑤ 9IF90S4□-B  
9IF90E4□-B



⑥ 9IF120S4□-B  
9IF120E4□-B



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER ø 11.55mm  
LENGTH 20mm

MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER ø 11.55mm  
LENGTH 20mm

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING		STARTING CURRENT mA	CAPACITOR pF	BRAKE		BRAKE CURRENT mA					
						SPEED rpm	INPUT W	CURRENT mA	TORQUE		TORQUE			TORQUE							
	STRAIGHT SHAFT	PINION SHAFT							kg-cm	N-m	kg-cm	N-m		kg-cm	N-m						
③	9IN40S4L-B	9IN40P4L-B	40	100	50	1250	110	1100	3.00	0.294	1.80	0.176	1700	10	0.10	0.010	100				
③	9IN40S4H-B	9IN40P4H-B	40	220	50	1250	110	1100	3.00	0.294	1.80	0.176	1100	2	0.10	0.010	100				
④	9IF60S4L-B	9IF60P4L-B	60	100	50	1250	150	1300	4.50	0.441	3.00	0.294	2200	16	0.10	0.010	100				
④	9IF60S4H-B	9IF60P4H-B	60	220	50	1250	150	700	4.50	0.441	3.00	0.294	1300	3.5	0.10	0.010	100				
⑤	9IF90S4L-B	9IF90E4L-B	90	100	50	1250	200	2000	6.80	0.666	4.20	0.412	3200	25	0.10	0.010	100				
⑤	9IF90S4H-B	9IF90E4H-B	90	220	50	1250	200	1000	6.80	0.666	4.20	0.412	1600	5	0.10	0.010	100				
⑥	9IF120S4L-B	9IF120E4L-B	120	100	50	1300	240	2400	8.70	0.853	5.40	0.549	4800	35	0.10	0.010	100				
⑥	9IF120S4H-B	9IF120E4H-B	120	220	50	1300	350	1600	8.70	0.853	5.40	0.540	3200	6	0.10	0.010	100				

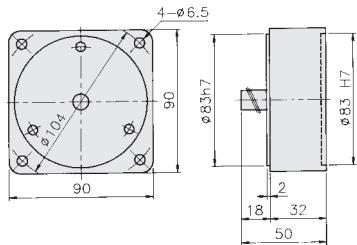
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

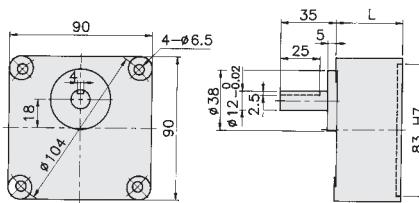
**4 9DP10Y**

WEIGHT 0.6kg

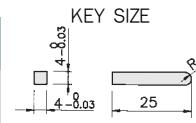


**3 9P□B**

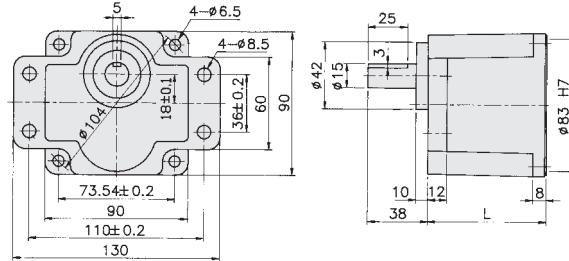
**9P□Y**



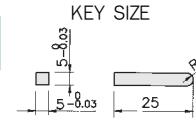
GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



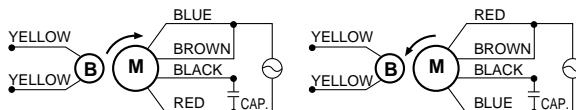
**5 9E□B**



GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◊ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◊ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	120	150	250	300	500	750
■9DP10Y	■9P□Y, 9P□B			7.3	12	18	30	36	55	66	98	120	120	120	D120	D120	D120	D120	D120
■9DP10Y	■9P□Y, 9P□B			7.3	12	18	30	36	55	66	98	120	120	120	D120	D120	D120	D120	D120
■9DP10Y	■9P□Y, 9P□B			11	18	28	46	55	83	100	120	120	120	120	D120	D120	D120	D120	D120
■9DP10Y	■9P□Y, 9P□B			11	18	28	46	55	83	100	120	120	120	120	D120	D120	D120	D120	D120
—	■9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—	■9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—	■9E□B			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-
—	■9E□B			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# MAGNETIC BRAKE INDUCTION MOTOR

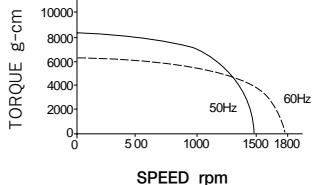
## MOTOR

### N - T CURVE

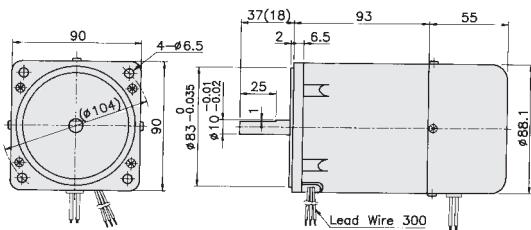
### MOTOR DIMENSIONS

### PINION SHAFT

#### ⑦ 9IN40S4J-B 9IN40P4J-B



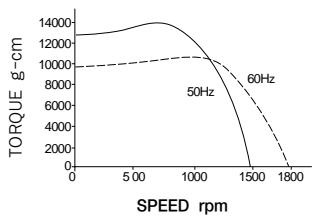
WEIGHT 2.7kg



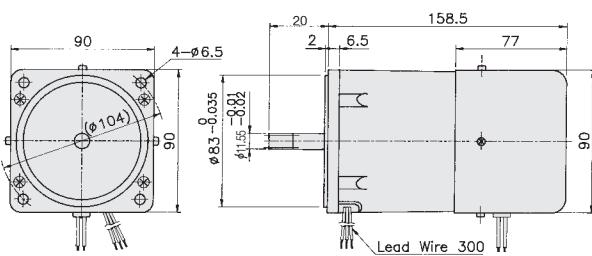
MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETTER  $\phi 9.63\text{mm}$   
LENGTH 18mm

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#### ⑧ 9IF60S4J-B 9IF90E4J-B

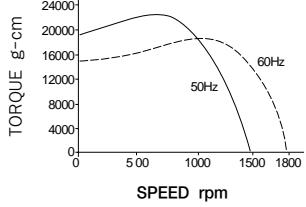


WEIGHT 2.8kg

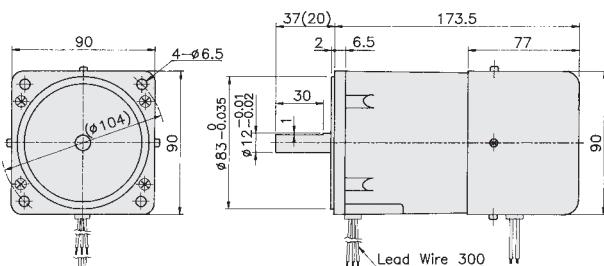


MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER  $\phi 11.55\text{mm}$   
LENGTH 20mm

#### ⑨ 9IF90S4J-B 9IF90E4J-B

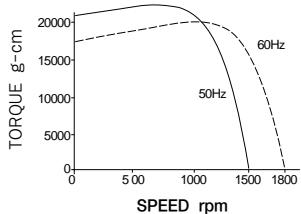


WEIGHT 3.4kg

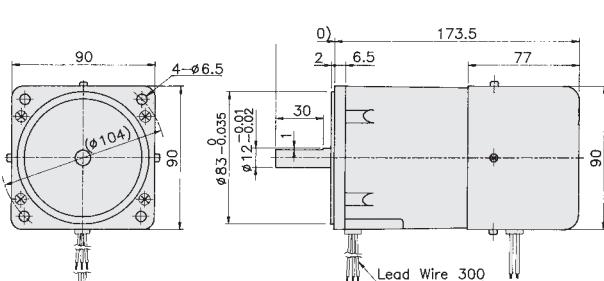


MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER  $\phi 11.55\text{mm}$   
LENGTH 20mm

#### ⑩ 9IF120S4J-B 9IF120E4J-B



WEIGHT 3.4kg



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER  $\phi 11.55\text{mm}$   
LENGTH 20mm

#### ELECTRICAL PERFORMANCES

- THREE PHASE, 4 POLES, CONTINUOUS DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		BRAKE TORQUE		BRAKE CURRENT mA
	Straight Shaft	Pinion Shaft				Speed rpm	Input W	Current mA	Torque kg-cm N-m		kg-cm	N-m	kg-cm	N-m
⑦	9IN40S4J-B	9IN40P4J-B	40	220	50 60	1300 1550	90 90	400 400	3.00 2.60	0.294 0.255	6.50 5.00	0.637 0.490	0.10 0.010	100
⑧	9IF60S4J-B	9IF60E4J-B	60	220	50 60	1300 1550	135 135	600 600	4.50 3.80	0.441 0.372	7.50 6.00	0.735 0.588	0.10 0.010	100
⑨	9IF90S4J-B	9IF90E4J-B	90	220	50 60	1250 1500	180 180	800 800	6.80 5.70	0.666 0.559	8.50 7.00	0.833 0.686	0.10 0.010	100
⑩	9IF120S4J-B	9IF120E4J-B	120	220	50 60	1300 1550	240 240	1000 1000	9.00 7.60	0.882 0.745	16.00 14.00	1.568 1.372	0.10 0.010	100

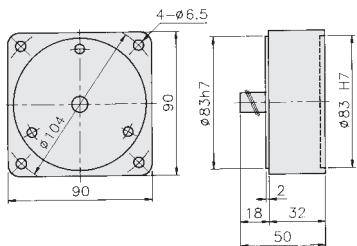
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

## GEAR HEAD (RATIO 1/3~1/180)

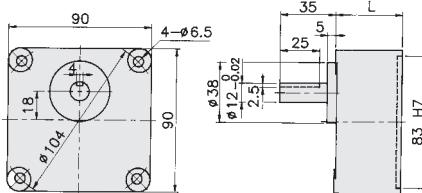
### 4 9DP10Y

WEIGHT 0.6kg



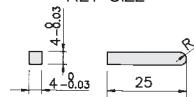
### 3 9P□B

### 9P□Y

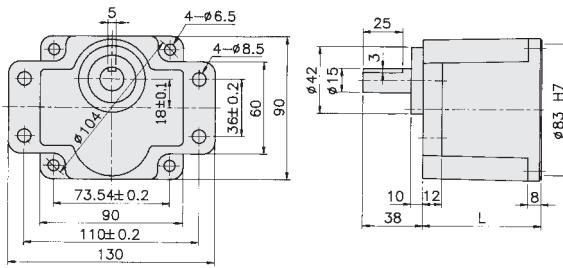


GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80

KEY SIZE

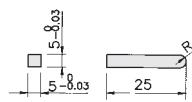


### 5 9E□B

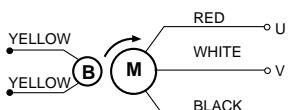


GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25

KEY SIZE



### WIRING(THREE PHASE MOTOR)



\*Facing output shaft

For CCW rotation, Switch any 2 wires of U.V.W shown above.

◊ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◊ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◊ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	120	150	250	300	500	750
	■9DP10Y	■9P□Y, 9P□B			7.6	13	19	32	38	57	68	102	120	120	120	D120	D120	D120	D120	D120
	—	■9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
	—	■9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
	—	■9E□B			22	37	55	83	100	150	180	299	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# MAGNETIC BRAKE REVERSIBLE MOTOR

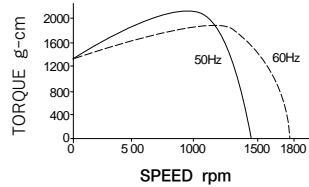
## MOTOR

### N - T CURVE

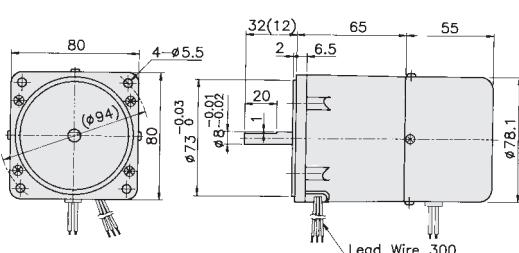
### MOTOR DIMENSIONS

### PINION SHAFT

⑪ 8RN20S4□-B  
8RN20GN4□-B



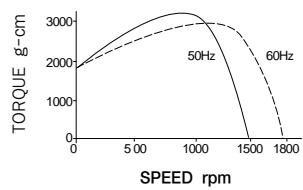
WEIGHT 1.7kg



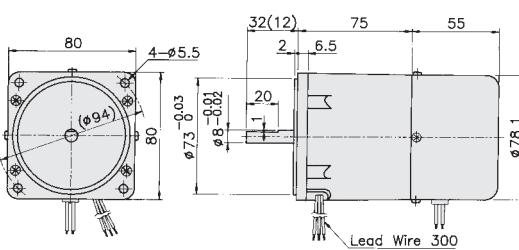
MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETTER	ø 7.2mm
LENGTH	12mm

60

⑫ 8RN25S4□-B  
8RN25GN4□-B

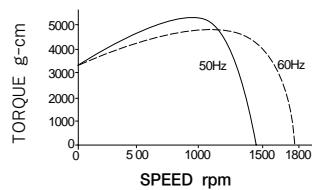


WEIGHT 1.8kg

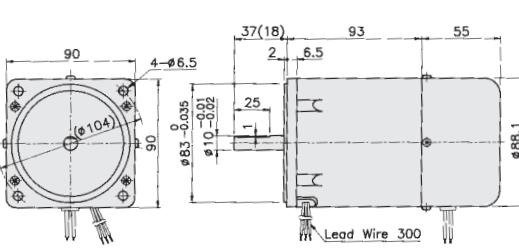


MODULE	0.5
PRESSURE ANGLE	20°
TEETH No.	10
DIAMETTER	ø 7.2mm
LENGTH	12mm

⑬ 9RN40S4□-B  
9RN40P4□-B



WEIGHT 2.7kg



MODULE	0.6
PRESSURE ANGLE	20°
TEETH No.	12
DIAMETTER	ø 9.63mm
LENGTH	18mm

#### ❖ ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN, DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING TORQUE		STARTING CURRENT mA	CAPACITOR pF	BRAKE TORQUE		BRAKE CURRENT mA	
	Straight Shaft	Pinion Shaft				SPEED rpm	INPUT W	CURRENT mA	TORQUE		kg-cm	N-m		kg-cm	N-m		
⑪	8RN20S4L-B	8RN20GN4L-B	20	100	50	1250	50	500	1.50	0.147	1.04	0.102	900	8	0.10	0.010	100
⑪	8RN20S4H-B	8RN20GN4H-B	20	220	50	1250	60	280	1.50	0.147	1.04	0.102	430	1.5	0.10	0.010	100
⑫	8RN25S4L-B	8RN25GN4L-B	25	100	50	1300	65	650	1.80	0.176	1.28	0.125	1250	10	0.10	0.010	100
⑫	8RN25S4H-B	8RN25GN4H-B	25	220	50	1300	70	330	1.80	0.176	1.28	0.125	550	2	0.10	0.010	100
⑬	9RN40S4L-B	9RN40P4L-B	40	100	50	1200	115	1150	3.20	0.314	2.60	0.255	1850	16	0.10	0.010	100
⑬	9RN40S4H-B	9RN40P4H-B	40	220	50	1200	140	650	3.20	0.314	2.60	0.255	900	3.5	0.10	0.010	100
						1550	50	500	1.17	0.115	1.04	1.102	850				
						1550	60	280	1.17	0.115	1.04	1.102	430				
						1600	65	650	1.37	0.134	1.28	0.125	1200				
						1600	70	330	1.37	0.134	1.28	0.125	550				
						1500	115	1150	2.60	0.255	2.60	0.255	1850				
						1500	115	1150	2.60	0.255	2.60	0.255	900				

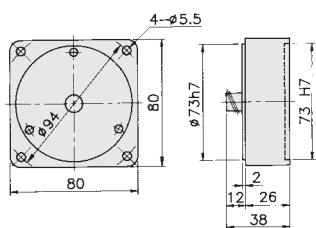
# GEAR HEAD

## DECIMAL GEAR HEAD (RATIO 1/10)

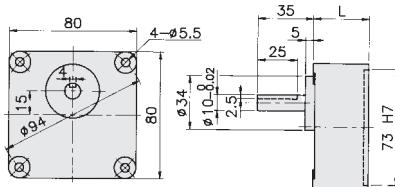
## GEAR HEAD (RATIO 1/3~1/180)

**2 8DGN10Y**

WEIGHT 0.3kg

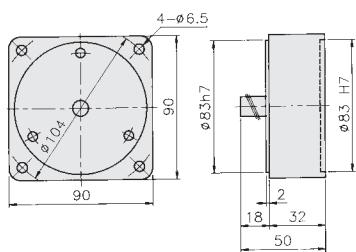


**1 8GN□B  
8GN□Y**

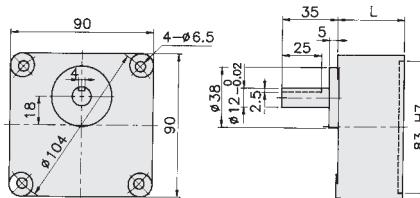


**4 9DP10Y**

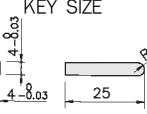
WEIGHT 0.6kg



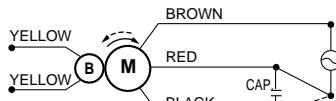
**3 9P□B  
9P□Y**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80



### WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

61

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

	DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
			DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
	8DGN10Y	8GN□Y, 8GN□B	3.6	6	9	15	18	30	36	60	90	120	180	300	360	600	900	1800		
	8DGN10Y	8GN□Y, 8GN□B	3.4	5.7	8.5	14	17	26	31	46	69	92	100	D35	D35	D65	D80	D100		
	8DGN10Y	8GN□Y, 8GN□B	3.4	5.7	8.5	14	17	26	31	46	69	92	100	D35	D35	D65	D80	D100		
	8DGN10Y	8GN□Y, 8GN□B	4.0	6.7	10	17	20	30	36	54	81	100	100	D35	D35	D65	D80	D100		
	8DGN10Y	8GN□Y, 8GN□B	4.0	6.7	10	17	20	30	36	54	81	100	100	D35	D35	D65	D80	D100		
	9DP10Y	9P□Y, 9P□B	7.6	13	19	32	38	57	68	102	120	120	120	D120	D120	D120	D120	D120		
	9DP10Y	9P□Y, 9P□B	7.6	13	19	32	38	57	68	102	120	120	120	D120	D120	D120	D120	D120		

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# MAGNETIC BRAKE REVERSIBLE MOTOR

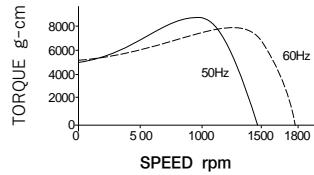
## MOTOR

### N - T CURVE

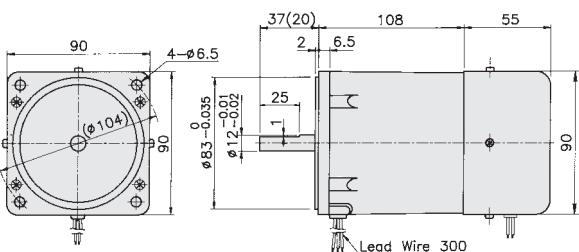
### MOTOR DIMENSIONS

### PINION SHAFT

⑭ 9RN60S4□-B  
9RN60E4□-B



WEIGHT 2.8kg

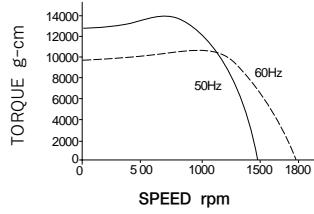


MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETTER  
LENGTH

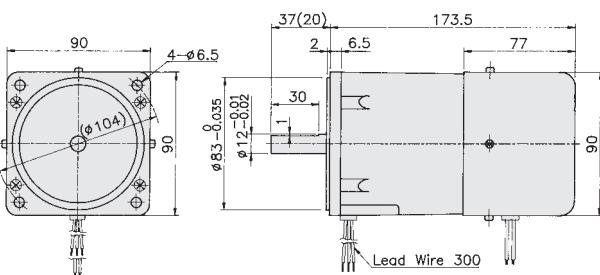
0.8	20°
11	φ11.55mm
20mm	

62

⑮ 9RF90S4□-B  
9RF90E4□-B



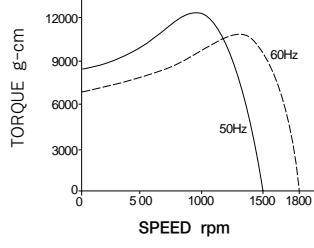
WEIGHT 3.4kg



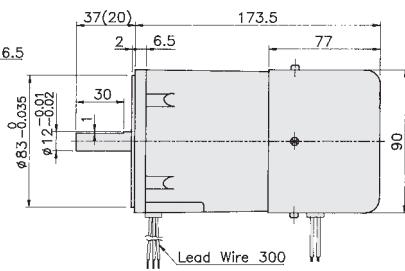
MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETTER  
LENGTH

0.8	20°
1	φ11.55mm
20mm	

⑯ 9RF120S4□-B  
9RF120E4□-B



WEIGHT 3.4kg



MODULE  
PRESSURE ANGLE  
TEETH NO.  
DIAMETTER  
LENGTH

0.8	20°
11	φ11.55mm
20mm	

### ELECTRICAL PERFORMANCES

- SINGLE PHASE, 4 POLES, 30MIN. DUTY, INSULATION CLASS "E"

FIG NO.	MODEL		OUTPUT W	VOLTAGE V	FREQUENCY Hz	RATED				STARTING		STARTING CURRENT mA	CAPACITOR μF	BRAKE		BRAKE CURRENT mA		
						SPEED rpm	INPUT W	CURRENT mA	TORQUE		TORQUE	kg-cm	N-m	kg-cm	N-m	kg-cm	N-m	
	Straight Shaft	Pinion Shaft				rpm	W	mA	kg-cm	N-m	kg-cm	N-m	mA	kg-cm	N-m	kg-cm	N-m	
⑭	9RN60S4L-B	9RN60E4L-B	60	100	50	1300	180	1800	4.50	0.441	3.50	0.343	3000	25	0.10	0.010	100	
⑭	9RN60S4H-B	9RN60E4H-B	60	220	50	1300	220	1000	4.50	0.441	3.50	0.343	1700	5	0.10	0.010	100	
⑮	9RF90S4L-B	9RF90E4L-B	90	100	50	1250	200	2000	6.80	0.666	4.20	0.412	3200	25	0.10	0.010	100	
⑮	9RF90S4H-B	9RF90E4H-B	90	220	50	1250	200	1000	6.80	0.666	4.20	0.412	1600	5	0.10	0.010	100	
⑯	9RF120S4L-B	9RF120E4L-B	120	100	50	1300	240	2400	8.70	0.853	6.00	0.588	4800	35	0.10	0.010	100	
⑯	9RF120S4H-B	9RF120E4H-B	120	220	50	1300	320	1400	8.70	0.853	6.00	0.588	3200	7	0.10	0.010	100	

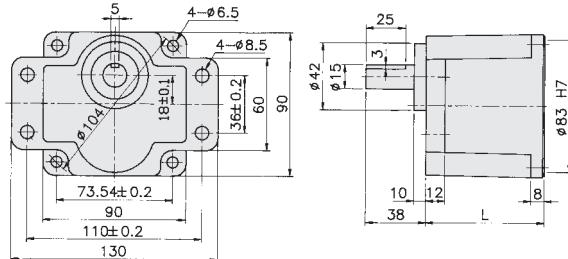
# GEAR HEAD

DECIMAL GEAR HEAD (RATIO 1/10)

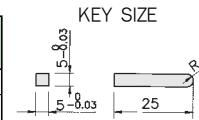
GEAR HEAD (RATIO 1/3~1/180)



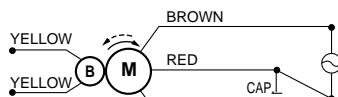
5 9E□B



GEAR RATIO	mm L	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/18	85	2.0	M6×25



WIRING(SINGLE PHASE MOTOR)



\* Facing output shaft

◆ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

DECIMAL GEAR HEAD	GEAR HEAD MODEL	SYNCHRONOUS SPEED (RPM)		500	300	200	120	100	60	50	30	20	15	10	6	5	3	2	1
		DENOMINATOR OF REDUCTION RATIO	50Hz	3	5	7.5	12.5	15	25	30	50	75	100	150	250	300	500	750	1500
—	■9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
—	■9E□B			11	18	28	42	50	75	90	150	202	269	300	-	-	-	-	-
—	■9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—	■9E□B			17	28	42	62	75	112	135	224	300	300	300	-	-	-	-	-
—	■9E□B			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-
—	■9E□B			21	35	53	80	96	144	172	287	300	300	300	-	-	-	-	-

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

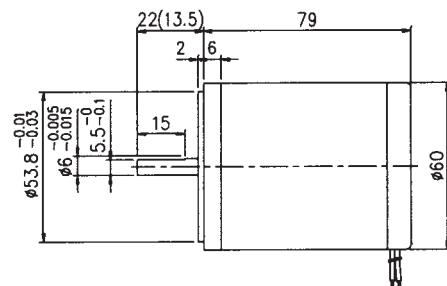
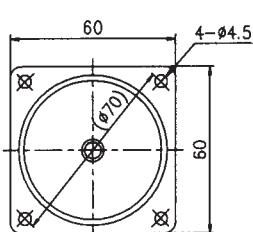
# DC MOTOR

## DIMENTIONS

□60mm

## PINION SHAFT

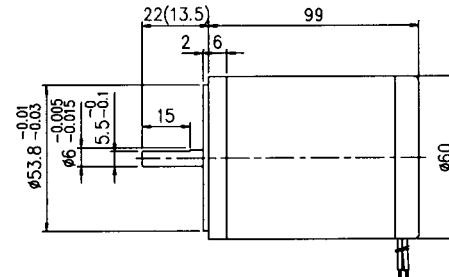
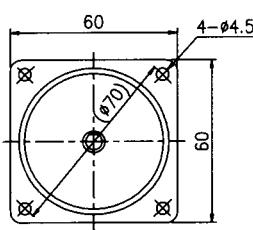
**[1] 10W**



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 8  
DIAMETTER φ 5.98mm  
LENGTH 13.5mm

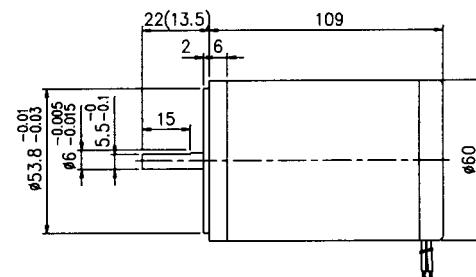
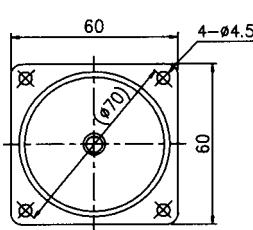
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**[2] 20W**



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 8  
DIAMETTER φ 5.98mm  
LENGTH 13.5mm

**[3] 30W**



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 8  
DIAMETTER φ 5.98mm  
LENGTH 13.5mm

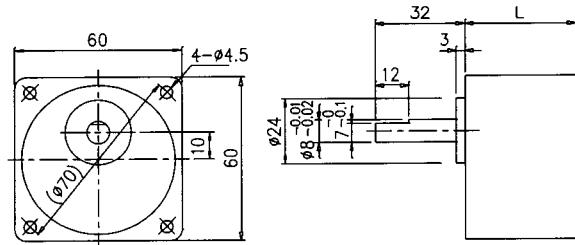
FIG. NO.	MODEL		OUTPUT W	SPEED rpm	VOLTAGE V	TORQUE kg-cm(N-m)	RATED CURRENT A	
	STRAIGHT SHAFT	PINION SHAFT						
①	6DN10S2□	6DN10G2□	10	3000	24	0.32	0.60	
					90		0.20	
					180		0.12	
②	6DN20S2□	6DN20G2□	20	3000	24	0.65	1.20	
					90		0.30	
					180		0.15	
③	6DN30S2□	6DN30G2□	30	3000	24	0.97	1.80	
					90		0.50	
					180		0.22	

# GEAR HEAD

## DIMENSIONS

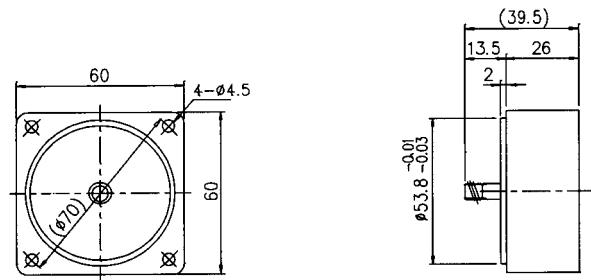


**GEARHEAD  
6G□Y(B)**



GEAR RATIO	L mm	WEIGHT(kg)	BOLT
1/3~1/18	30	0.25	M4×50
1/25~1/180	40	0.35	M4×60

**DECIMAL GEARHEAD  
6DG10Y(B)**



- ❖ □ OF GEAR HEAD MODEL NAME INDICATE THE DEDUCTION RATIO.
- ❖ THE NORMAL TORQUE(kg·cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.
- THE NORMAL TORQUE(kg·cm) IS 30kg·cm IN CASE THE DECIMAL GEARHEAD OF THE DEDUCTION RATIO 1/10 IS CONNECTED.
- ❖ THE ROTATION DIRECTION OF OUTPUT SHAFT FOR THE GEARHEAD INDICATED ■ ROTATES WITH MOTOR ON THE CONTRARY.
- ❖ THE ACTUAL ROTATION SPEED IS 2-20% LESS THAN SYNCHRONOUS SPEED ACCORDING TO THE SIZE OF THE LOAD.

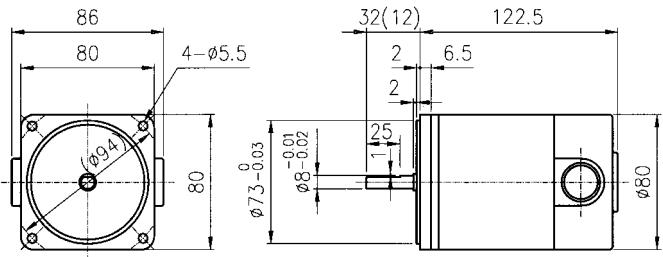
	MODEL	rpm	1000	833	600	500	400	333	240	200	166	150	120	100	83	60	50	40	33	30	25	20	16
		RATIO	3	3.6	5	6	7.5	9	12.5	15	18	20	25	30	36	50	60	75	90	100	120	150	180
6G□Y	kg·cm	0.8	1.0	1.4	1.7	2.2	2.6	3.6	4.3	5.2	5.4	6.8	8.2	9.8	13.6	15.3	19	23	25	30	30	30	30
	kg·cm	1.7	2.1	2.9	3.5	4.4	5.2	7.3	8.7	10.5	11.0	13.8	16.5	19.8	27	30	30	30	30	30	30	30	30
	kg·cm	2.4	2.9	4.0	4.8	6.0	7.2	10.1	12.1	14.5	15.3	19.0	22	27	30	30	30	30	30	30	30	30	30

# DC MOTOR

## MOTOR

## PINION SHAFT

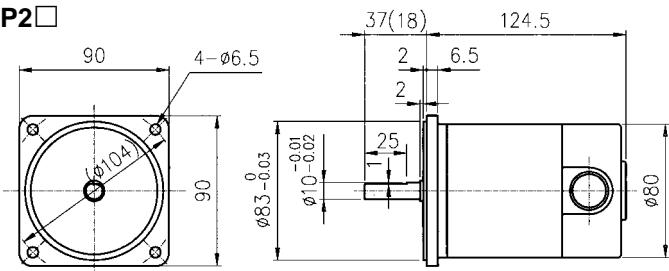
① 8DN25S2□  
8DN25GN2□



MODULE 0.5  
PRESSURE ANGLE 20°  
TEETH No. 10  
DIAMETTER ø7.2mm  
LENGTH 12mm

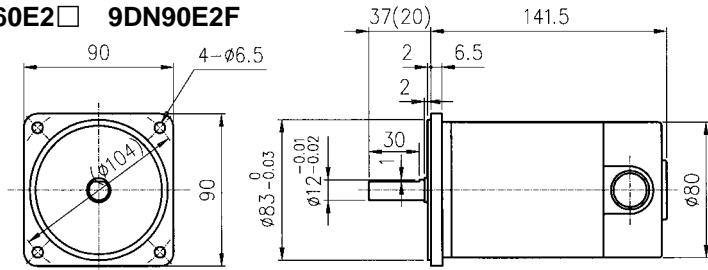
66

② 9DN40S2□  
9DN40P2□



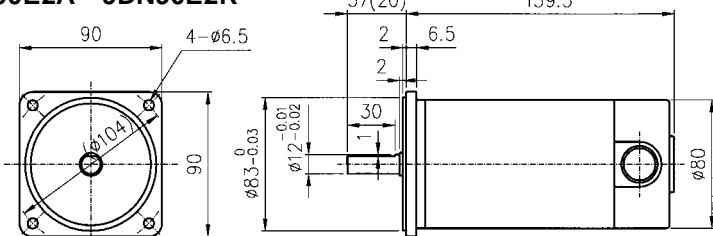
MODULE 0.6  
PRESSURE ANGLE 20°  
TEETH No. 12  
DIAMETTER ø9.63mm  
LENGTH 18mm

③ 9DN60S2□ 9DN90S2F  
9DN60E2□ 9DN90E2F



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER ø11.55mm  
LENGTH 20mm

④ 9DN90S2A 9DN90S2R  
9DN90E2A 9DN90E2R



MODULE 0.8  
PRESSURE ANGLE 20°  
TEETH No. 11  
DIAMETTER ø11.55mm  
LENGTH 20mm

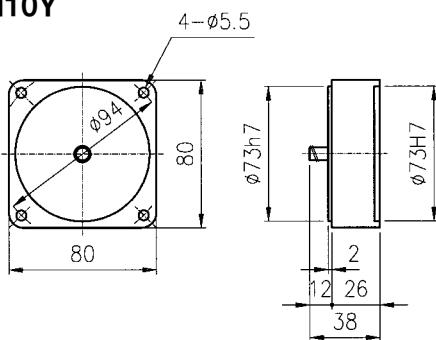
FIG. NO.	MODEL		OUTPUT W	SPEED rpm	VOLTAGE V	TORQUE kg-cm(N-m)	RATED CURRENT A	PEAK CURRENT A	DECIMAL GEAR HEAD	GEAR HEAD	
	STRAIGHT SHAFT	PINION SHAFT									
①	8DN25S2R	8DN25GN2R	25	3000	24	0.78 (0.078)	1.3	10.0	28DGN10Y	18GN□Y, 8GN□B	
	8DN25S2A	8DN25GN2A			90		0.4	3.0			
	8DN25S2F	8DN25GN2F			180		0.25	1.5			
②	9DN40S2R	9DN40P2R	40	3000	24	1.300 (0.127)	2.0	17	49DP10Y	9P□Y, 9P□B	
	9DN40S2A	9DN40P2A			90		0.8	4.5			
	9DN40S2F	9DN40P2F			180		0.4	1.35			
③	9DN60S2R	9DN60E2R	60	3000	24	1.95 (0.191)	3.2	25.0	N/A	59E□B	
	9DN60S2A	9DN60E2A			90		0.95	6.5			
	9DN60S2F	9DN60E2F			180		0.50	3.25			
④	9DN90S2R	9DN90E2R	90	3000	24	2.92 (0.286)	5.0	37.5	N/A	59E□B	
	9DN90S2A	9DN90E2A			90		1.3	10.0			
	9DN90S2F	9DN90E2F			180		0.7	5.0			

# GEAR HEAD

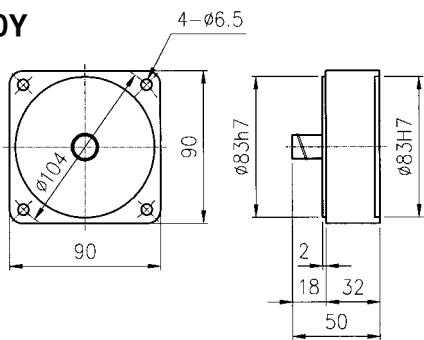
## DECIMAL GEAR HEAD

## GEAR HEAD

**2 8DGN10Y**

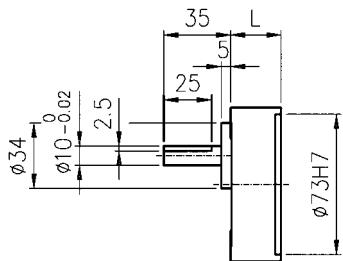
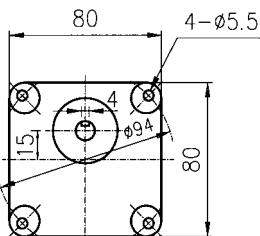


**4 9DP10Y**



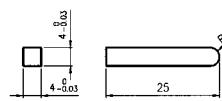
**1 8GN□B**

**8GN□Y**



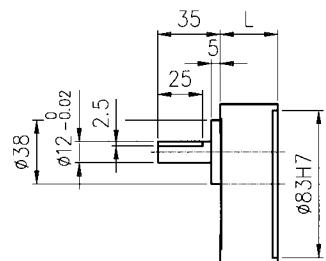
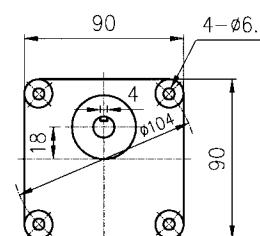
GEAR RATIO	L (mm)	WEIGHT(kg)	BOLT
1/3~1/18	30	0.5	M5×50
1/25~1/180	40	0.6	M5×60

KEY SIZE



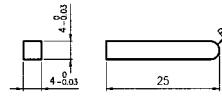
**3 9P□B**

**9P□Y**



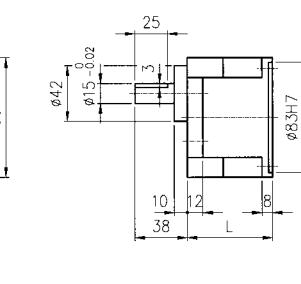
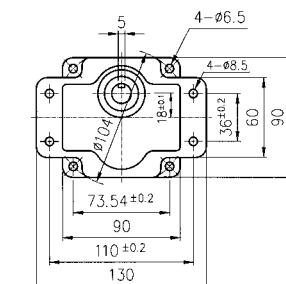
GEAR RATIO	L (mm)	WEIGHT(kg)	BOLT
1/3~1/18	42	0.8	M6×65
1/25~1/180	60	0.9	M6×80

KEY SIZE



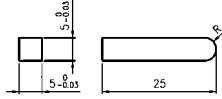
**5 9E□B**

**9E□Y**



GEAR RATIO	L (mm)	WEIGHT(kg)	BOLT
1/3~1/60	65	1.6	M6×25
1/75~1/180	85	2.0	M6×25

KEY SIZE



◆ THE NORMAL TORQUE(kg.cm) IS THAT THE MOTOR & GEAR HEAD ARE DIRECTLY COUPLED.

◆ INSERT THE DENOMINATOR OF REDUCTION RATIO IN □ OF GEAR HEAD MODEL NAME.

◆ ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

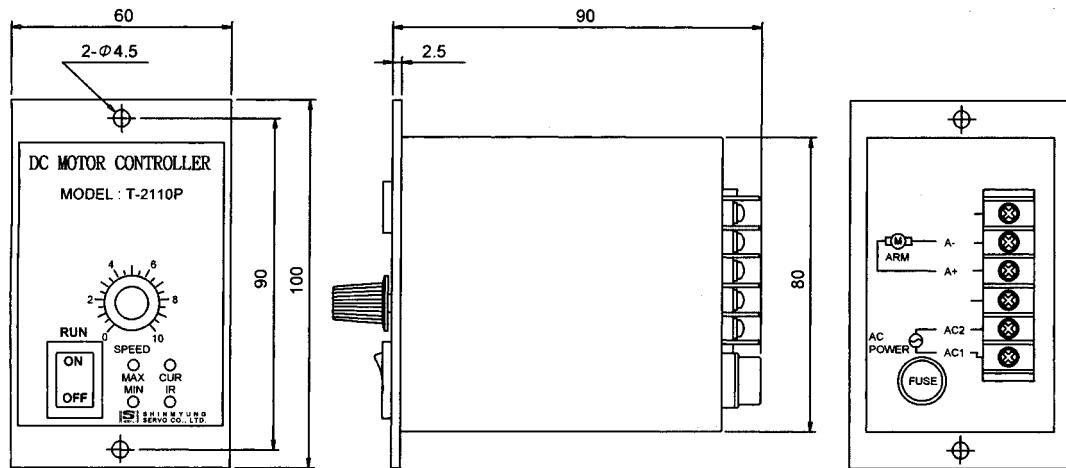
SPEED	1000	833	600	500	400	333	240	200	166	120	100	83	60	50	40	33	30	25	20	16	12	10	8.3	6	5	4	3.3	2	1.6
RATIO	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180	250	300	360	500	600	750	900	1500	1800
	2.0	2.4	3.3	4.0	5.0	6.0	8.3	10	12	15	18	22	27	32	40	48	54	65	81	97	D 100								
	3.2	3.8	5.2	6.3	7.9	9.5	13	16	19	24	28	34	43	51	64	77	85	102	120	120	D 100								
	4.7	5.7	7.9	9.5	12	14	20	21	26	32	38	46	64	77	86	104	115	138	173	207									
	7.1	8.5	12	14	18	21	30	32	38	48	57	69	96	115	129	155	172	207	259	300									

■ COLOR INDICATES THAT THE ROTATION OF GEARHEAD SHAFT IS IN OPPOSITE DIRECTION AS OUTPUT SHAFT OF MOTOR  
D:USE DECIMAL GEAR

# DC MOTOR CONTROLLER

68

\* Model : T-2110P  
-Applying for DC Motor 25~90W



## WIRING

AC : to be connected AC 110V or 220V power  
(Input 110VAC-Output 90VDC,  
Input 220VAC-Output 180VDC)

A+ : to be Connected to Plus(+) armature  
wire(red wire) on the motor.

A- : to be Connected Minus(-) Armature wire on the motor



## INSTALLATION

- Ambient temperature and humidity : -10°C~40°C, below 75% (protect from the direct rays of the sun)
- Keep away from a place of vibration, a shock, dusty, inflammable, and corrosive.
- Work carefully for the wiring. The wires between Controller and DC Motor are to be closed to each other.
- Use(install) a Noise Filter when the Motor accures a noise.

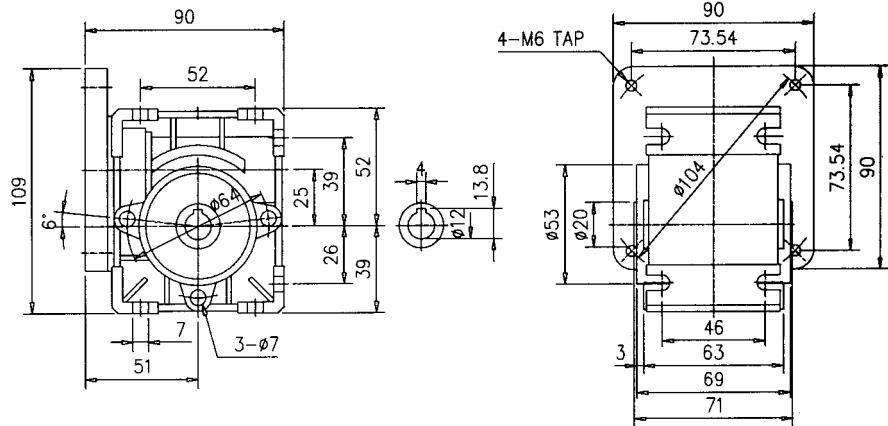
## Memo

# WORM GEARHEAD DEMENSIONS

## ■ Hollow type output shaft

**9W□B-H**

GEAR RATIO	WEIGHT(kg)	BOLT
1/10~1/60	1.2	M6×20

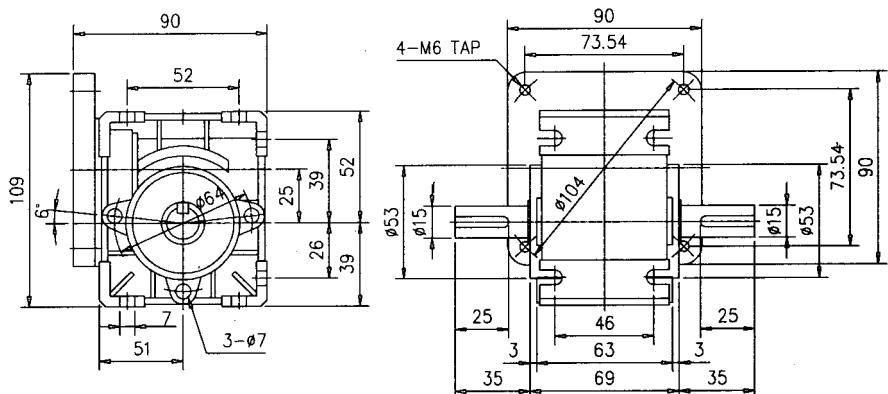


## ■ Dual oriented output shaft

**9W□B-D**

GEAR RATIO	WEIGHT(kg)	BOLT
1/10~1/60	1.2	M6×20

**Key size : 5x5x25**

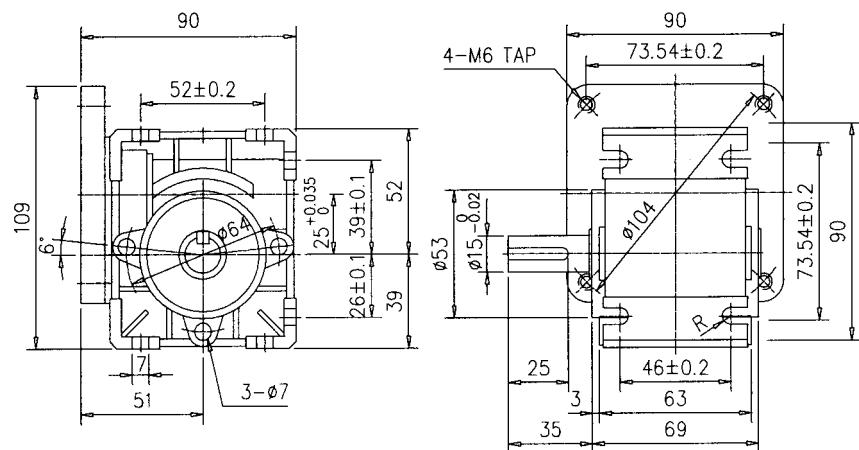


## ■ Right or Left oriented output shaft

**9W□B-R,L**

GEAR RATIO	WEIGHT(kg)	BOLT
1/10~1/60	1.2	M6×20

**Key size : 5x5x25**



# NEW PRODUCT \*WORM GEARHEAD TYPE\*

APPLICATION : 40W. 60W.



## ■ TABLE FOR THE TORQUE(kg-cm) OF WORM GEARHEAD CONNECTED WITH MOTOR:

MODEL NAME	OUTPUT W	DUTY	RATIO		1:10	1:20	1:30	1:40	1:50	1:60
			SPEED (rpm)	60Hz	180	90	60	45	36	30
				50Hz	150	75	50	37	30	25
<b>* INDUCTION MOTOR</b>										
9IN40W4H	40	CONTINUOUS	50Hz		20	33	41	49	54	60
			60Hz		17	28	34	41	45	51
9IF60W4H	60	CONTINUOUS	50Hz		30	50	60	60	60	60
			60Hz		25	42	52	60	60	60
<b>* REVERSIBLE MOTOR</b>										
9RN40W4H	40	30 MIN	50Hz		21	35	44	52	57	60
			60Hz		17	29	35	42	46	53
9RN60W4H	60	30 MIN	50Hz		30	50	60	60	60	60
			60Hz		25	42	52	60	60	60
<b>* SPEED CONTROL MOTOR</b>										
9IN40W4H-V	40		50Hz / 60Hz		4~19	7~31	8~38	10~45	11~50	12~57
9IN40W4H-V	60		50Hz / 60Hz		8~25	13~41	16~51	19~60	21~60	24~60
<b>* MAGNETIC BROKE MOTOR</b>										
9IN40W4H-B	40	CONTINUOUS	50Hz		20	33	41	49	54	60
			60Hz		17	28	34	41	45	51
9IF60W4H-B	60	CONTINUOUS	50Hz		30	50	60	60	60	60
			60Hz		25	42	52	60	60	60

\* ACTUAL ROTATION SPEED IS 2-15% LESS THAN SYNCHRONOUS SPEED.

## Memo

## Memo

# Memo